

4th 3D Metrology Conference 2019 November 5-7, London

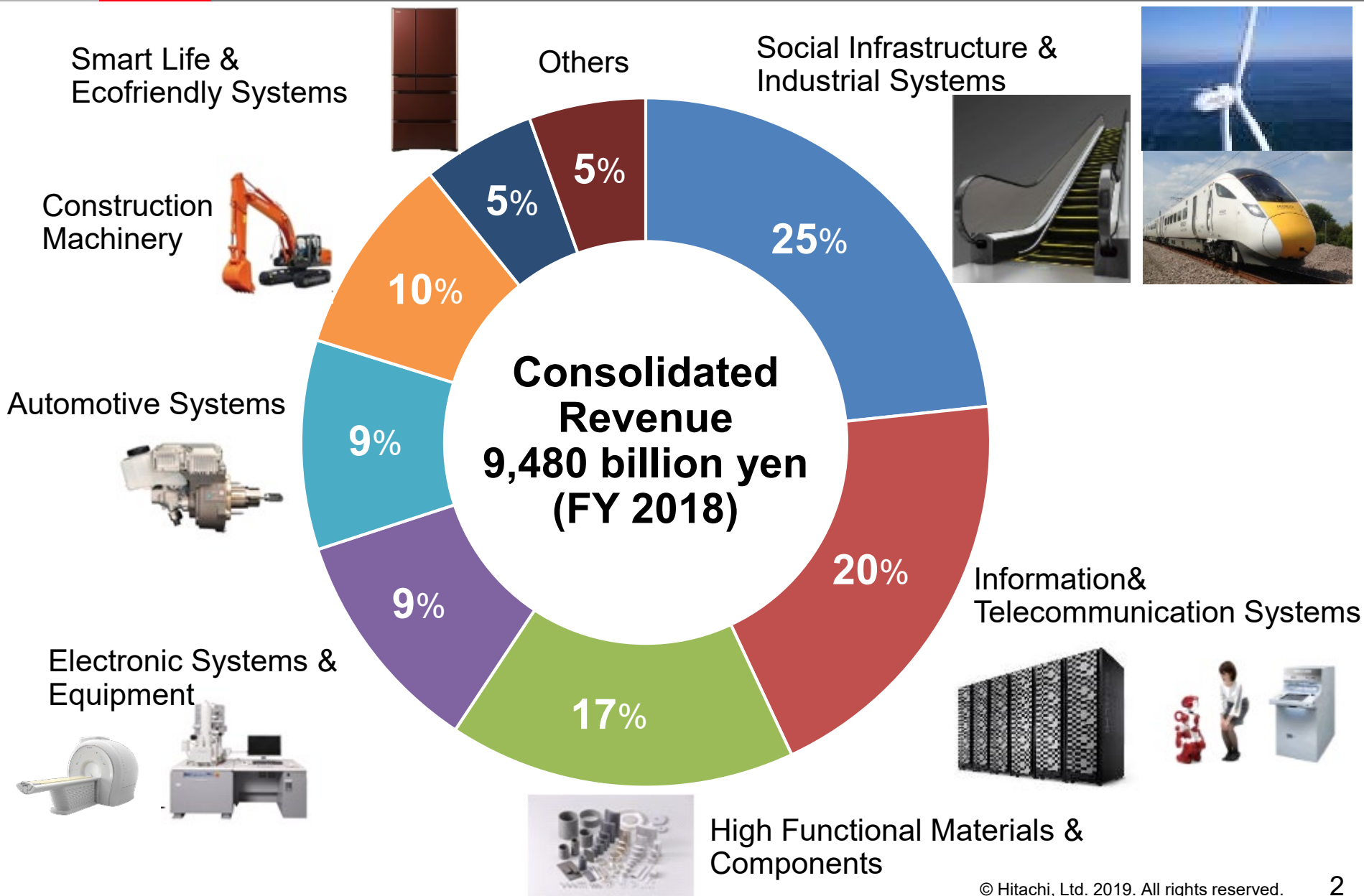
Development of Measurement Probe for Narrow-Space 3D Shapes

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Hitachi's train in England



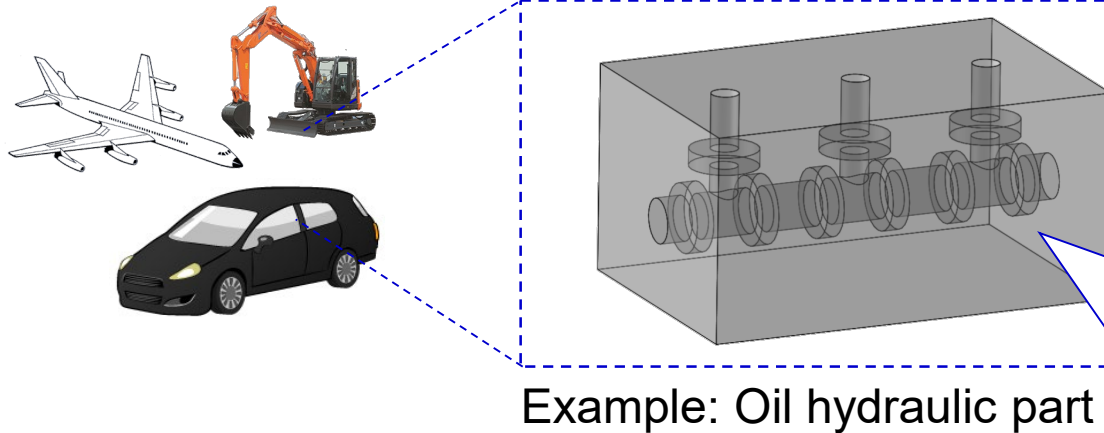
About Hitachi, Ltd.





- 1. Background & Purpose**
2. Our Former Probe & Improved Points
3. Accuracy Evaluation
& Demonstration of 3D Shape Meas.
4. Conclusion & Future Work

Complex mechanical parts in industrial Field

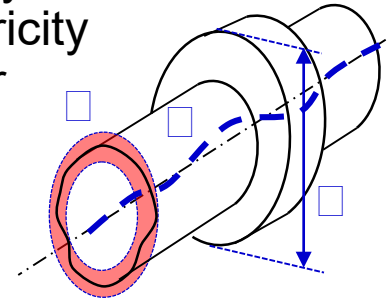


Example: Oil hydraulic part

Inspection item:

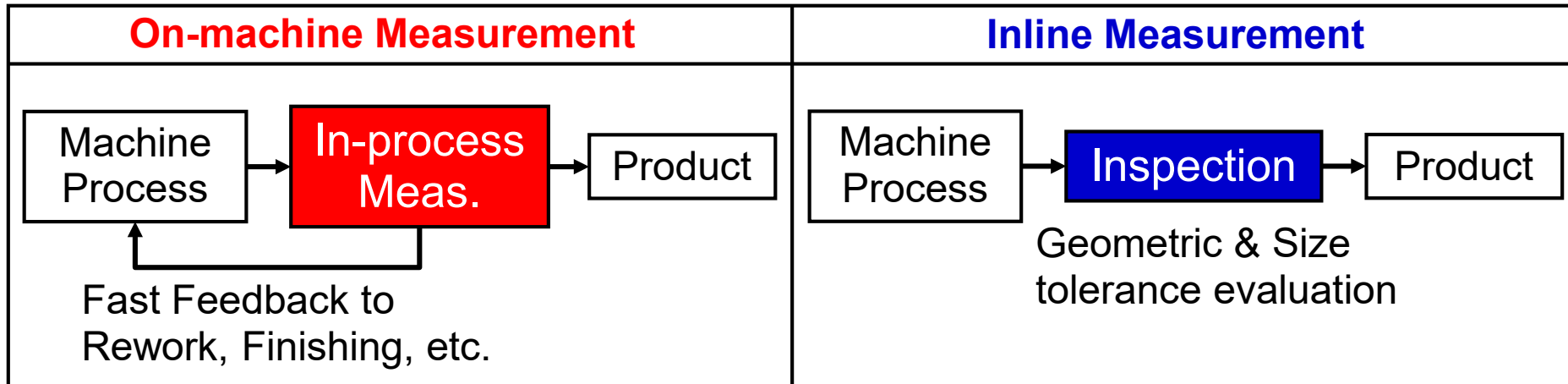
- Circularity
- Concentricity
- Diameter

-
-
-



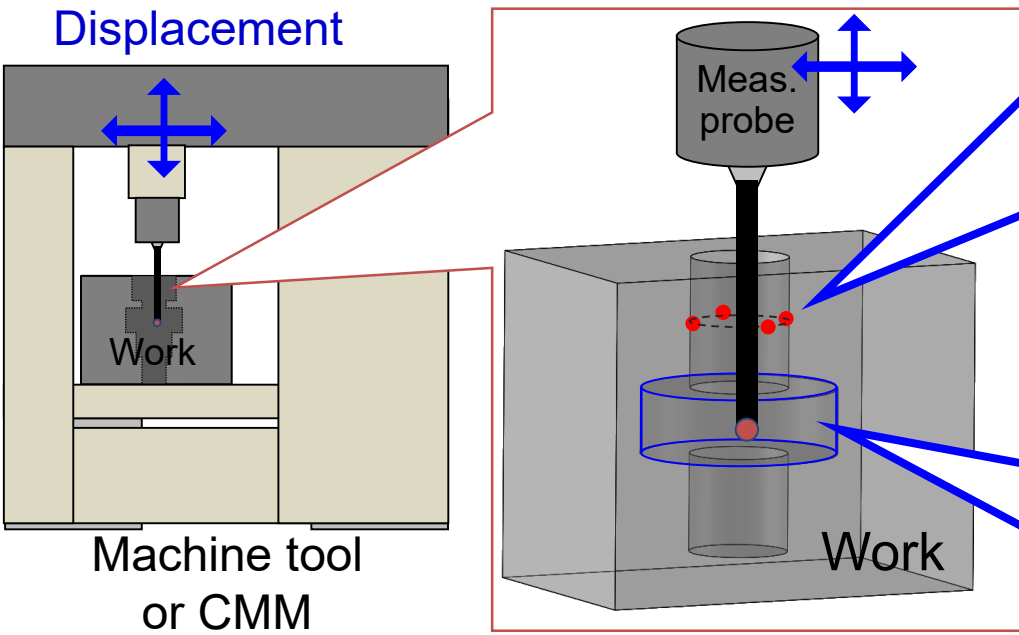
Geometric & Size tolerance evaluation is demanded

Need for High Accuracy On-machine / Inline Measurement



Issue of Conventional Method

Conventional on-machine/inline measurement probe;
Meas. surface point by touching surface with mechanical displacement



Problem 1 Point meas.

The first diagram shows a circular surface with four red dots representing measurement points. A blue double-headed arrow across the diameter is labeled 'Meas. size'. Below it is the text '4 meas. point'. The second diagram shows the same circular surface with four red dots at different positions. A blue double-headed arrow across the diameter is labeled 'Meas. size'. Below it is the text 'Another 4 meas. point'.

Problem 2

The diagram shows a probe tip positioned above a U-shaped hole in a workpiece. A red dashed line outlines the hole. A blue arrow points from the text 'Cannot touch' to the probe tip, and another blue arrow points from 'No surface data' to the hole. A double vertical line is placed between the two phrases.

Concept of Novel Developed Probe

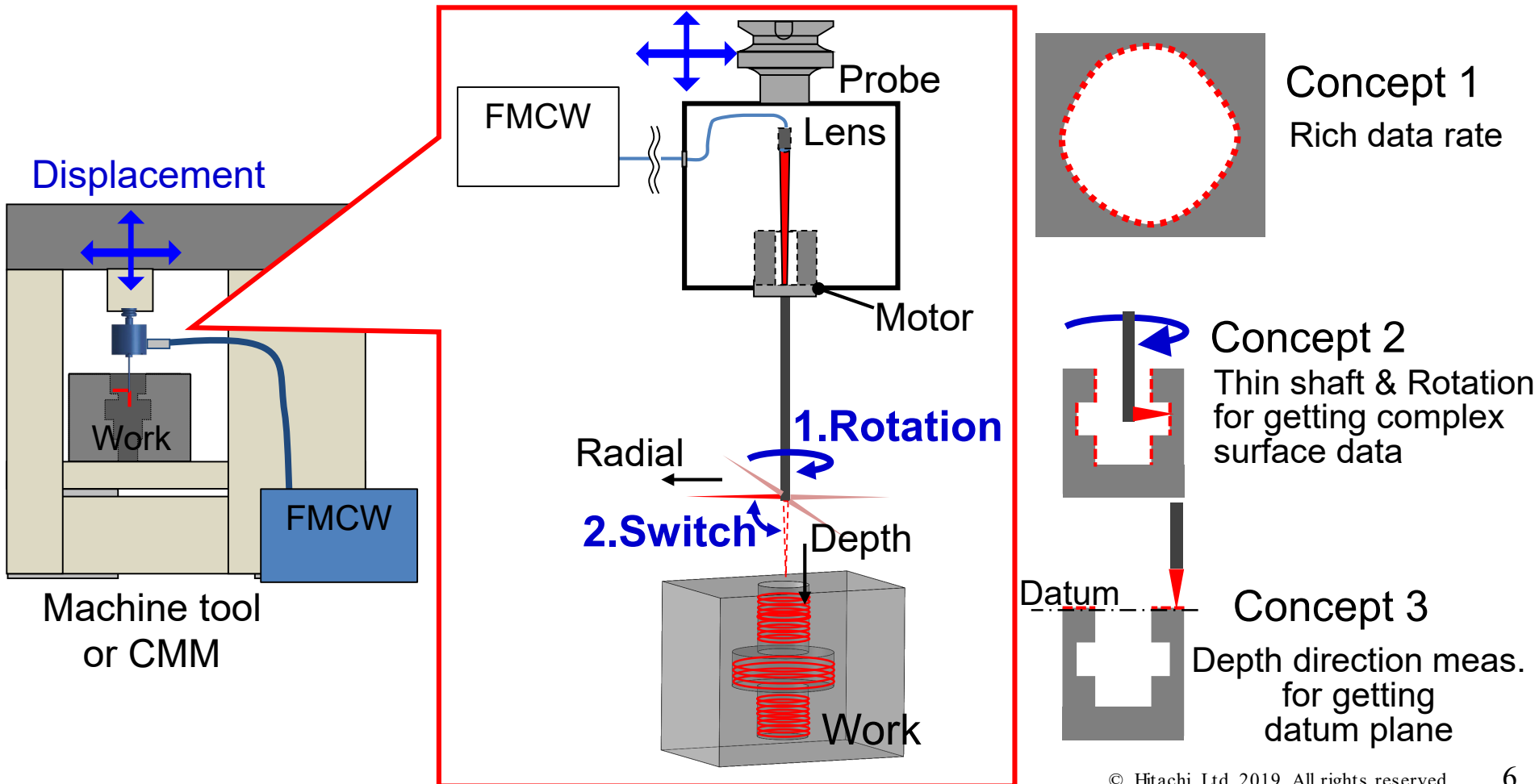
Multi-directional meas. probe which overcomes the conventional problems is proposed.

□ Development of fast on-machine/Inline measurement probe

Purpose; for 3D-shape inspection using FMCW*

□ Target accuracy □ $\pm 5\mu\text{m}$

*FMCW: Frequency Modulated Continuous Wave



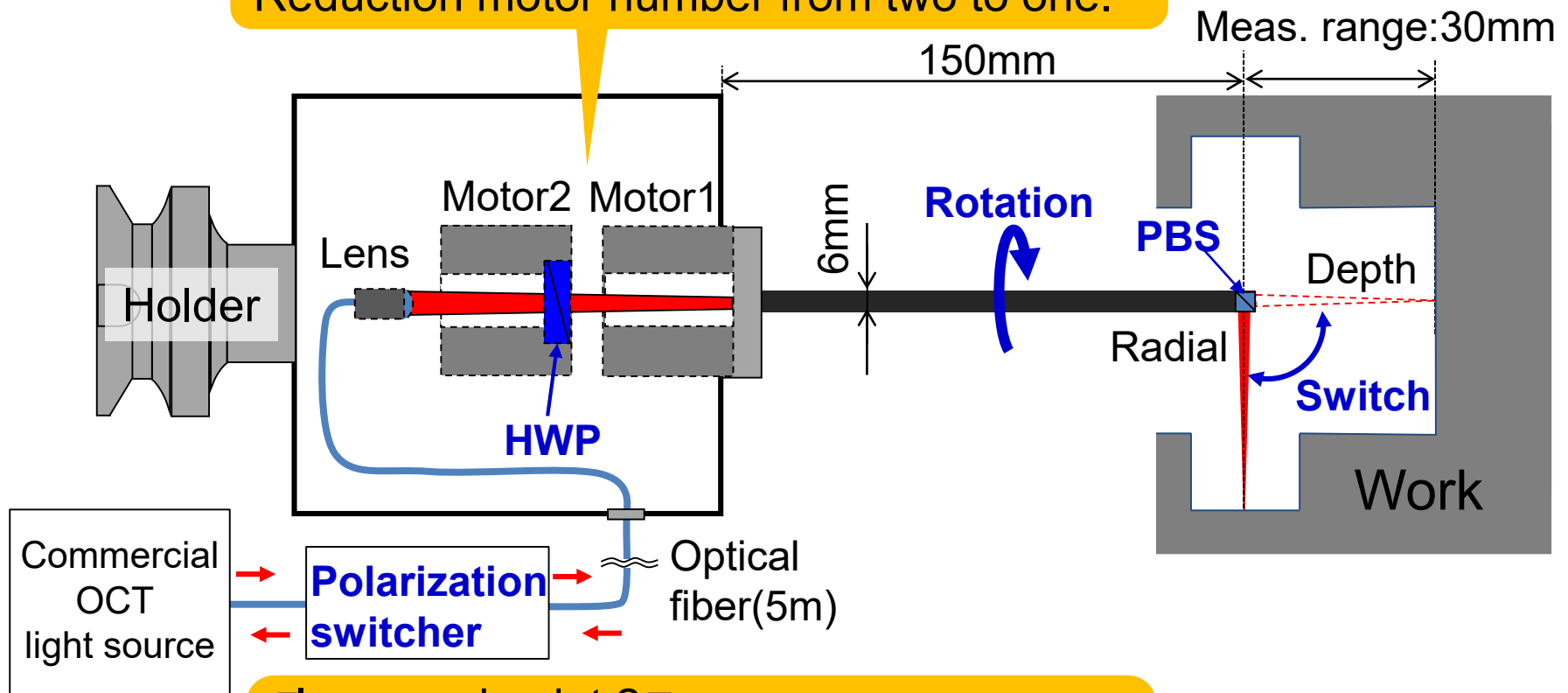


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Our Former Probe

A multi-direction measurement probe which we have reported in 3D Metrology Conference 2018.

Improved point 1
Reduction motor number from two to one.

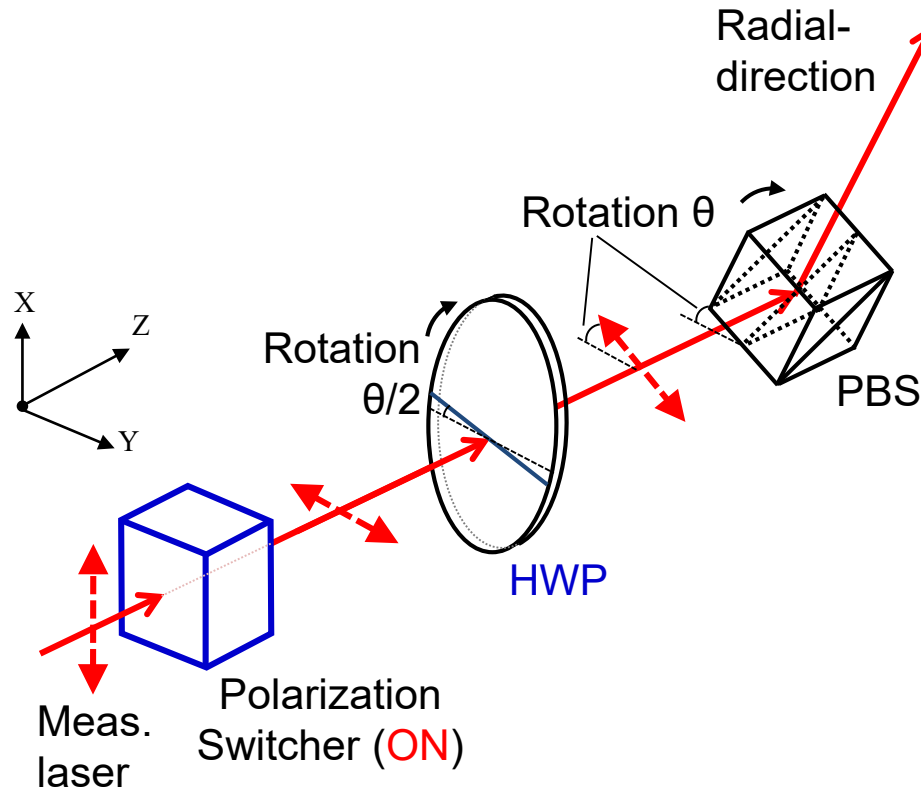


Improved point 2
In-house distance measurement system for measuring long distance stably.

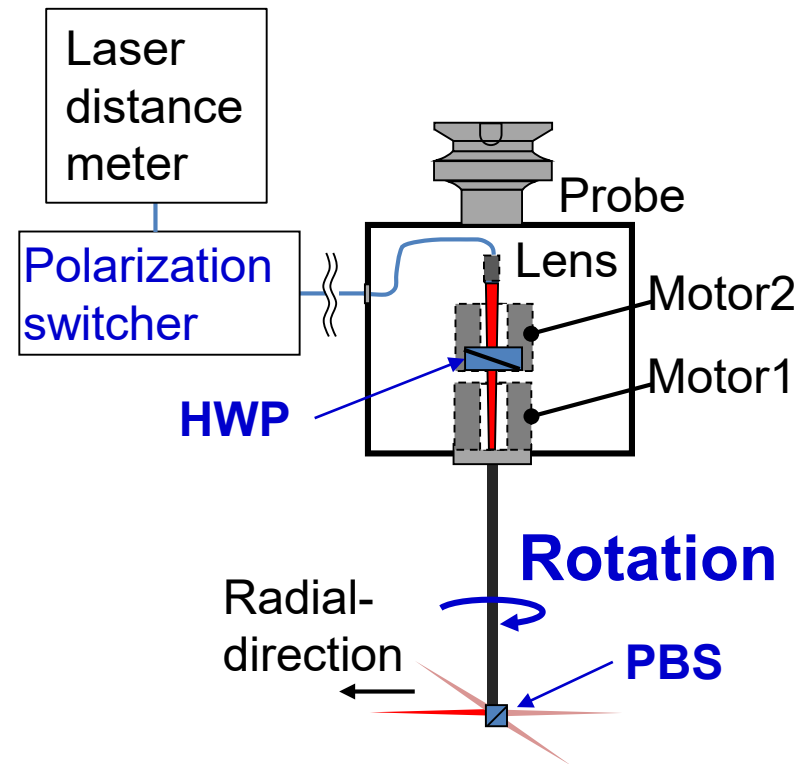
Point 1 Our Former Beam Rotation System

HWP(Half-Wave Plate) is adopted for rotating a beam

Principle of beam rotation



Beam rotation system

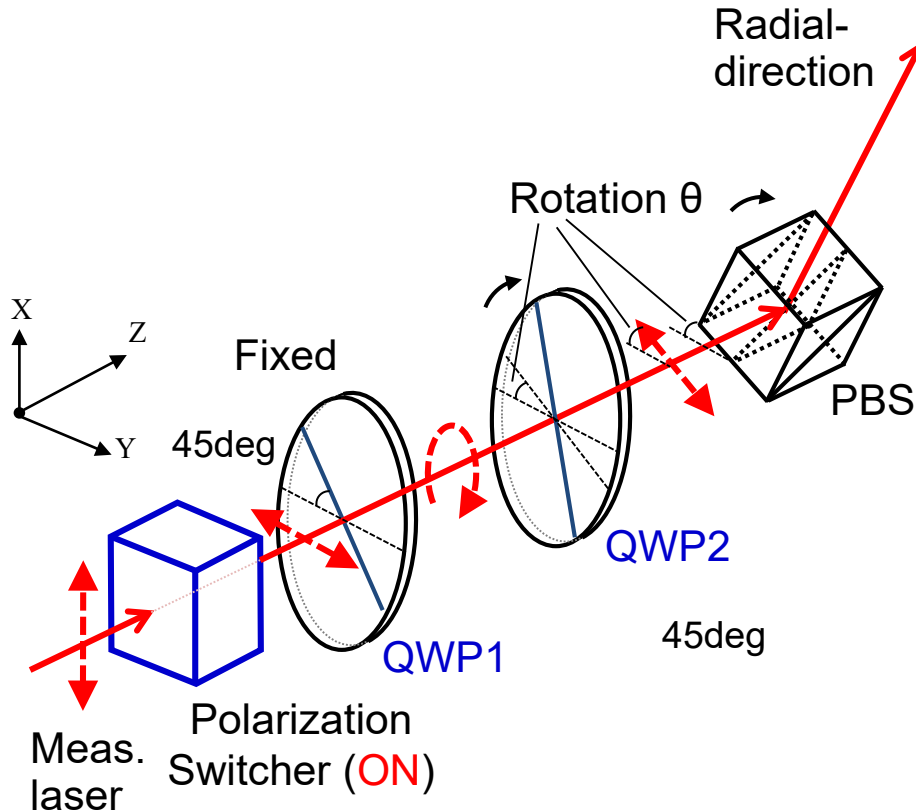


This system uses two motors for rotating a beam.

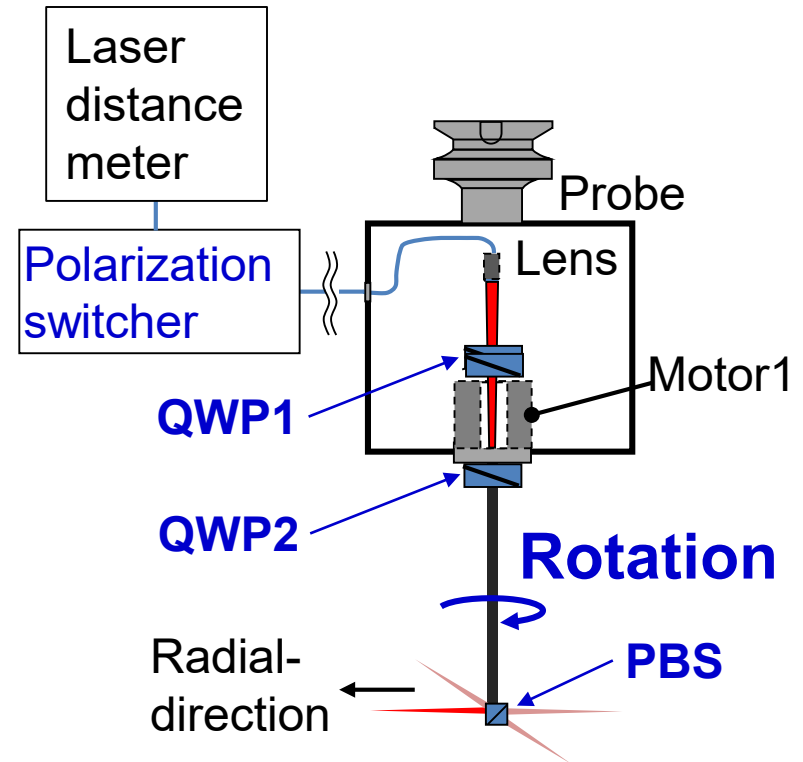
Point 1 New Beam Rotation System

Two QWP(Quarter-Wave Plate) are adopted for rotating a beam

Principle of beam rotation



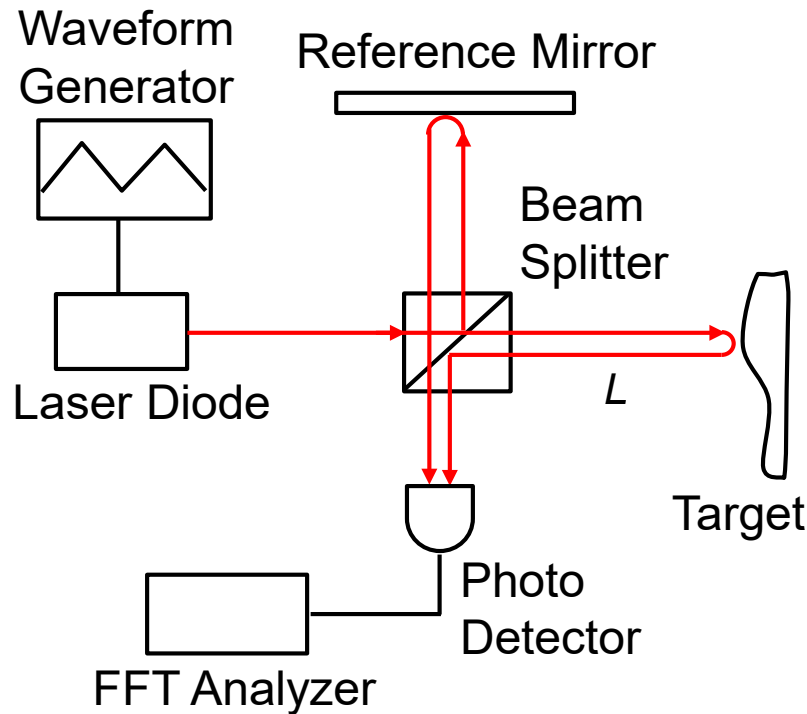
Beam rotation system



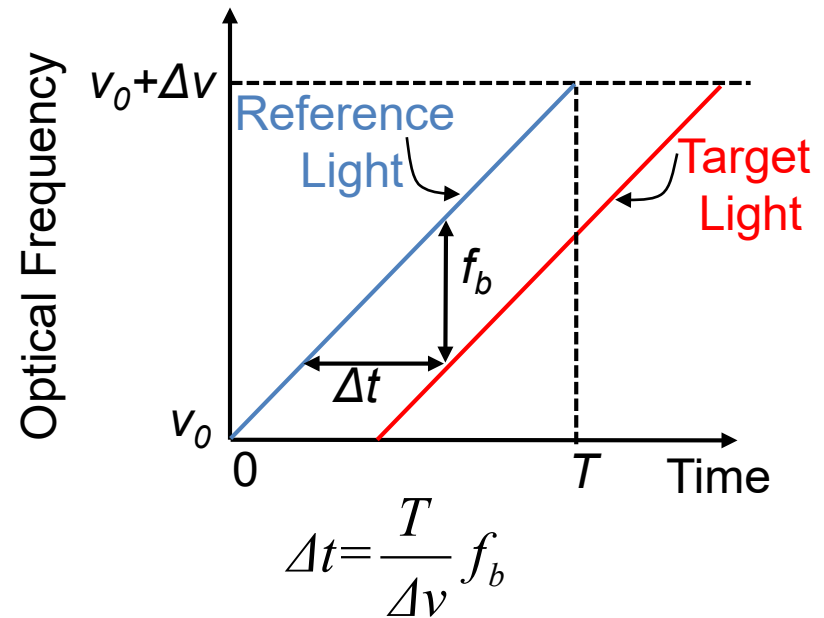
New system uses only one motor for rotating a beam.

Laser distance meter based on Frequency Modulated Continuous Wave

Optical setup



Distance Measurement Principle



Light travels a roundtrip distance L during Δt .
 L is expressed using light speed c .

$$\underline{L} = \frac{1}{2} c \Delta t = \frac{cT}{2\Delta v} \underline{f_b} \quad \text{Distance } L \propto \text{Beat Frequency } f_b$$

Point 2 Stable Measurement of Long Distance

Long distance measurement

	Commercial System	In-house System
Laser Type	ECL*1	VCSEL*2
Coherent Length	60mm	9m
Measurable Distance	30mm	300mm*3
Wavelength Swept Range	25nm	10nm
Data Rate	3kHz	10kHz
Light Source Cost	☹️	😊

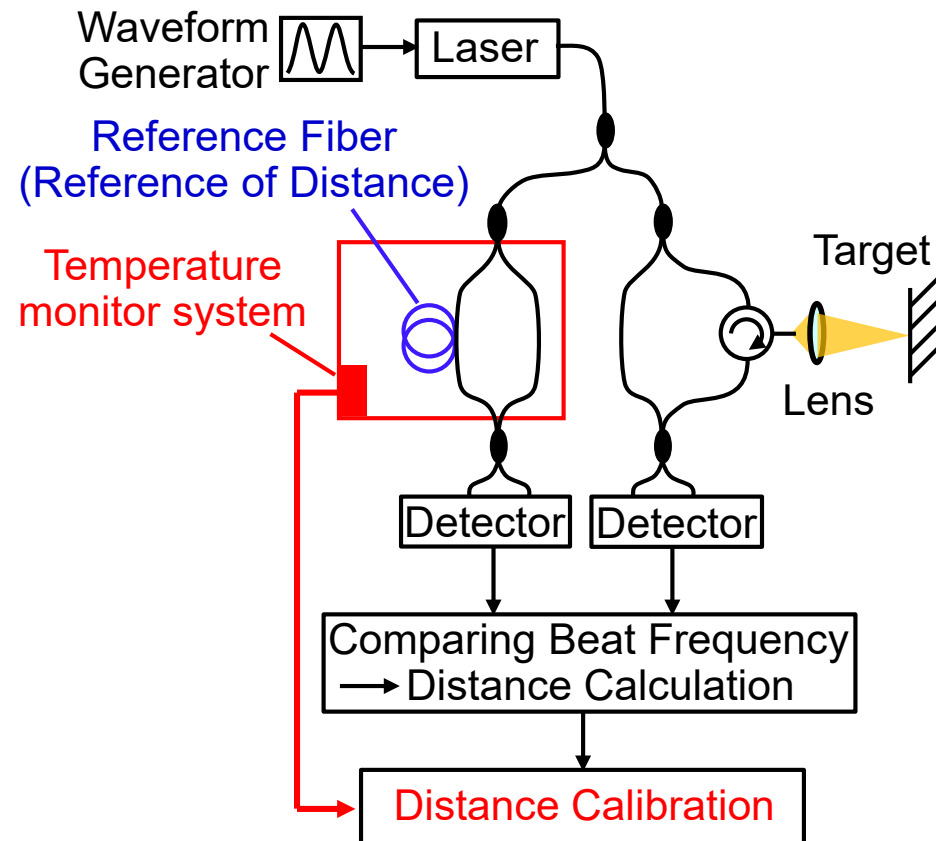
$$\text{Distance Resolution } \frac{\Delta L}{\Delta \nu} = \frac{c}{2 \Delta \nu} \frac{\text{Wavelength Sweep Range}}{\text{Wavelength Sweep Range}}$$

- Improvement of the distance resolution by
1. Calibrating a non-linearity of frequency sweep
 2. Interpolating FFT peak position



In-house system achieves high-accuracy long distance measurement.

Stable distance measurement



Optical path change of reference fiber is calibrated by temperature monitor system.

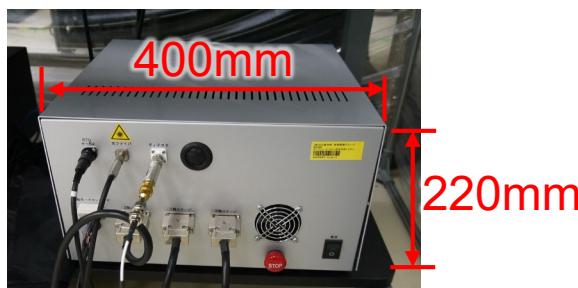
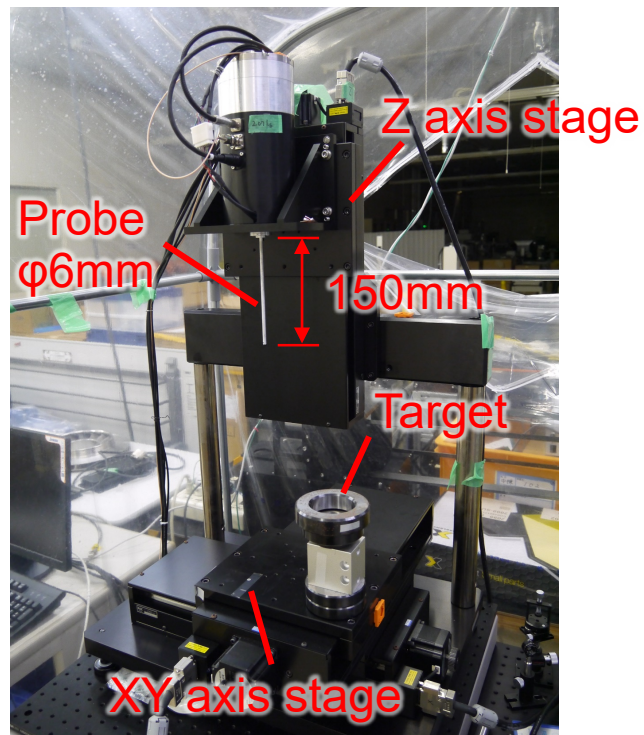
*1ECL:External Cavity Laser, *2VCSEL:Vertical Cavity Surface Emitting Laser, *3Limited by the A/D converter frequency



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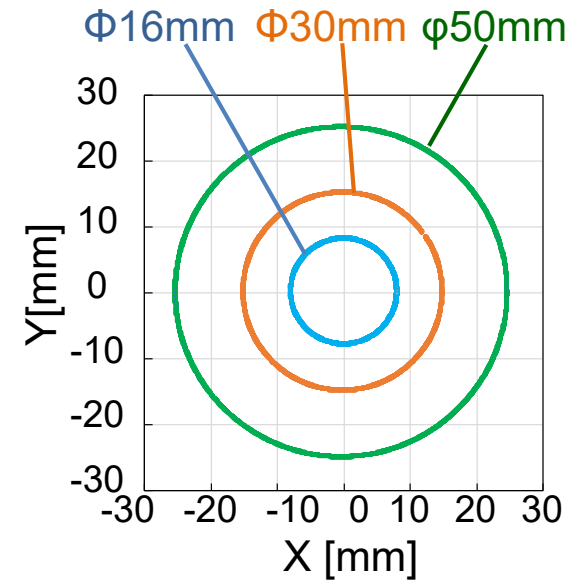
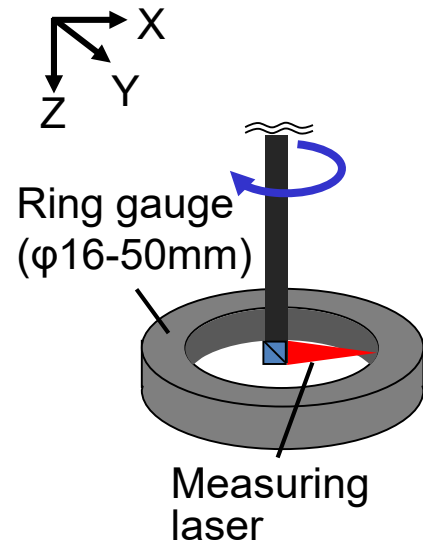
Evaluation of Short Time Accuracy

■ Developed system



Control box
(Laser, Stage controller, etc)

■ Ring gauge measurement



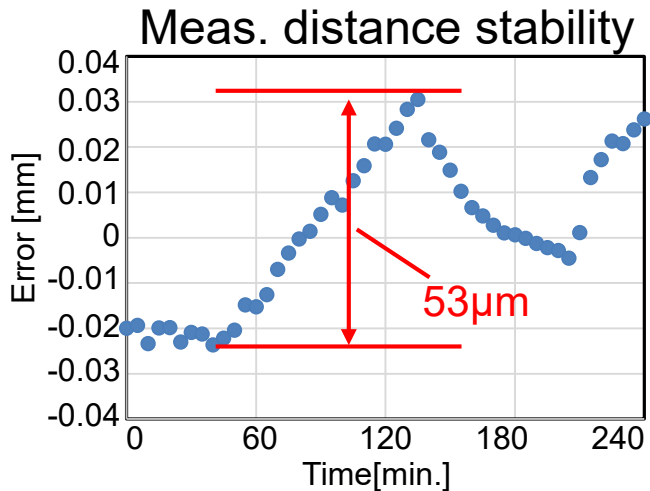
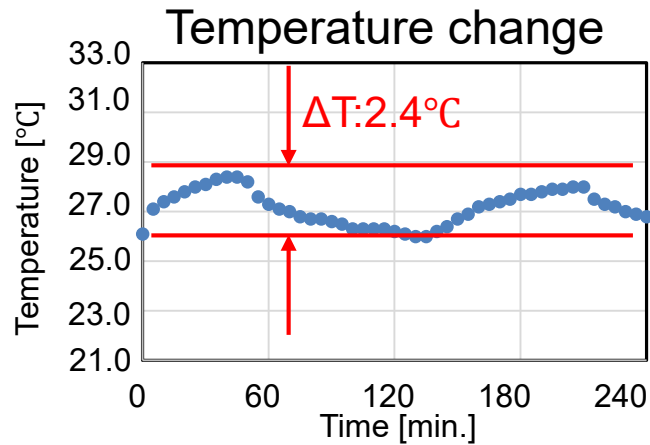
Value [mm]	15.999	30.001	49.996
Meas. result [mm]	15.9992	30.0013	49.9949
Error [μm]	0.2	0.3	-1.1

Short time accuracy is better than target accuracy $\pm 5\mu\text{m}$

Evaluation of Measurement Stability

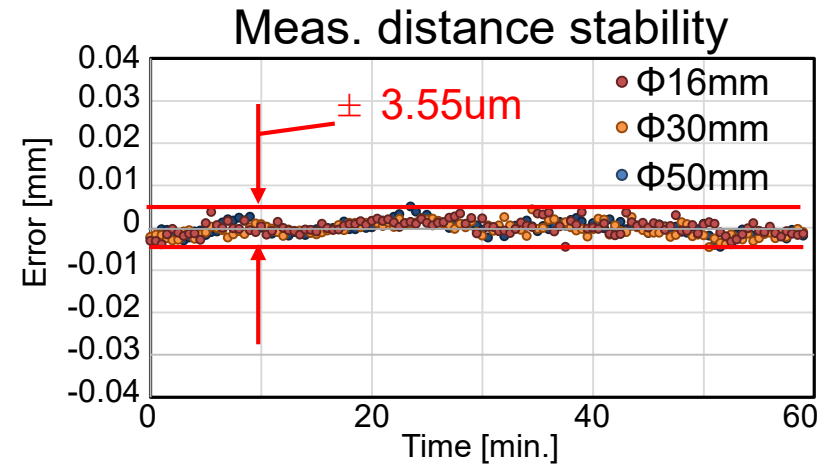
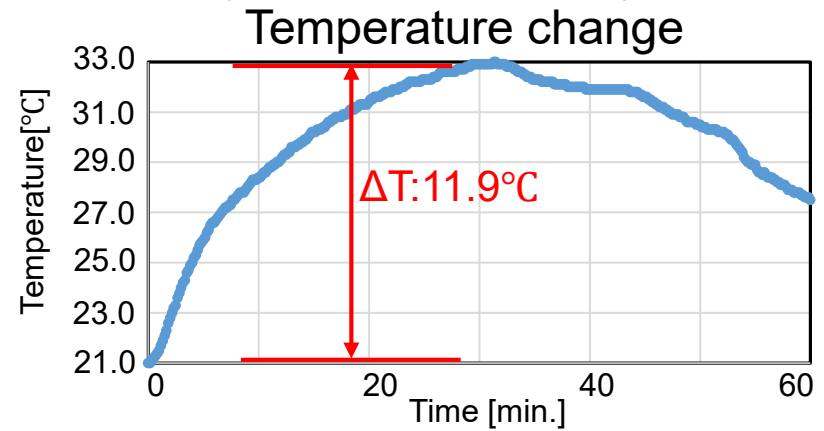
- Measurement stability is evaluated by changing a temperature surrounding the system.

Our former system



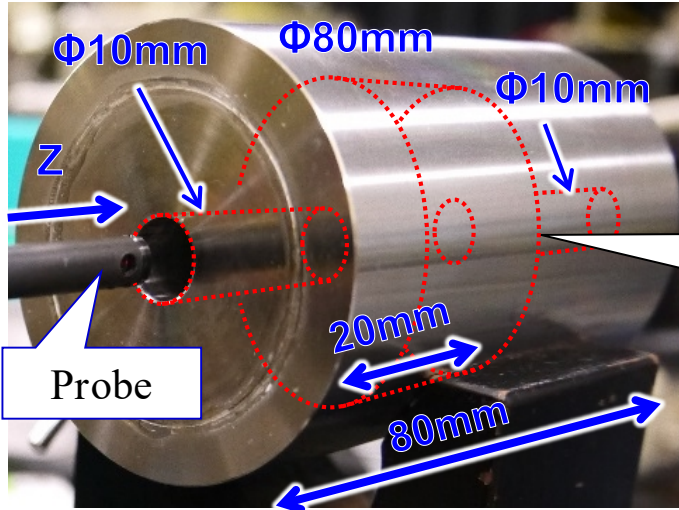
Developed system

(Temperature calibration)

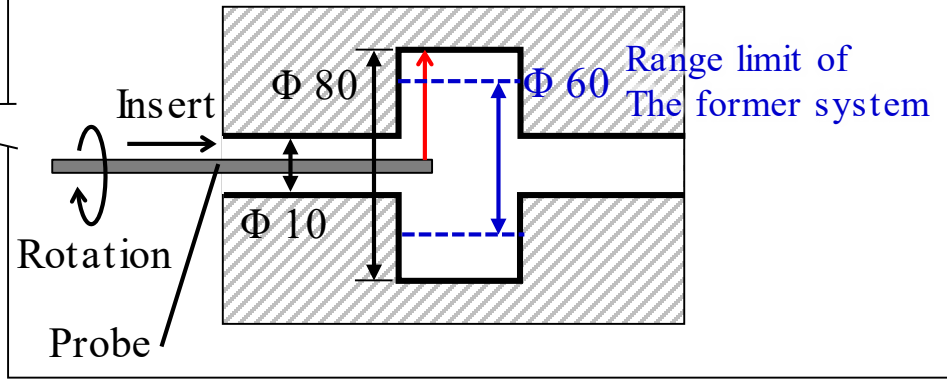


Measurement stability is better than target accuracy $\pm 5\mu\text{m}$

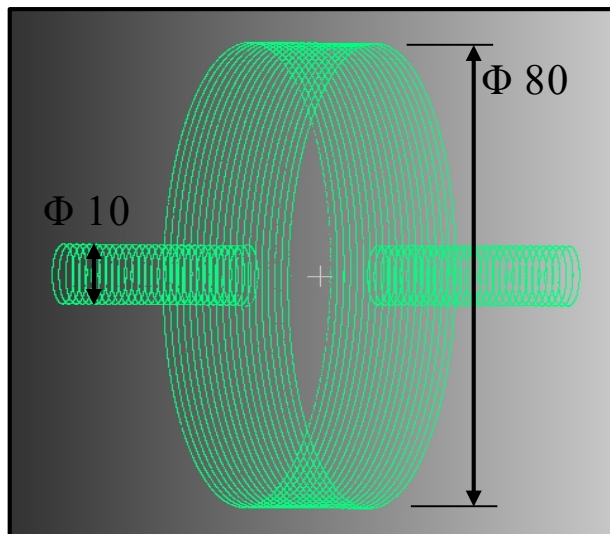
- Inner shape measurement of a cylinder which has different size holes inside



The former system can not measure the whole shape by a single scan.



- Measurement result



Developed system can measure the whole shape by a single scan.

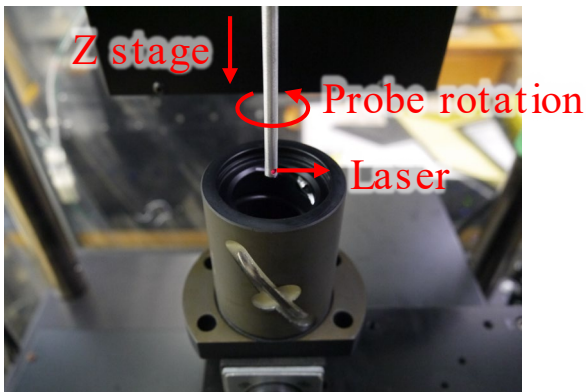
Application Data to a Ball Screw

■ Sample

Misumi BSSZ3232

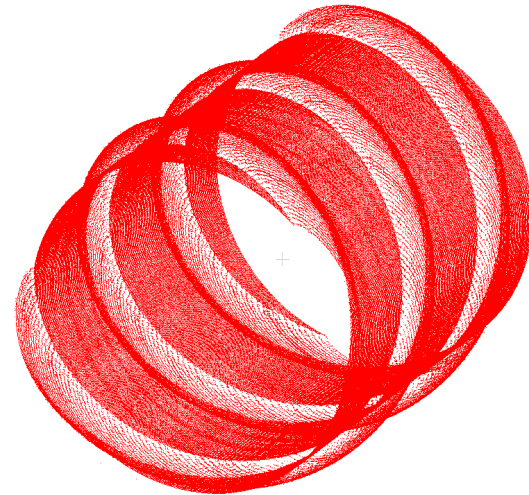
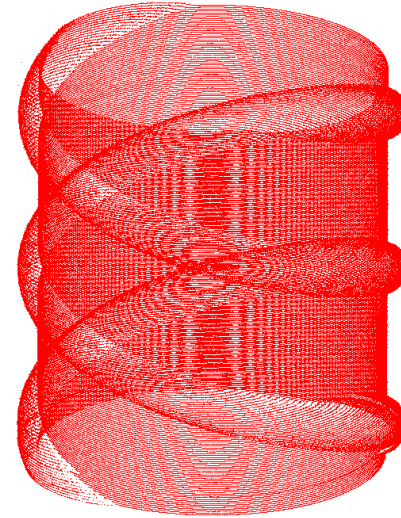


■ Measurement condition



■ Measurement result

655,690points



Developed system can measure complex inner shape.

Application Data to a Torque Converter

■ Sample

Impeller of a torque converter for automobile

https://www.exedy.com/ja/product/passenger/at_torque/



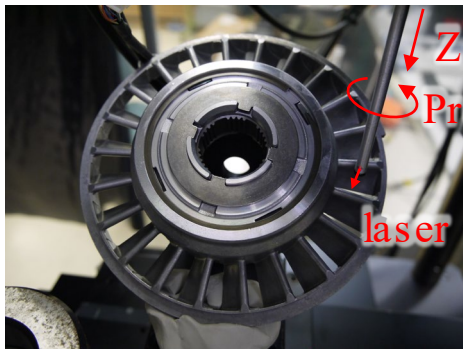
Actual figure



Toyota



■ Measurement condition



Z stage

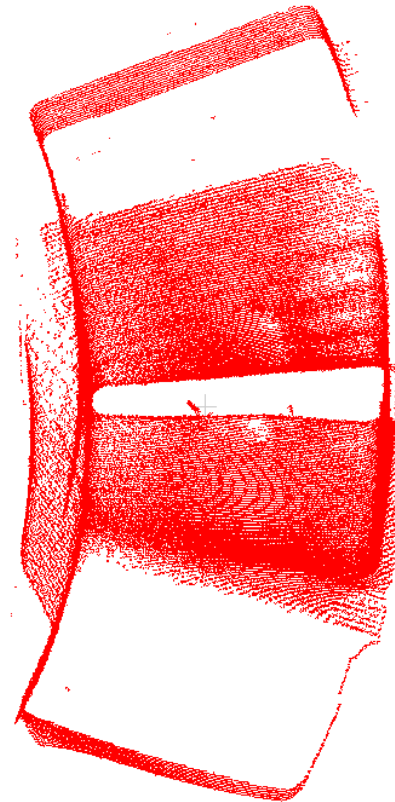
Probe rotation

laser

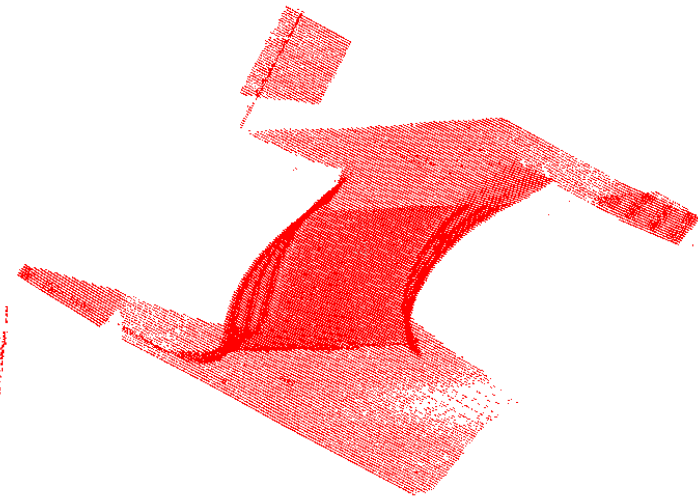
■ Measurement result

311,966points

Front view



Side view



Developed system can measure complex inner shape.



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■ Conclusion

Developed:

Our former multi-directional optical measurement probe is Improved by

1.Reduction of motor number from two to one.

2.In-house distance measurement system for measuring long distance stably.

Achieved:

- Stability of long term measurement is $\pm 3.55\mu\text{m}$ (<Target: $\pm 5\mu\text{m}$).
- Long range measurement r5~40mm is demonstrated(max range:300mm).
- Measuring complex 3D-shape of such as ball a screw and a torque converter.

■ Future Work

- Application of the developed probe to various products being made in Hitachi's factories.
- Feedback of the measurement data to the machine processing condition.

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