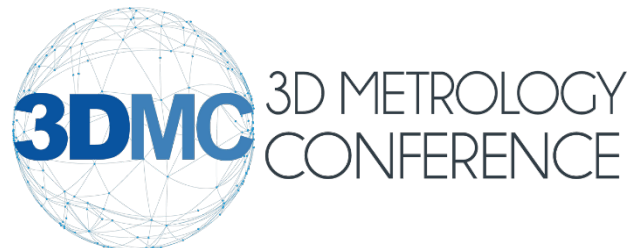


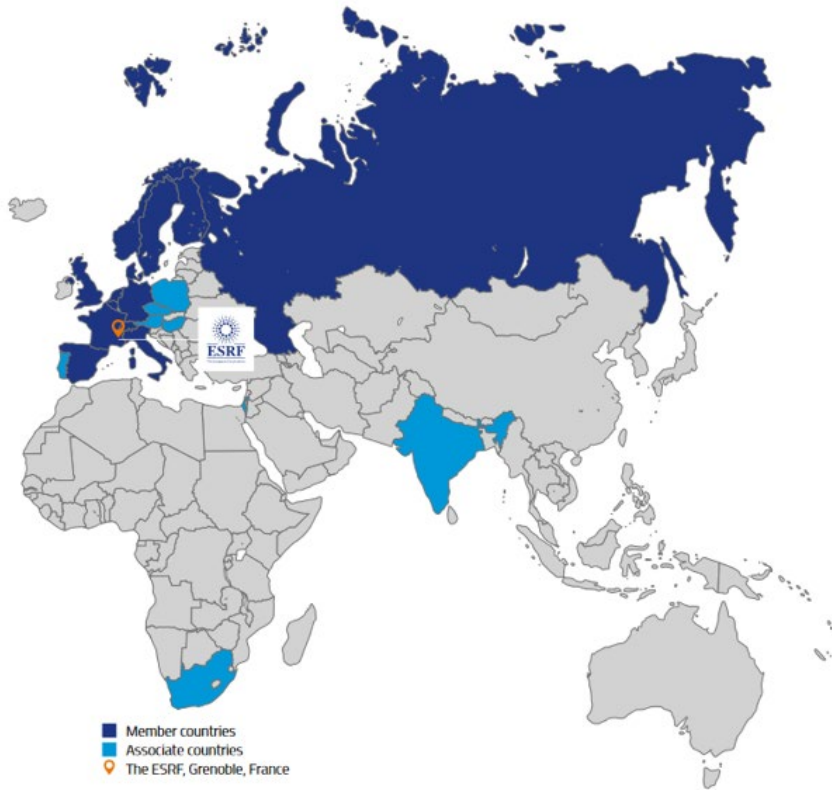


# Alignment for the ESRF Extremely Brilliant Source (EBS)

D. Martin  
*[martin@esrf.fr](mailto:martin@esrf.fr)*

3DMC – Bilbao  
28 September 2023





The ESRF is a synchrotron radiation light source.

It provides the world's brightest X-rays.

The X-rays are used to unveil the structure of materials and the mechanisms of life down to the atomic scale.



Founded in  
**1988**



**21**  
partner countries



**700**  
staff from more than  
**40** countries



**9000**  
users  
each year



**2000**  
scientific publications  
each year



**30%**  
of research carried out  
with industrial partners

# WHAT IS SYNCHROTRON RADIATION?

When electrons are accelerated they generate synchrotron radiation

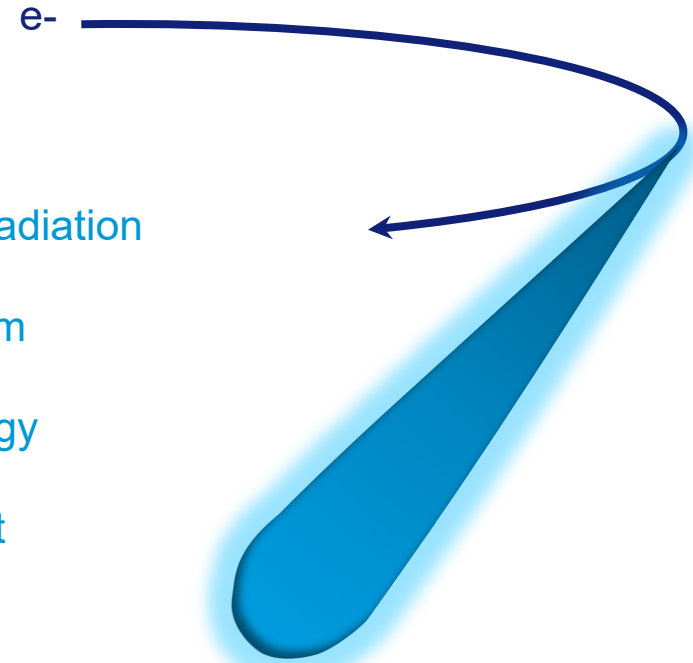
Synchrotron radiation is light on the electromagnetic spectrum

The wavelength of this light is a function of the electron energy

The ESRF electron velocity is very close to the speed of light

So the wavelength of the light is in the hard X-ray regime

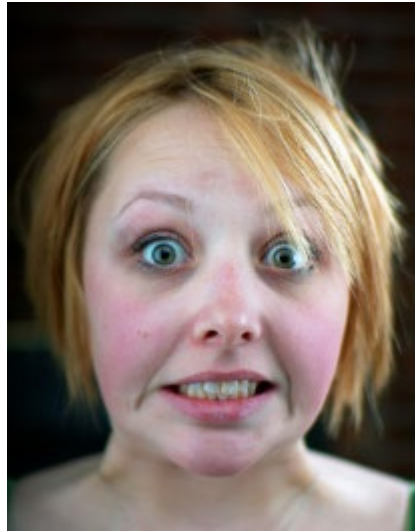
The wavelengths of X-rays are small so they can be used to look at the atomic structure of matter



# THE ELECTROMAGNETIC SPECTRUM



INFRARED 720-850nm



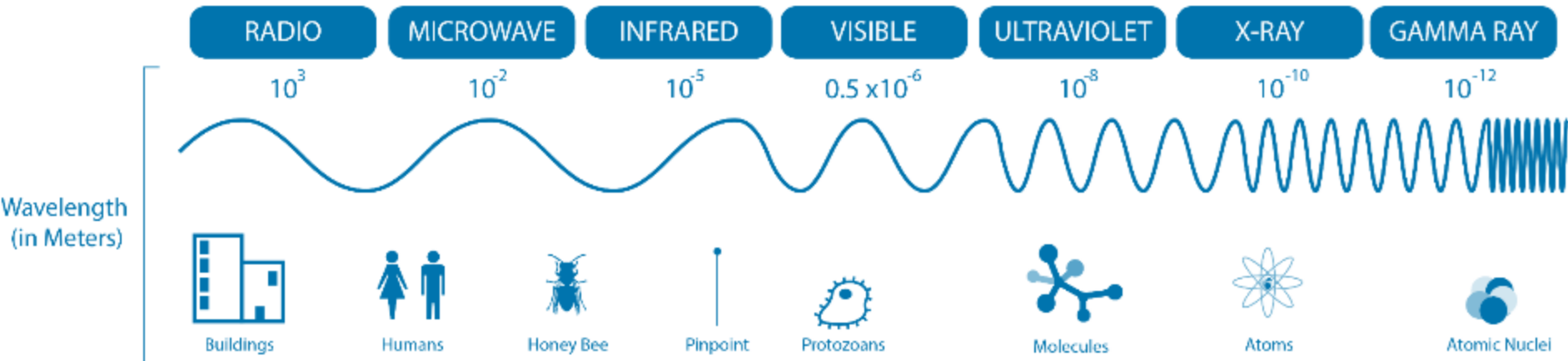
VISIBLE 440-640nm



ULTRAVIOLET 335-365nm



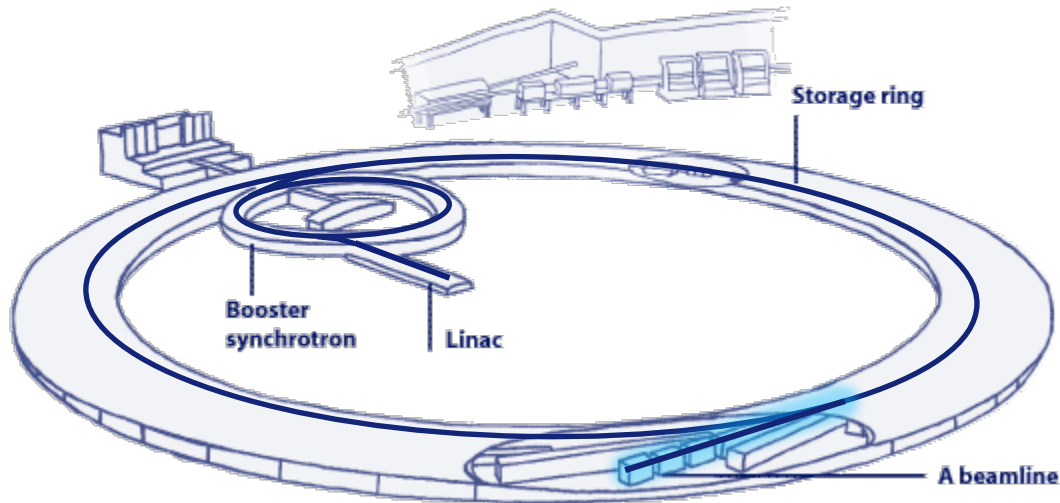
X-RAY 0.025 nm



# WHAT IS A SYNCHROTRON RADIATION LIGHT SOURCE?

A synchrotron radiation light source is composed of two main elements:

- A particle accelerator that accelerates electrons  $e^-$  to nearly the speed of light, and
- Beamlines that use the synchrotron radiation generated by the accelerator to study matter.



The linear accelerator (linac) accelerates the electrons from rest mass to 100 MeV

The booster accelerates the electrons from 100MeV to 6GeV

The storage ring (SR) keeps the electrons circulating at 6GeV for many hours

The 6GeV electrons produce synchrotron radiation in a tangential direction to the  $e^-$  beam travel

More importantly, special assemblies of magnets called insertion devices (IDs) make the 6GeV electrons oscillate about their orbit, producing very bright and collimated X-rays.

The X-rays are used on the beamlines to study matter.

## General applications of synchrotron radiation at the ESRF

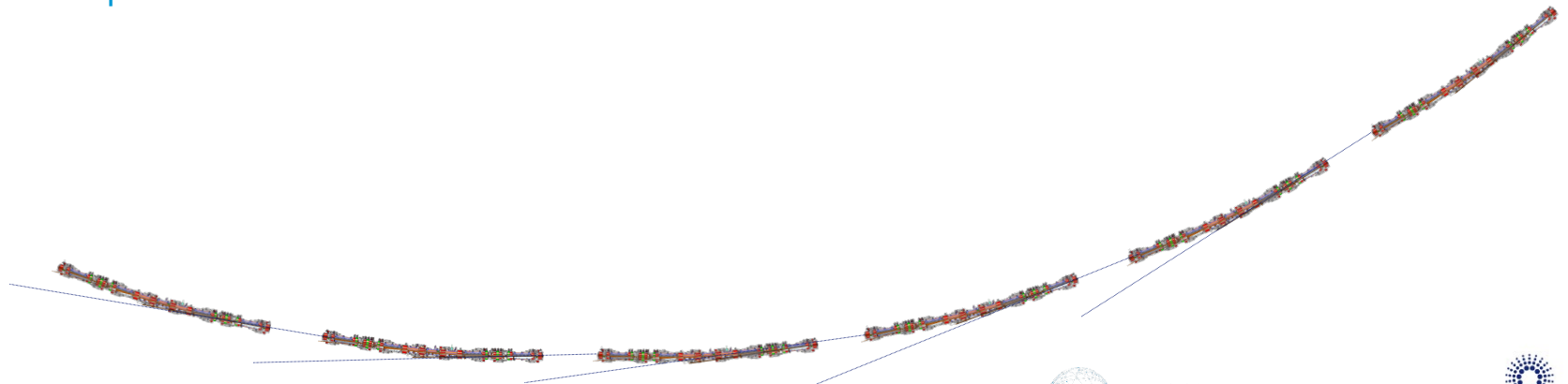
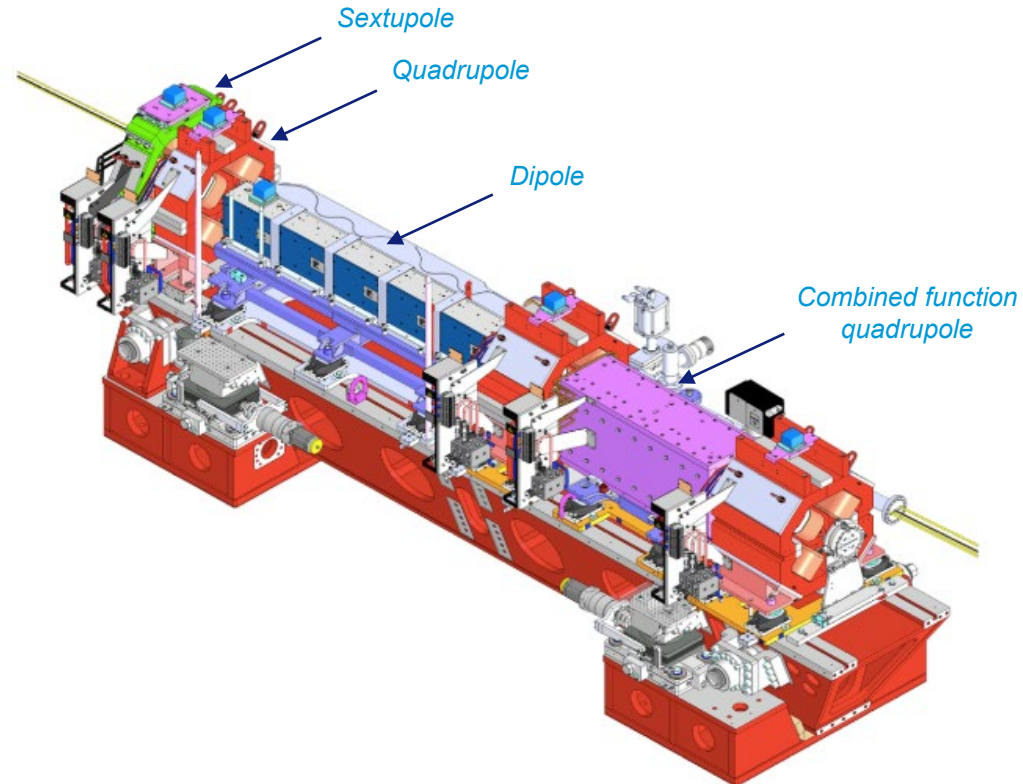


# WHAT IS THE SR ACCELERATOR AND HOW DOES IT WORK?

An accelerator is composed of a repeating array of magnets. The array of magnets is referred to as the lattice. At the ESRF, the lattice comprises 32 cells. Each cell is composed of 4 girders and a total of 49 magnets ...

Different magnets have different functions. Simplistically, for the main magnet families:

- The dipoles change the e- beam direction.
- The quadrupoles focus the e- beam.
- The sextupoles correct the e- beam.



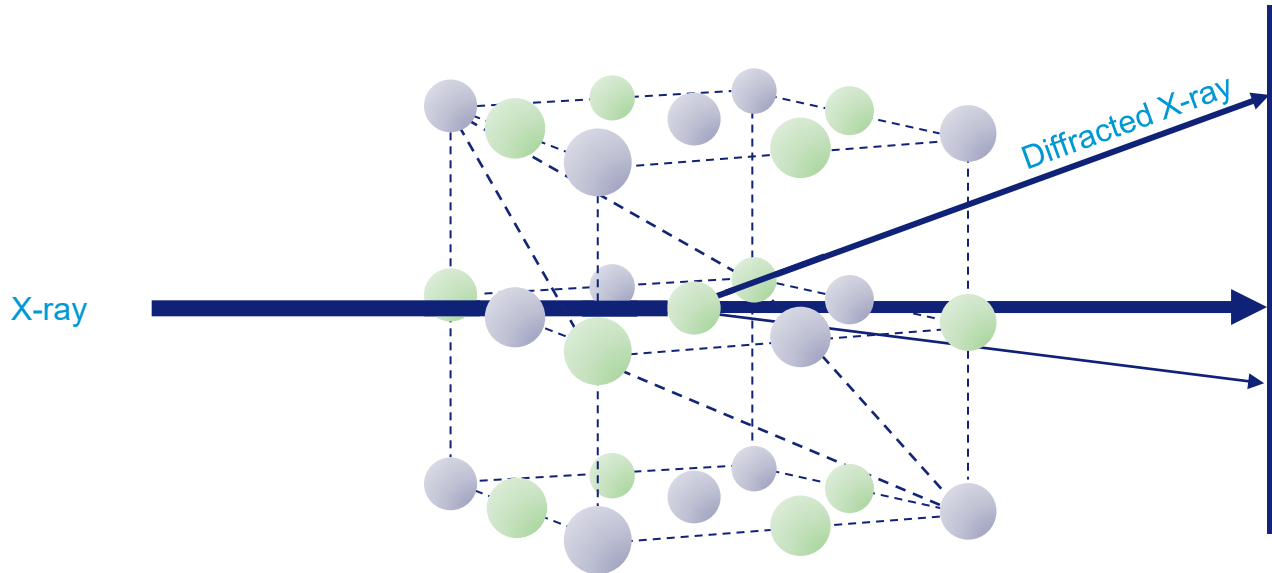
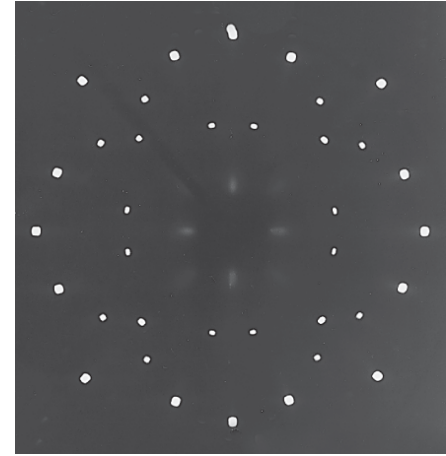
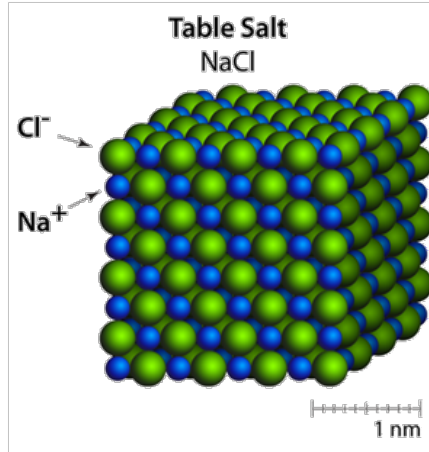
## SO HOW ARE X-RAYS USED AT THE ESRF?

A good example of the type of science made at the ESRF is crystallography using X-ray diffraction.



A **crystal** is a solid material whose constituent atoms, molecules or ions, are arranged in a **highly ordered microscopic structure**, forming a **lattice** that extends in all directions.

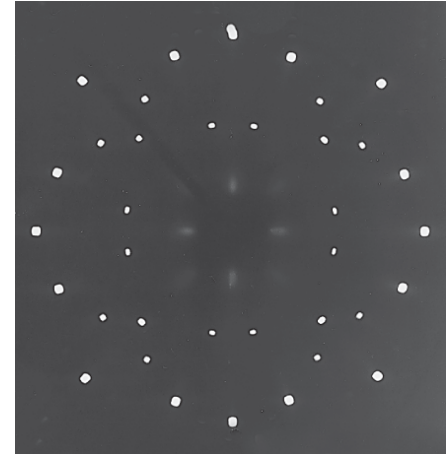
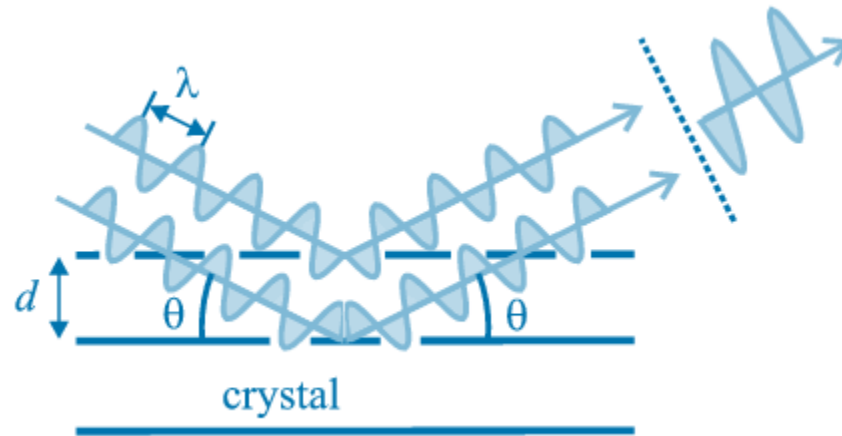
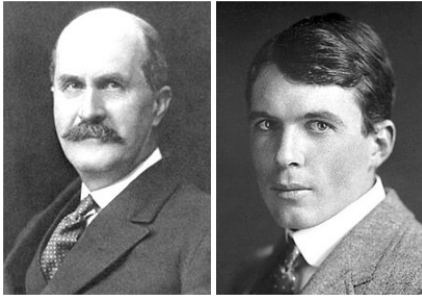
# CRYSTALLOGRAPHY AND X-RAY DIFFRACTION



The atoms comprising the crystal structure form planes. When X-rays are incident on these crystal planes they are diffracted and produce a characteristic pattern of spots



# BRAGG'S LAW

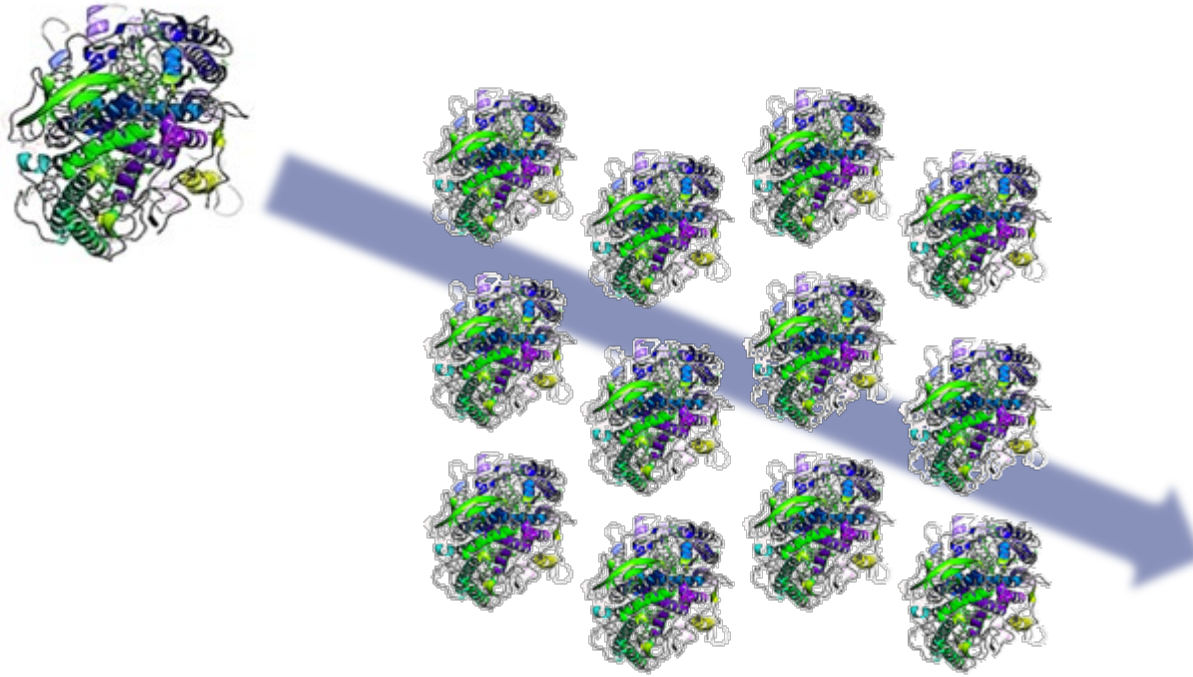


$$n\lambda = 2d \sin \theta$$

Bragg's law provides an elegant and powerful description of diffraction from crystals.

It describes how constructive interference leads to the pattern of X-ray diffraction spots.

Qualitatively, the diffraction picks up a *specific distance* in real-space, and transforms it into a frequency in *reciprocal space*.

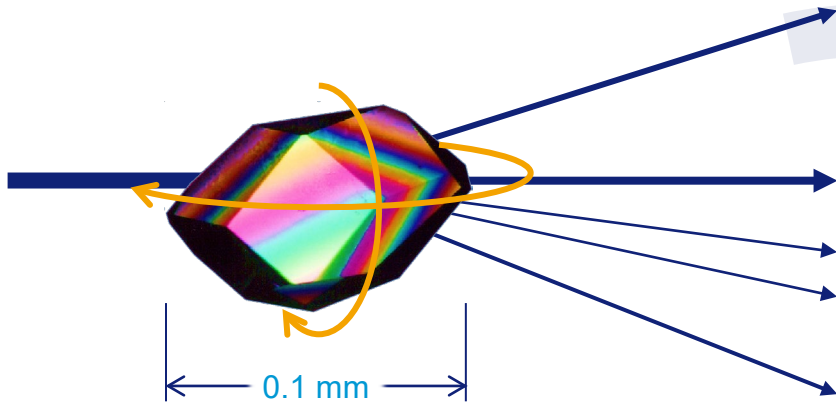


The same techniques can be used to image complex systems such as proteins

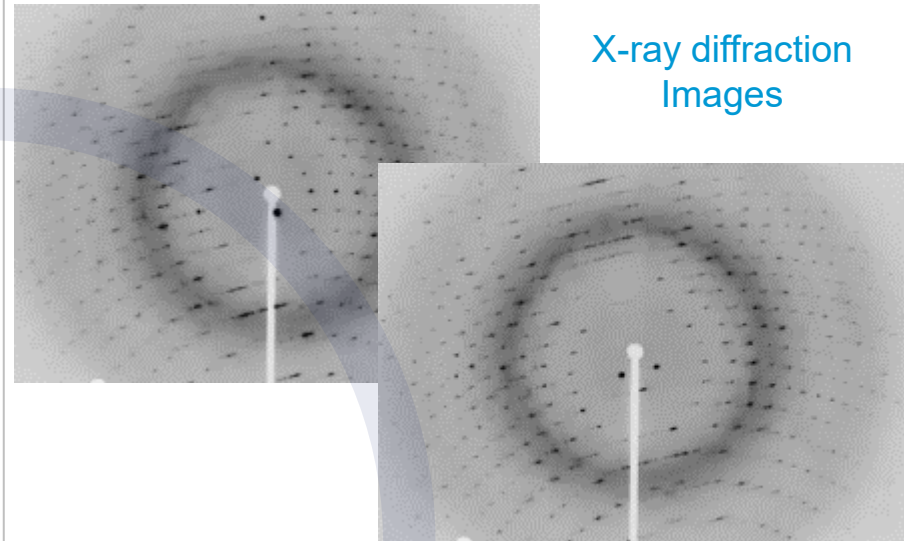


# X-RAY CRYSTALLOGRAPHY METHOD

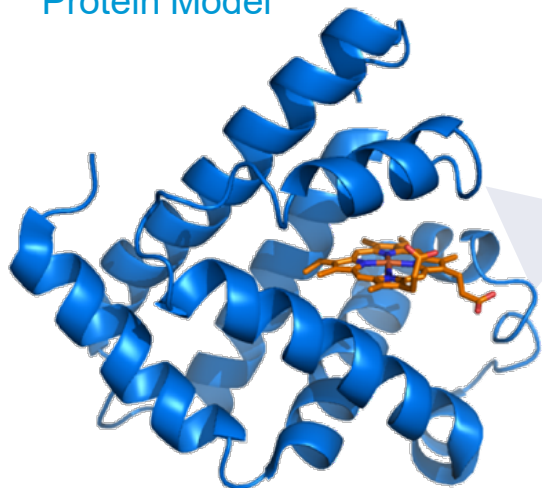
X-ray diffraction



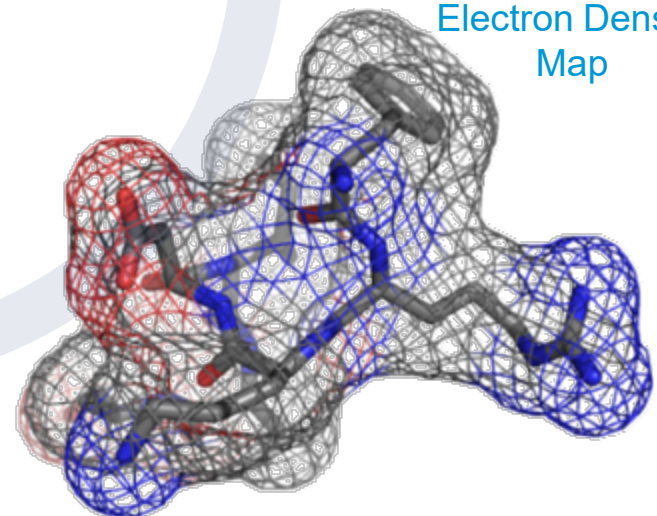
X-ray diffraction Images



Protein Model



Electron Density Map



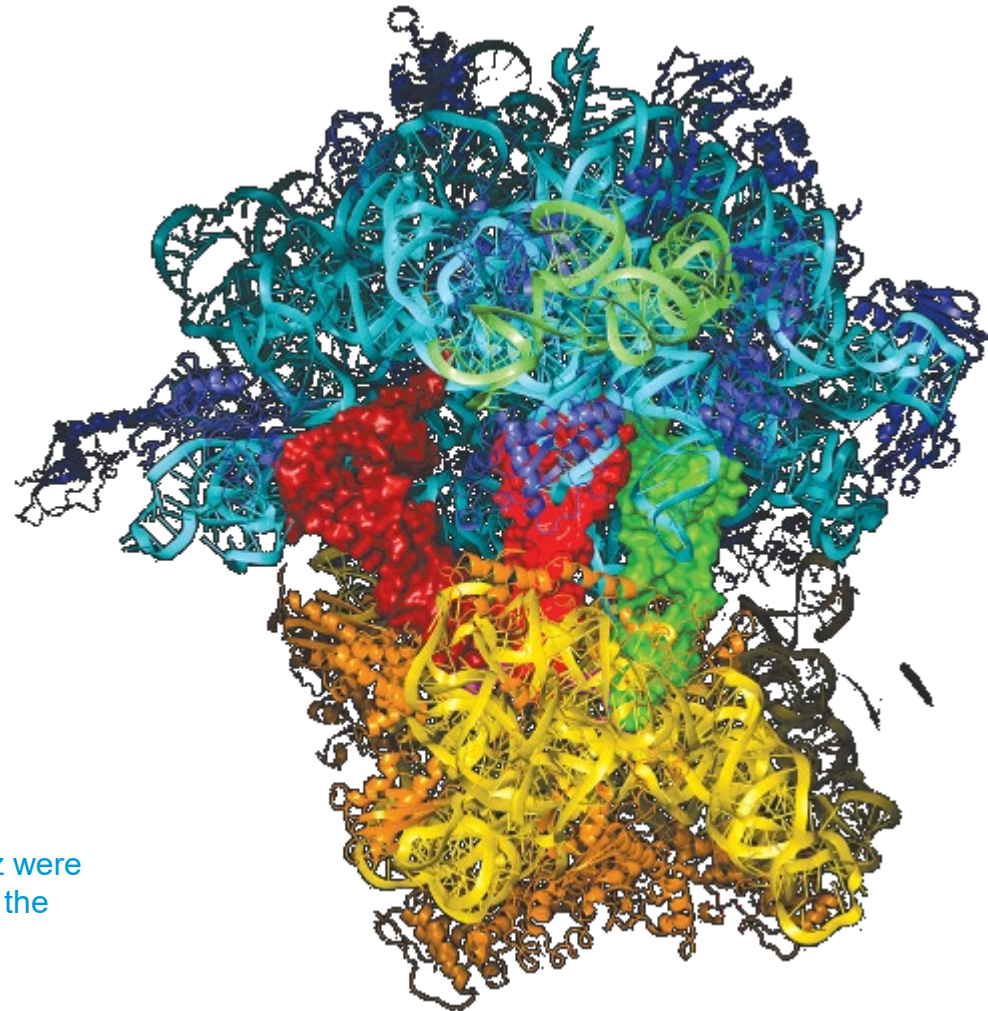
Form



Function

This technique has led to the discovery of some fantastically complex structures like the ribosome.

Ada Yonath, Venkatraman Ramakrishnan and Thomas Steitz were awarded the 2009 Nobel prize in Chemistry for their work on the ribosome



← 20 nm →

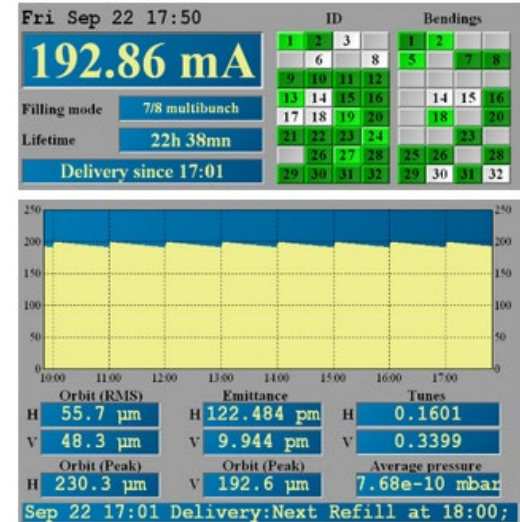
# METROLOGY IN SYNCHROTRON RADIATION

Where does 3D metrology fit into this?

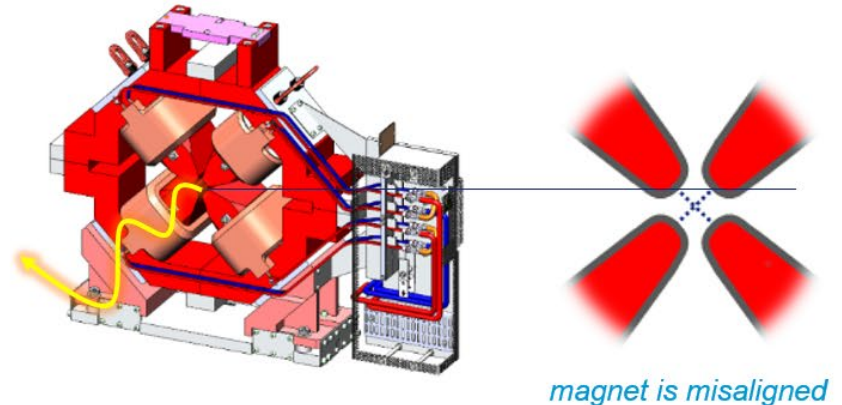
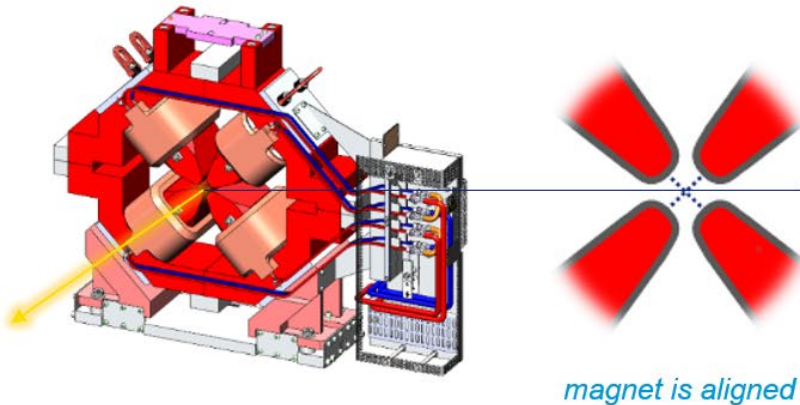
Typically electrons circulate in the SR for days. New electrons are injected (topped up) every hour\*.

All of the time they are circulating, the electrons must stay within a sub-millimetric path. Any disturbance will cause them to oscillate and rapidly be lost.

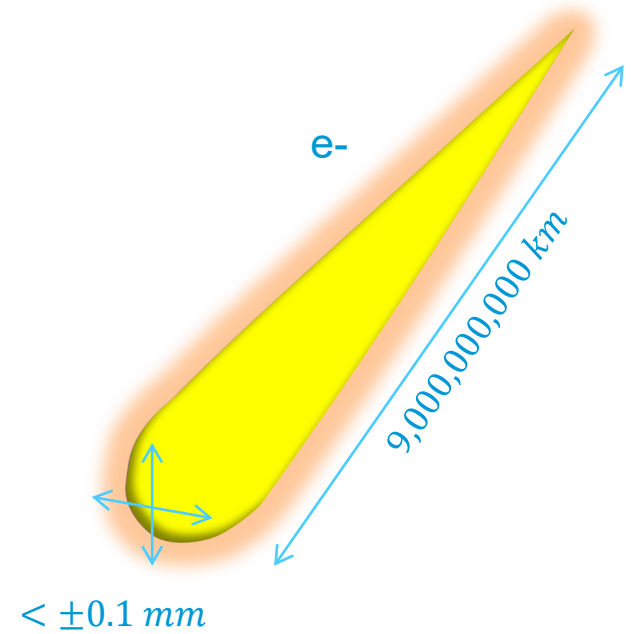
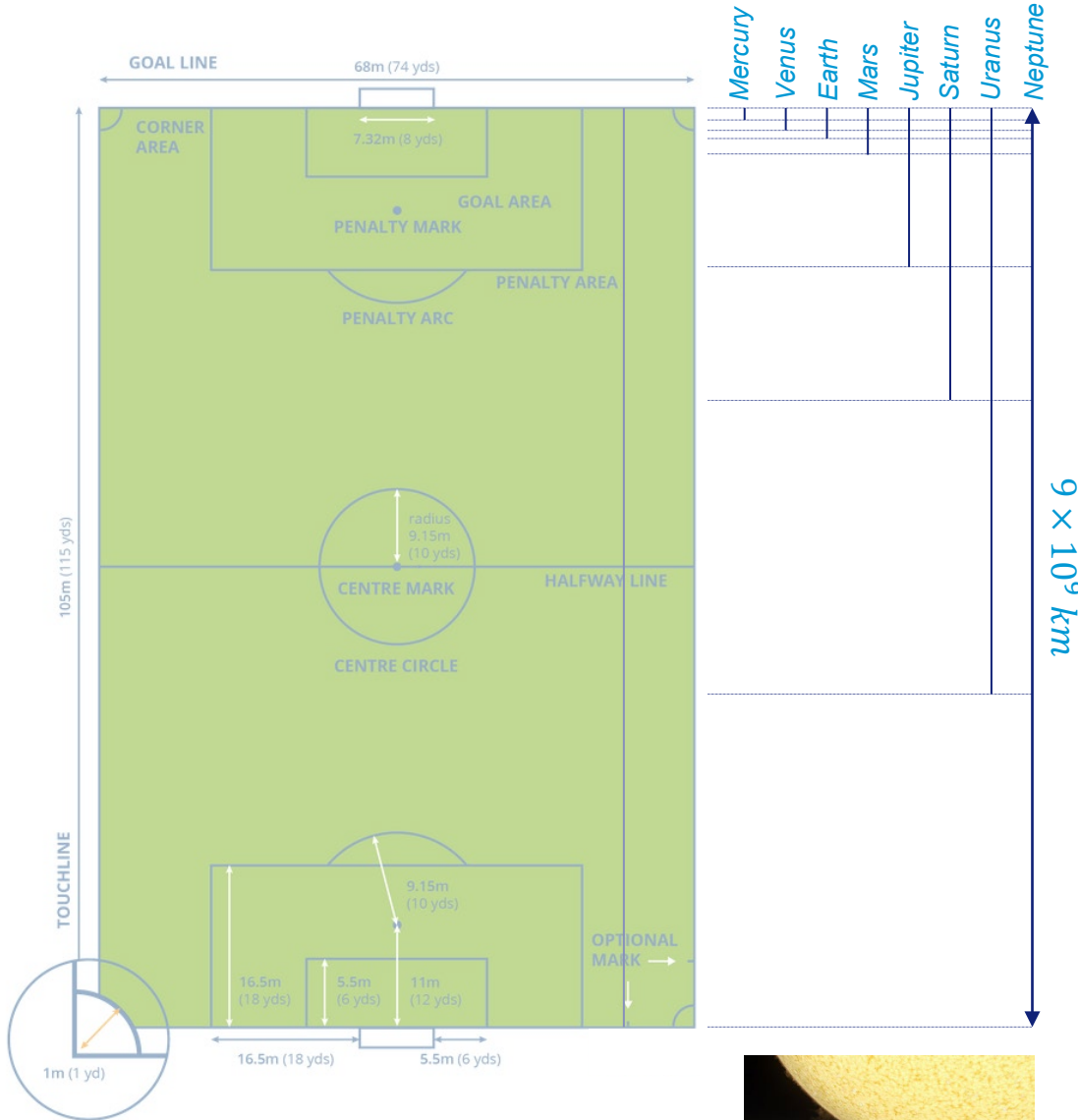
*\*In an 8 hour shift, 6 GeV electrons travel nearly 9 billion km in the ESRF Storage Ring*



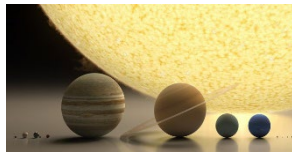
Machine status



# 9x10<sup>9</sup> km IS THE DISTANCE ACROSS THE ORBIT OF NEPTUNE!



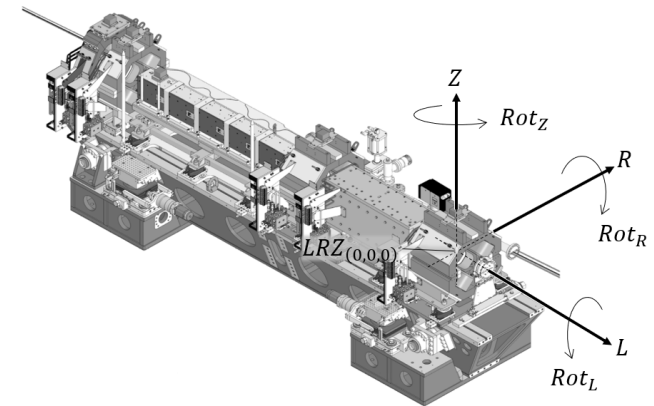
Electrons must effectively stay in a virtual cylinder of radius less than 0.1 mm and 9x10<sup>9</sup> km long over 8 hours!



There were **two key constraints** for EBS

**first** respect the magnet (and other) alignment tolerances

Machine	U(L) [ $\mu\text{m}$ ]	U(R) [ $\mu\text{m}$ ]	U(Z) [ $\mu\text{m}$ ]
Long. Varying field dipoles	1000	>100	>100
High gradient quadrupoles, Combined function dipoles	500	60	60
Medium gradient quads	500	100	85
Sextupoles	500	70	50
Octupoles	500	100	100



*Maximum permissible error  $2.5\sigma$*

... and **second** ensure the new machine was in the same place as the old machine to minimize disturbance to the functioning beamlines.

# ALIGNMENT TOLERANCES – WHAT DO THEY MEAN?

Machine	U(L) [ $\mu\text{m}$ ]	U(R) [ $\mu\text{m}$ ]	U(Z) [ $\mu\text{m}$ ]
Long. Varying field dipoles	1000	>100	>100
High gradient quadrupoles, Combined function dipoles	500	60	60
Medium gradient quads	500	100	85
Sextupoles	500	70	50
Octupoles	500	100	100

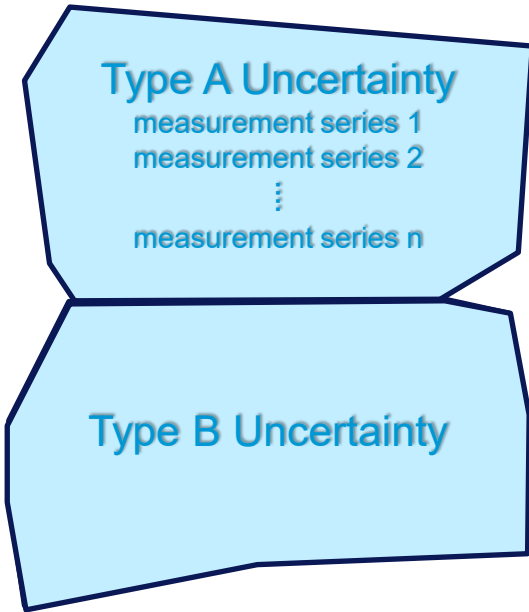
Early on it was decided that these tolerances included all possible errors, and notably:

- Fiducialisation,
- Alignment on the girder including:
  - opening and closing of magnets,
  - girder rectitude,
- Transportation,
- Alignment in the tunnel,
- ...

It was also decided the most appropriate way to determine the overall uncertainty was to follow the methodology for an uncertainty calculation outlined in the Guide to the Uncertainty in Measurement – the GUM\*.

*\*available at <https://www.bipm.org/en/publications/guides/gum.html>*



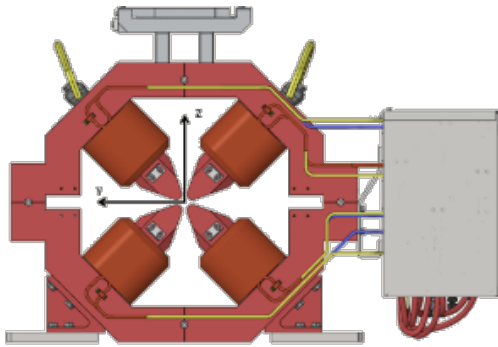


**measurement uncertainty**  
non-negative parameter  
characterizing the dispersion of the  
quantity values being attributed to a  
measurand, based on the information  
used

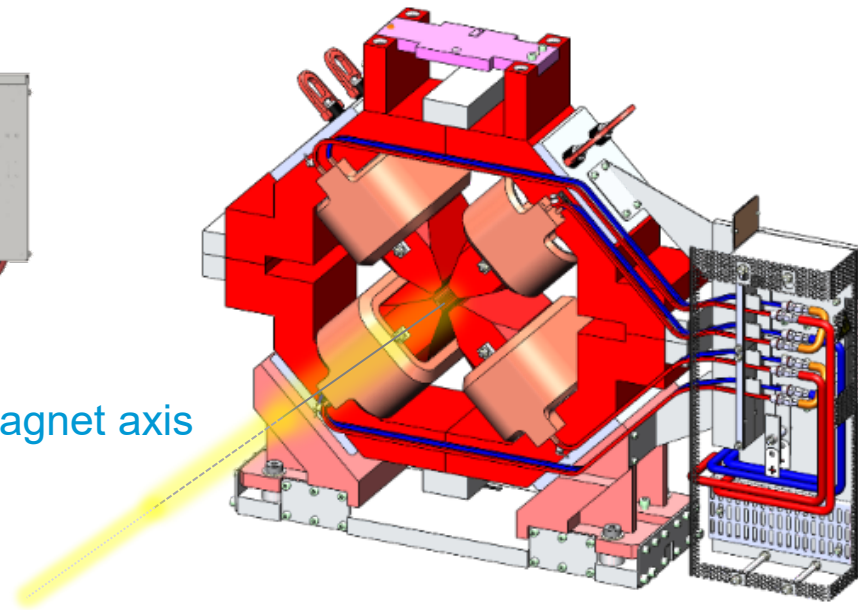
$$U = \sqrt{\text{Type A}^2 + \text{Type B}^2}$$

An uncertainty calculation is generally done in a characteristic manner

For a magnet, we are interested in putting the magnet axis in the right place

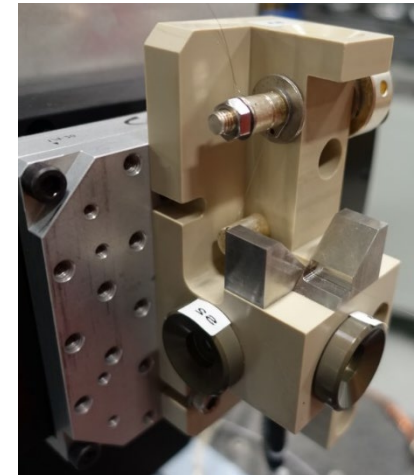
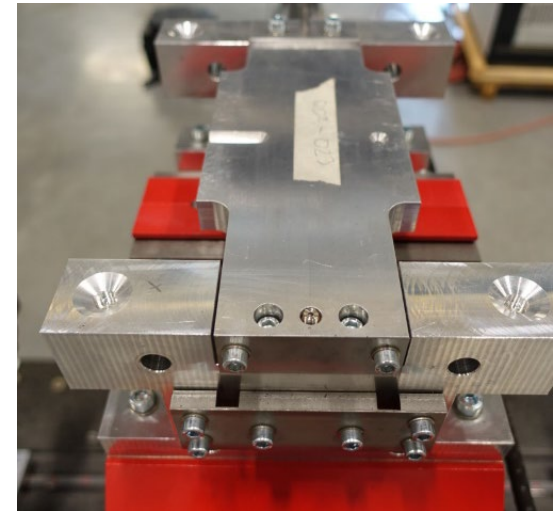
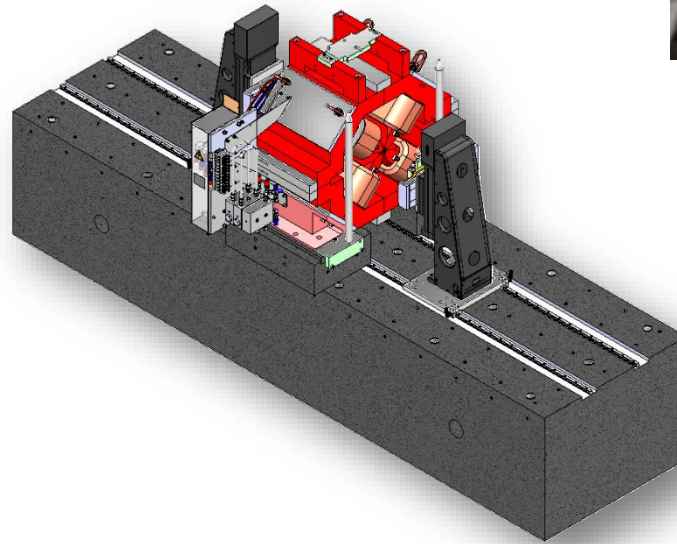
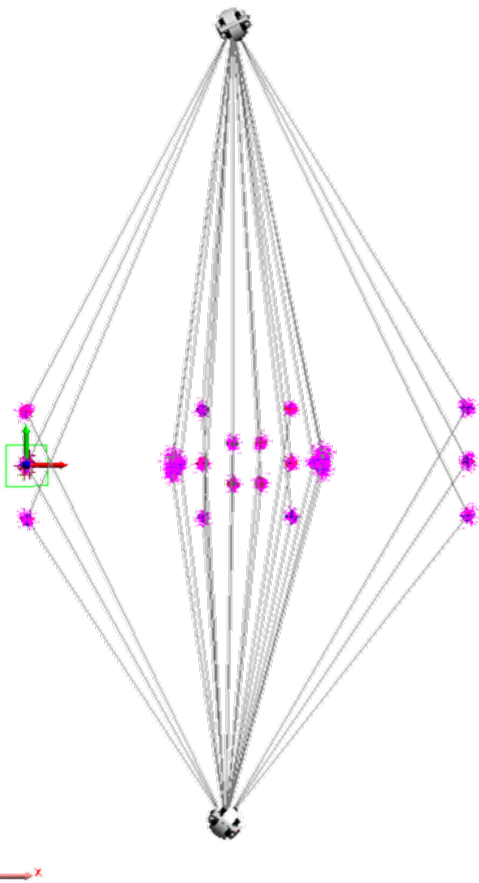


But we cannot see the magnet axis



So we have to reference it with respect to something we can see.

The magnet reference points were determined from two laser tracker stations.



# FIDUCIALISATION UNCERTAINTY

	U(L) [μm]	U(R) [μm]	U(Z) <sup>1</sup> [μm]	U(Z) <sup>2</sup> [μm]
Laser Tracker				
Wire position	13	15	18	18
Measurement	9	10	9	9
Repeatability	3	3	12	12
<i>Magnet measurements</i>		4	4	4
<i>Magnetic Fiducialisation</i>		20	20	20
<i>Magnet Shim Determination</i>				20
<b>Total</b>	<b>16</b>	<b>26</b>	<b>31</b>	<b>37</b>

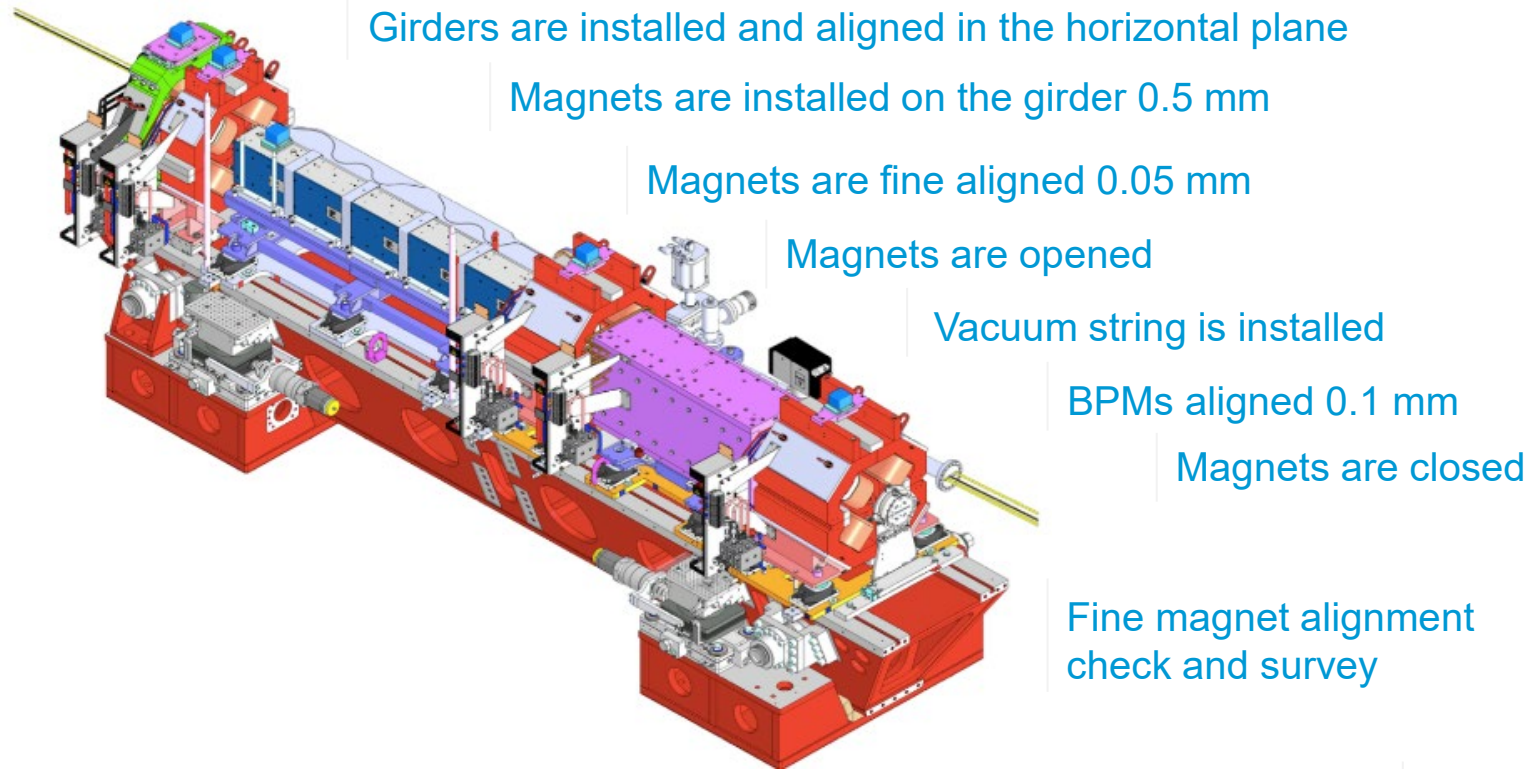
*Shims were used to align certain magnets:*

- 1) High gradient quadrupoles, Combined function dipoles
- 2) Medium gradient quadrupoles, sextupoles and octupoles

We combine all of these errors/uncertainties to determine the fiducialisation uncertainty contribution.

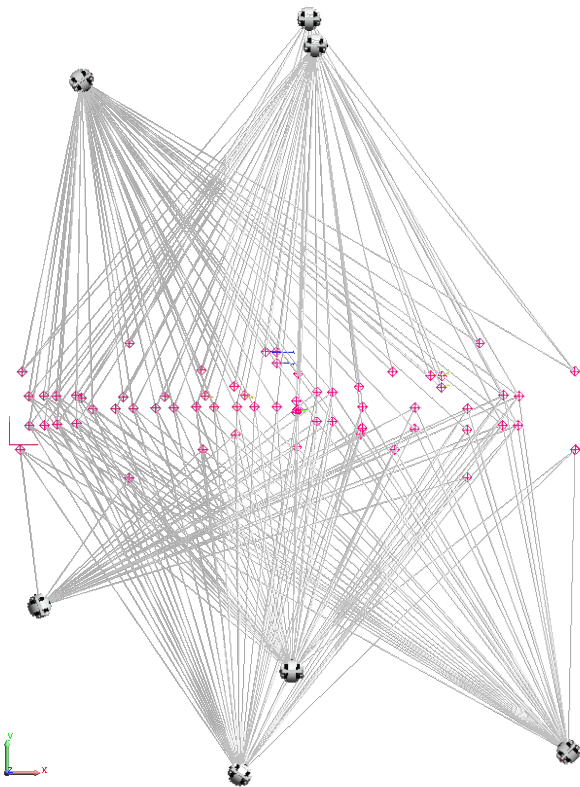
This is the first of several contributions to the overall alignment uncertainty...

*Reference: G. Le Bec, J. Chavanne, L. Lefebvre, D. Martin, and C. Penel, "Magnetic Measurements and Fiducialisation of the ESRF-EBS Magnets", in Proc. 11th Int. Particle Accelerator Conf. (IPAC'20), Caen, France, May 2020, paper THVIR09, pp. XX-XX*



Assembly was made at ESRF01 – a dedicated building

# GIRDER ALIGNMENT UNCERTAINTY



USMN - Unified Spatial Metrology Network

Weight	Instrument (check if moving)	Weight	Point	Ma...	Ra...	Ux	Uy	Uz	Umag	Meas
<input type="checkbox"/>	1.000 0 SA A: 0 - Leica emScon AT403	<input checked="" type="checkbox"/>	1.000 DL28_3_E	0.032	121%	0.007	0.008	0.008	0.013	01_345_
<input checked="" type="checkbox"/>	1.000 1 SA B: 0 - Leica emScon AT403	<input checked="" type="checkbox"/>	1.000 QF88_SI	0.025	104%	0.006	0.007	0.007	0.012	01_3456
<input checked="" type="checkbox"/>	1.000 2 SA C: 0 - Leica emScon AT403	<input checked="" type="checkbox"/>	1.000 QF88_EI	0.028	101%	0.006	0.007	0.007	0.012	01_3456
<input checked="" type="checkbox"/>	1.000 3 SA D: 0 - Leica emScon AT403	<input checked="" type="checkbox"/>	1.000 DL28_2_E	0.021	98%	0.008	0.008	0.009	0.014	01_345_
<input checked="" type="checkbox"/>	1.000 4 SA E: 0 - Leica emScon AT403	<input checked="" type="checkbox"/>	1.000 DL28_3_S	0.027	95%	0.007	0.008	0.008	0.013	01_345_
<input checked="" type="checkbox"/>	1.000 5 SA F: 0 - Leica emScon AT403	<input checked="" type="checkbox"/>	1.000 SD18_EI	0.032	95%	0.008	0.009	0.009	0.015	01_345_
<input checked="" type="checkbox"/>	1.000 6 SA G: 0 - Leica emScon AT403	<input checked="" type="checkbox"/>	1.000 DL28_4_E	0.024	93%	0.007	0.008	0.008	0.013	01_345_
		<input checked="" type="checkbox"/>	1.000 QF88_SI	0.021	89%	0.007	0.009	0.008	0.014	01_3456
		<input checked="" type="checkbox"/>	1.000 SD18_SE	0.027	88%	0.008	0.009	0.008	0.015	01_345_
		<input checked="" type="checkbox"/>	1.000 QF88_EE	0.031	88%	0.008	0.009	0.007	0.014	01_3456
		<input checked="" type="checkbox"/>	1.000 CH6-BPM04-P2	0.023	87%	0.009	0.011	0.010	0.018	___45_
		<input checked="" type="checkbox"/>	1.000 DL28_1_E	0.025	85%	0.009	0.009	0.009	0.016	_1_345_
		<input checked="" type="checkbox"/>	1.000 DL28_1_S	0.029	85%	0.008	0.009	0.009	0.015	_0_345_
		<input checked="" type="checkbox"/>	1.000 DL28_5_E	0.027	81%	0.007	0.007	0.007	0.013	01_345_
		<input checked="" type="checkbox"/>	1.000 DL28_4_S	0.021	81%	0.007	0.007	0.007	0.012	01_345_
		<input checked="" type="checkbox"/>	1.000 DQ18_SE	0.020	78%	0.009	0.011	0.009	0.016	___3456
		<input checked="" type="checkbox"/>	1.000 DQ18_EE	0.020	75%	0.007	0.009	0.008	0.014	_0_345_
		<input checked="" type="checkbox"/>	1.000 G128-SI08	0.020	72%	0.008	0.009	0.009	0.016	___3456
		<input checked="" type="checkbox"/>	1.000 QF88_SE	0.017	72%	0.006	0.007	0.007	0.012	01_3456
		<input checked="" type="checkbox"/>	1.000 QD58_SI	0.023	71%	0.008	0.009	0.008	0.014	01_345_
		<input checked="" type="checkbox"/>	1.000 G128-SE07	0.022	70%	0.010	0.010	0.011	0.018	012_---
		<input checked="" type="checkbox"/>	1.000 QF88_SE	0.022	69%	0.008	0.009	0.008	0.014	01_3456
		<input checked="" type="checkbox"/>	1.000 QF88_EI	0.020	68%	0.008	0.009	0.007	0.014	01_3456
		<input checked="" type="checkbox"/>	1.000 QF88_EE	0.018	67%	0.007	0.007	0.007	0.012	01_3456
		<input checked="" type="checkbox"/>	1.000 QD58_EI	0.016	65%	0.008	0.009	0.008	0.014	01_345_
		<input checked="" type="checkbox"/>	1.000 SD18_SI	0.021	65%	0.009	0.009	0.009	0.016	01_345_
		<input checked="" type="checkbox"/>	1.000 QD58_SE	0.014	65%	0.008	0.009	0.009	0.015	01_345_

Instrument Solution Reference Frame  
 Instrument Frame  Working Frame

Auto Solve, Trim Outliers, and Re-Solve  
  Do this automatically

Best-Fit Only  Instrument Settings

Solve

Uncertainty Field Analysis  
 Samples: 300  
 Time Limit: 4.0 min.

Reporting  
 Instrument Uncertainty Analysis  Error  Uncertainty

Apply Results  
 Create composite group: USMN Composite  
 Create point uncertainty fields  
 Update composite point offsets  
 Apply instrument and point group transforms in SA  
 De-Activate measurements weighted to zero

Apply

No scale bars defined.

Summary  
 Point Error: Overall RMS = 0.009, Average = 0.007, Max = 0.032 'SD18\_EI'  
 System Solution Time: 0.3 sec., Robustness Factor = 0.002318, Unknowns 24, Equations 762  
 Uncertainty Magnitude: Average = 0.016, Max = 0.023 'CH5-1'  
 68.26% Confidence Interval (1.0 sigma), Samples: 300, WCF: GNet:Gref  
 Uncertainty Analysis Time: 39.8 sec

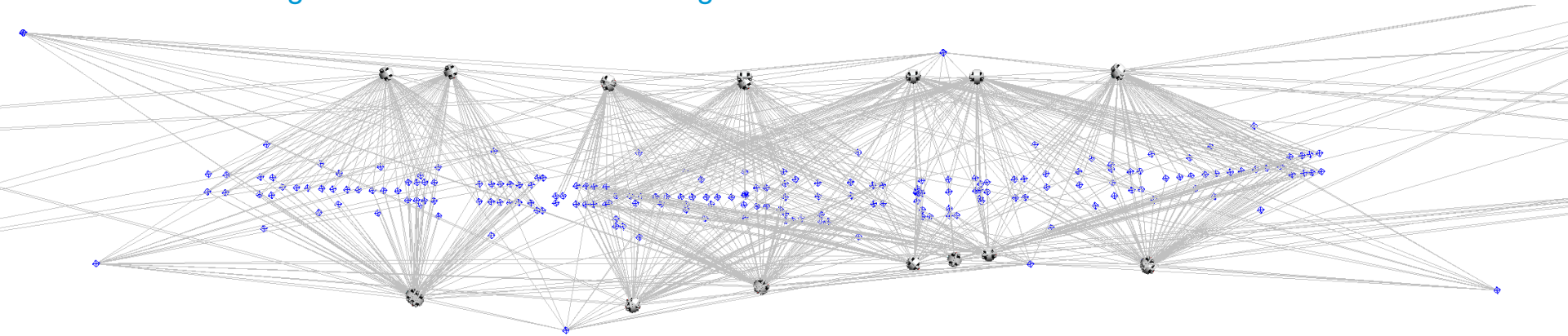
	U(L) [μm]	U(R) [μm]	U(Z) <sup>1)</sup> [μm]	U(Z) <sup>2)</sup> [μm]
Measurements	6	7	6	6
Difference to nominal	126	24	25	25
Overall uncertainty		14	17	17
Magnet Opening/Closing	8	5	7	7
Girder rectitude				8
<b>Total</b>	<b>126</b>	<b>29</b>	<b>31</b>	<b>31</b>

Shims were used to align certain magnets:

- 1) High gradient quadrupoles, Combined function dipoles
- 2) Medium gradient quadrupoles, sextupoles and octupoles

# EFFECT OF STORAGE, TRANSPORTATION, INSTALLATION AND BAKEOUT

After the installation and initial alignment in the tunnel all of the girders were remeasured like they were during in ESRF01. This was done again after the bakeout was finished in the tunnel.



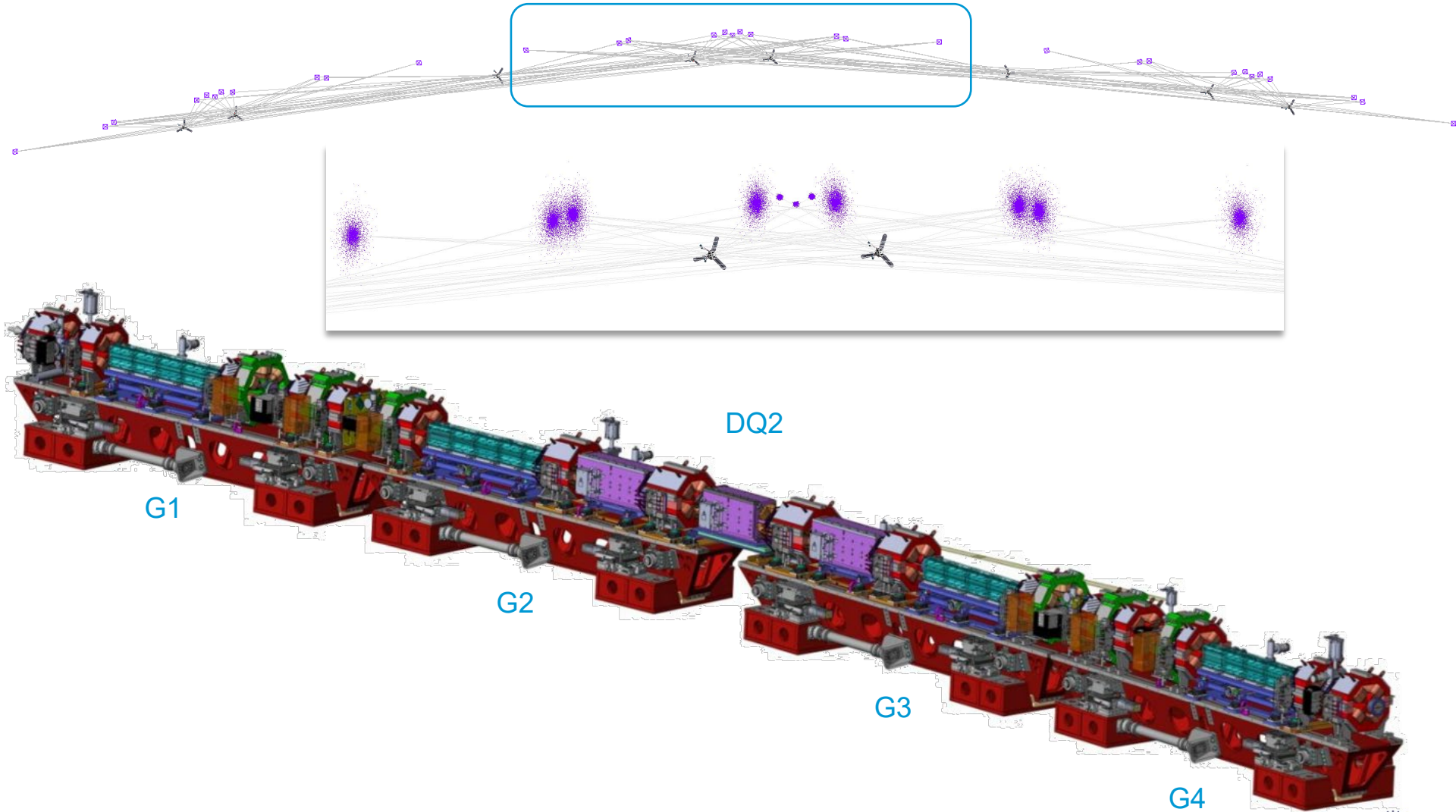
The magnet positions were then adjusted onto the magnet positions measured at ESRF01.

Survey	U(R) [ $\mu\text{m}$ ]	U(Z) [ $\mu\text{m}$ ]
ESRF01 (see girder alignment uncertainty)	14	17
After transport (3D adjustment on ESRF01)	17	20
After bakeout (3D adjustment on ESRF01)	19	21

These results suggest the effect of transport was  $\sim 10 \mu\text{m}$  – and the effect of bakeout on the alignment less than that ...

*ESRF01 was the building where the girders were assembled.*

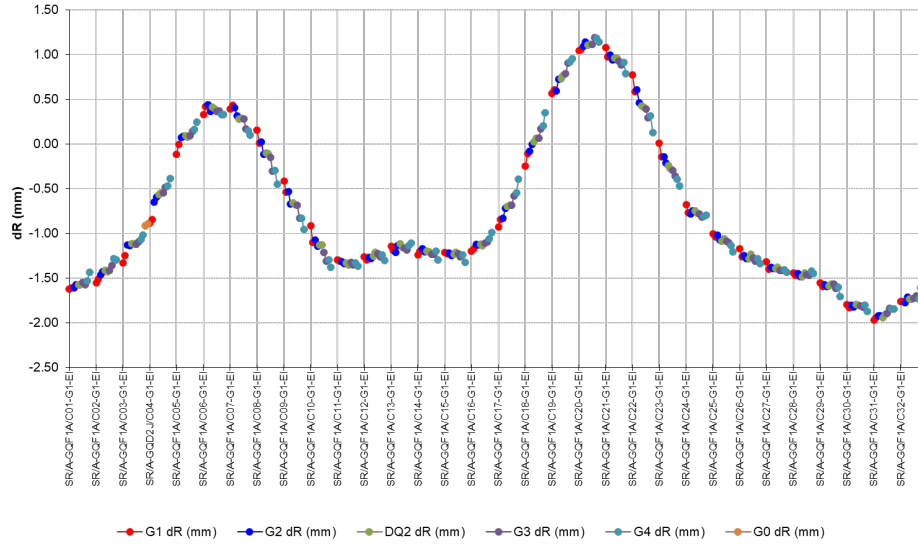
# GIRDERS IN THE TUNNEL



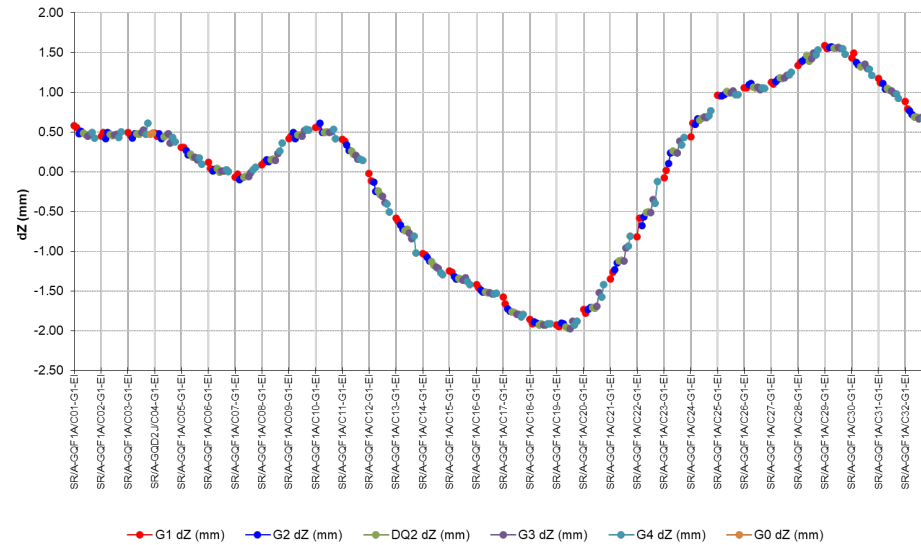


# NOVEMBER 2019 AFTER FINAL ALIGNMENT

srNov19after dR (St Dev = 0.84 mm)

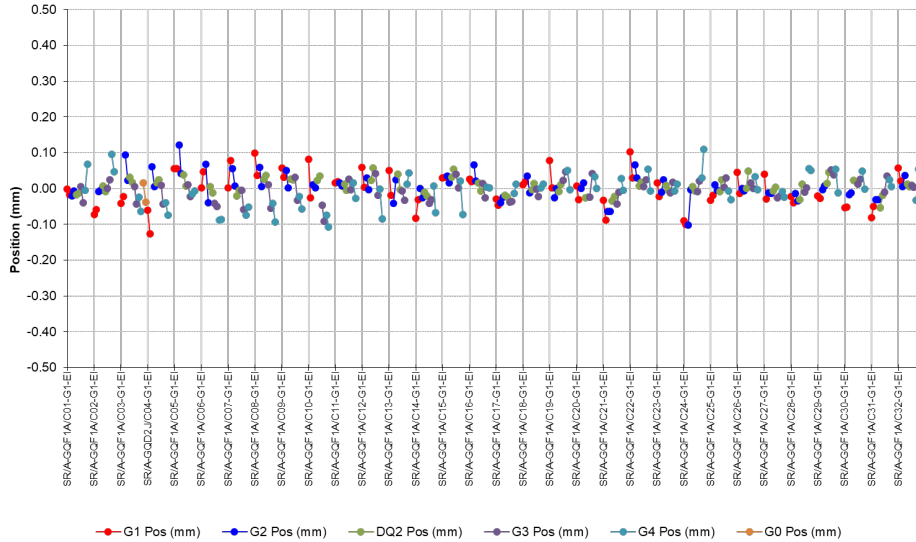


srNov19after dZ (St Dev = 1.03 mm)



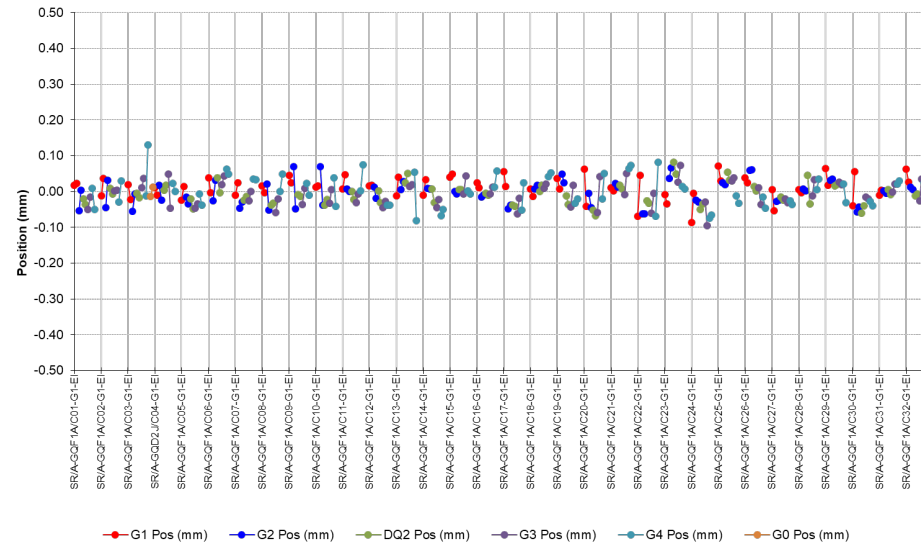
# NOVEMBER 2019 AFTER FINAL ALIGNMENT - ERROR

srNov19after Position (St Dev = 0.039 mm)



$U_R = 39 \mu\text{m}$   
 $U_Z = 36 \mu\text{m}$

srNov19after Position (St Dev = 0.036 mm)



	U(R) [ $\mu\text{m}$ ]	U(Z) [ $\mu\text{m}$ ]
G1E, G4S	52	42
G1S, G2E, G3S, G4E	42	34
G2S, G3E	24	32
DQ2	23	30

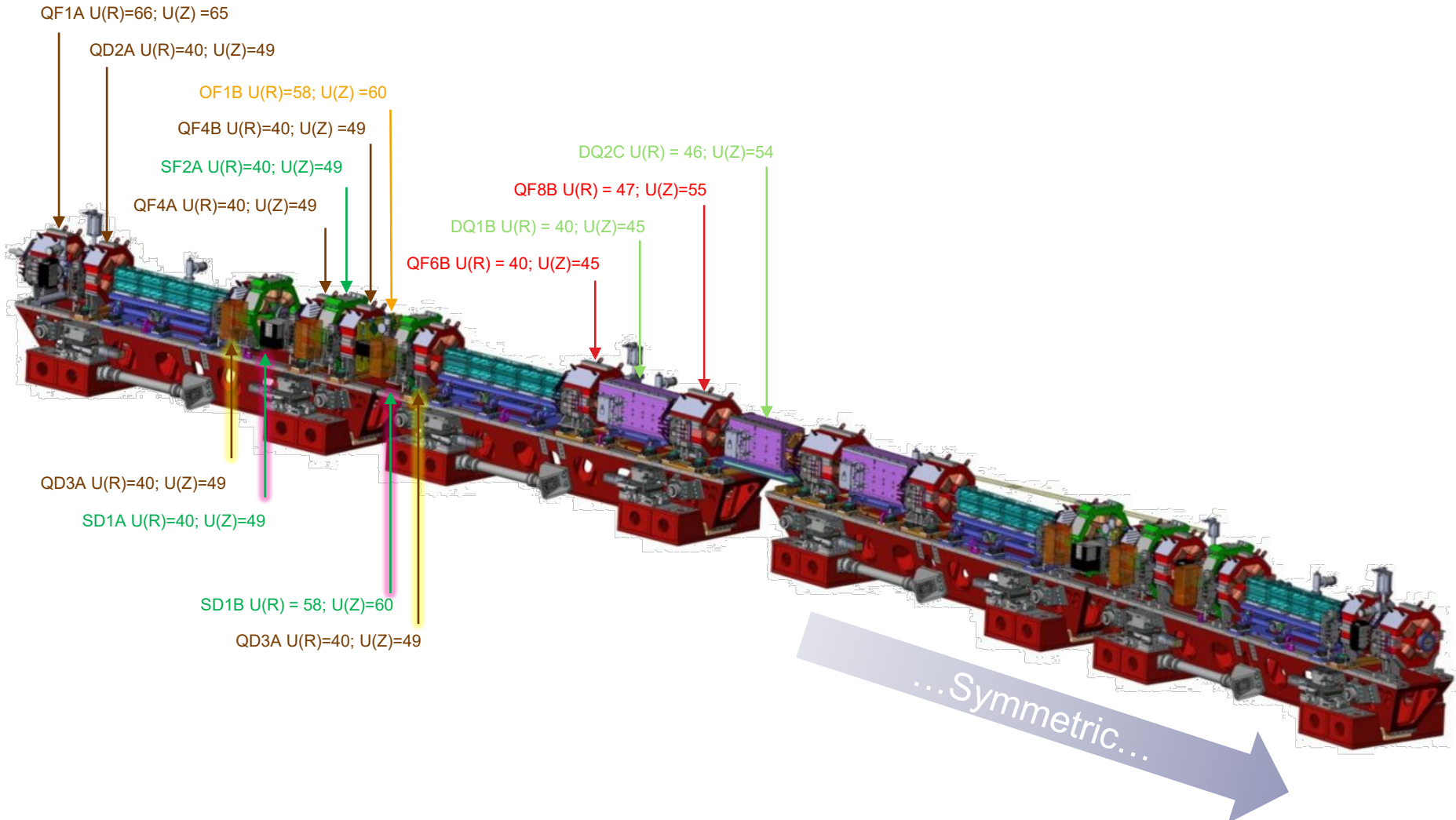
# ALIGNMENT UNCERTAINTY BY MAGNET FOR ½ CELL – 2<sup>ND</sup> HALF IS SYMETRIC

Combined alignment uncertainties for the EBS machine using the  $U_R$  and  $U_Z$  from the previous slides are estimated to be:

Magnet type		Nominal $U(R)$ [ $\mu\text{m}$ ]	Measured $U(R)$ [ $\mu\text{m}$ ]	Nominal $U(Z)$ [ $\mu\text{m}$ ]	Measured $U(Z)$ [ $\mu\text{m}$ ]
QF1A	Med. Grad. Quad.	100	66	85	65
QD2A	Med. grad. quad.	100	40	85	49
QD3A	Med. Grad. Quad.	100	40	85	49
SD1A	Sextupole	70	40	50	49
QF4A	Med. Grad. Quad.	100	40	85	49
SF2A	Sextupole	70	40	50	49
QF4B	Med. Grad. Quad.	100	40	85	49
OF1B	Octupole	100	58	100	60
SD1B	Sextupole	70	58	50	60
QD3A	Med. Grad. Quad.	100	40	85	49
QF6B	High Grad. Quad.	60	40	60	45
DQ1B	Dipole-Quadrupole	60	40	60	45
QF8B	High Grad. Quad.	60	47	60	55
DQ2C	Dipole-Quadrupole	60	46	60	54
...Symmetric ...					

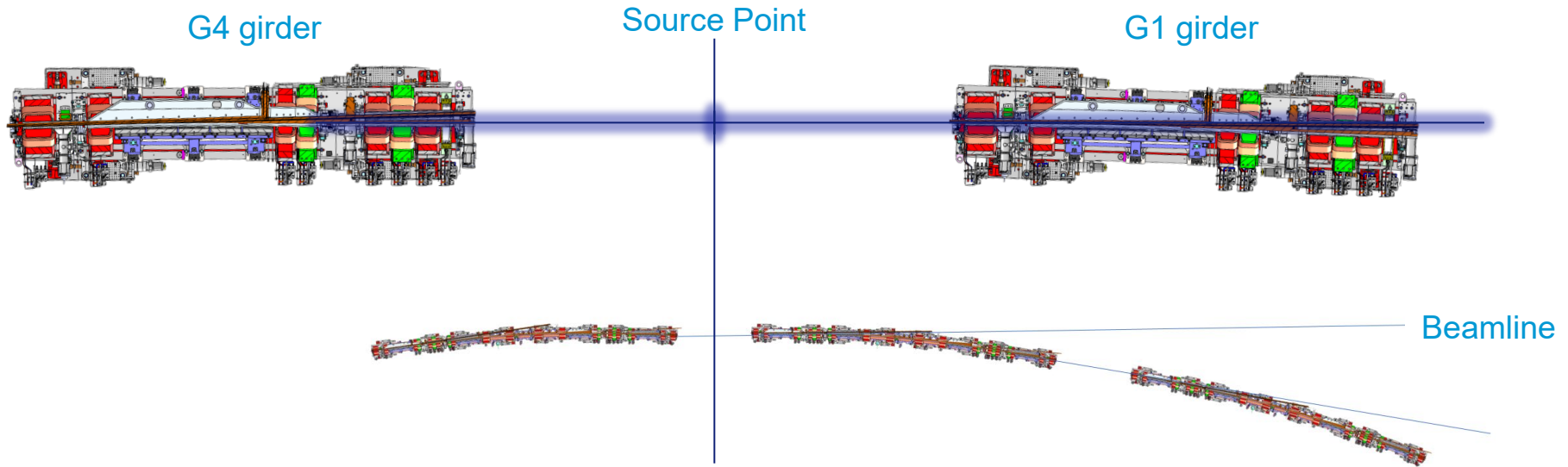
Note  $U(L)$  along the beam = 453  $\mu\text{m}$  for a nominal value of 500m

# ALIGNMENT UNCERTAINTY BY MAGNET

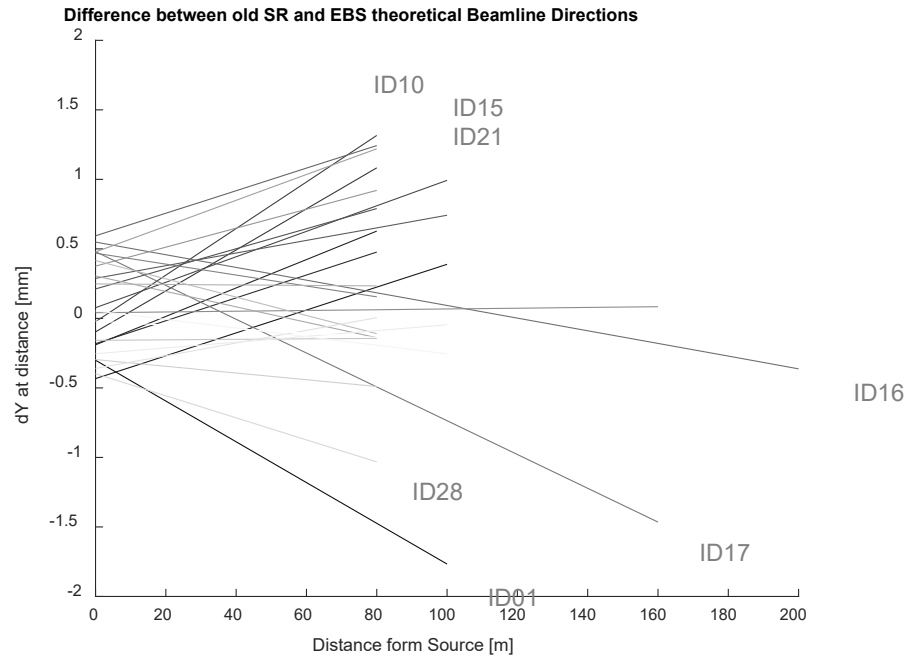
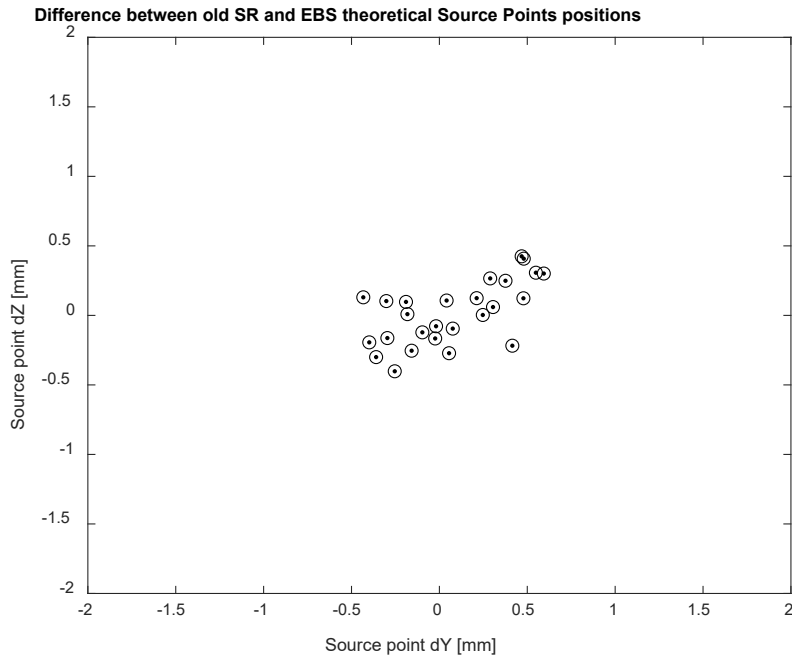


# BEAMLINE POSITION CONSTRAINT

The constraint was to align the beamline source points and directions as they were in the old machine. The beamline direction is determined by the magnet positions on either side of the source point.



Recall the second major constraint – put the machine back where the old machine was...



RMS R [mm]	RMS Z [mm]	RMS Direction [urad]
0.32	0.22	8

Machine simulations estimate the alignment uncertainties to be less than these values. The SR alignment estimates were:

- rms quadrupole horizontal orbit → 22 to 42  $\mu\text{m}$
- rms quadrupole vertical orbit → 22 to 53  $\mu\text{m}$

*P. Raimondi, et al., "Commissioning of the Hybrid Multi-Bend Achromat lattice at the European Synchrotron Radiation Facility"  
Phys. Rev. Accel. Beams 24, 110701 – Published 1 November 2021*

Our estimates for alignment uncertainties are:

## Medium gradient magnets

- $U(R) = 40$  to  $66$   $\mu\text{m}$  for a nominal value of  $100$   $\mu\text{m}$
- $U(Z) = 49$  to  $69$   $\mu\text{m}$  for a nominal value of  $85$   $\mu\text{m}$

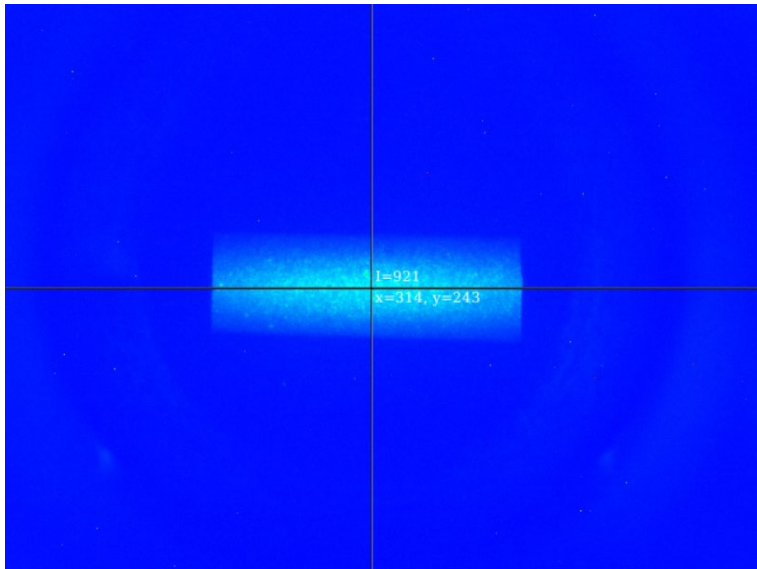
## Sextupole magnets

- $U(R) = 40$  to  $58$   $\mu\text{m}$  for a nominal value of  $70$   $\mu\text{m}$
- $U(Z) = 49$  to  $60$   $\mu\text{m}$  for a nominal value of  $50$   $\mu\text{m}$

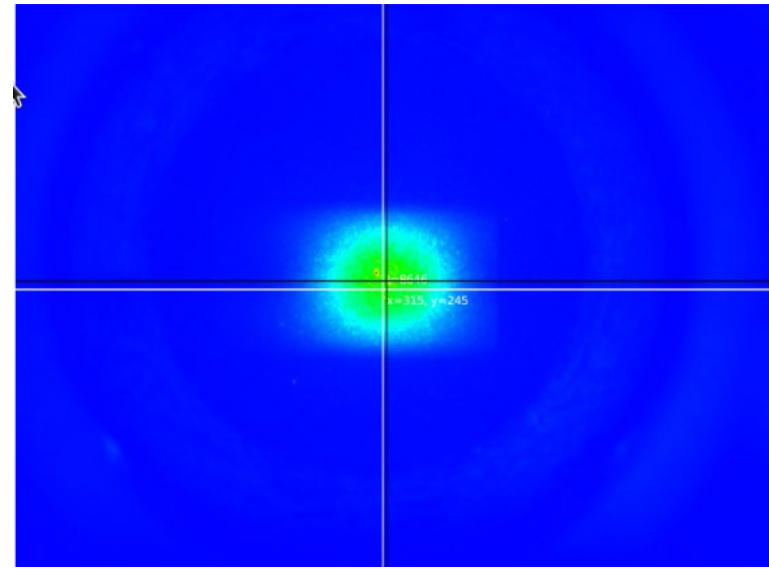
## High gradient and combined function magnets

- $U(R) = 40$  to  $47$   $\mu\text{m}$  for a nominal value of  $60$   $\mu\text{m}$
- $U(Z) = 45$  to  $54$   $\mu\text{m}$  for a nominal value of  $60$   $\mu\text{m}$

Finally, the beamline source points were within  $0.3$  mm and  $8$  urad of their nominal positions.



Old SR  
26 November 2018



EBS  
30 January 2020

...The EBS X-ray beam at distances varying from 45 to 160m was found within fractions of millimetres from its position in December 2018...

*E-mail Francesco Sette to all staff on 31/01/2020*





3D METROLOGY  
CONFERENCE



| The European Synchrotron

Thank you for your attention...