

Alignment of Radio Telescopes with Photogrammetry

Date: 23.11.2016



Outline

1. About sigma3D

2. Overview Radio Telescopes worldwide

3. Requirements / Accuracy Radio Telescopes

4. Measurement & Evaluation - Surface Alignment

5. Measurement & Evaluation - Various Elevation

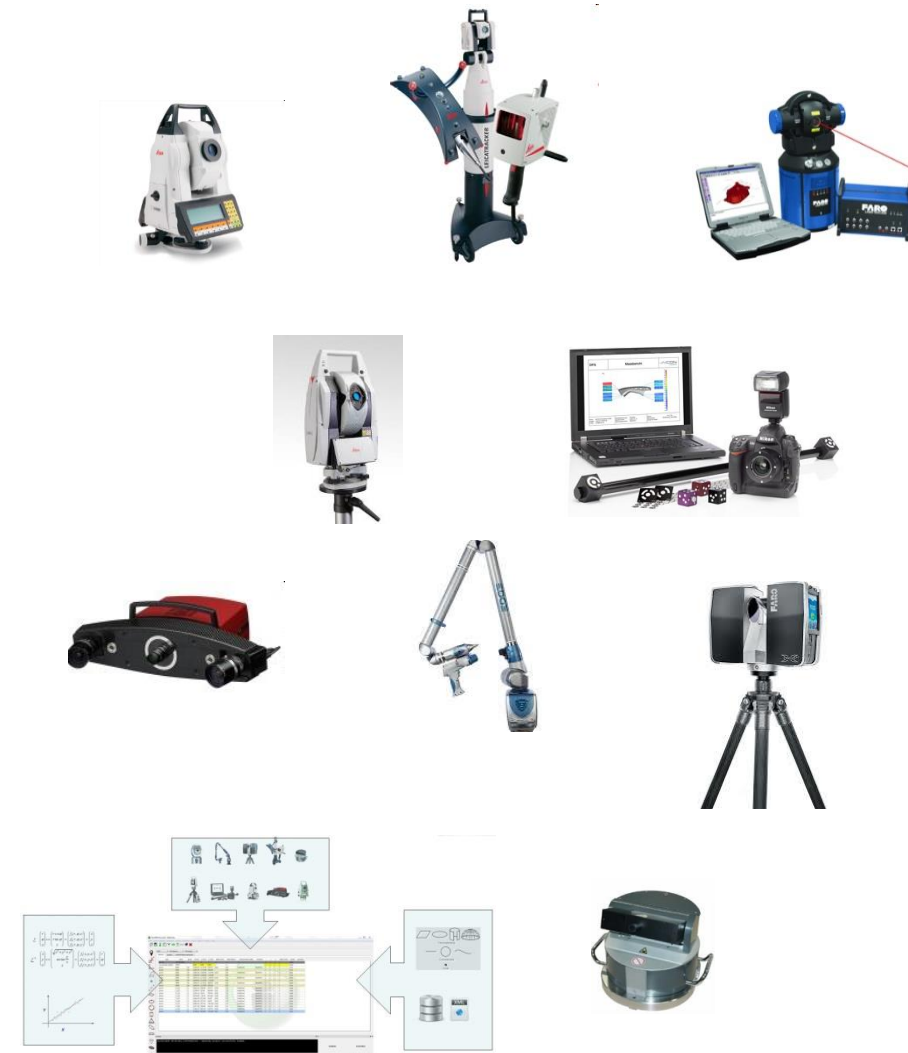
6. Results & Summary

Mobile 3D Measurement Service



- ✓ Mobile 3D Measurement Service
- ✓ Scanning and Digitizing
- ✓ Verification and Calibration tooling machines & CMMs
- ✓ Software development for 3D measurement tasks

- ✓ Since 8 years Radio Telescope Alignment



Design types Radio Telescopes

The performance of an antenna depends on several parameters:

- Diameter of the Main-Reflector -> Sensitivity / Resolution
- Surface accuracy / receiver equipment -> frequency range
- Turnable or static -> Application areas



Arecibo, Puerto Rico, 305m



Pico Veleta 30m, Spain

Application for Radio Telescopes & Antennas

Sat-data communication (data, pictures)

- $d=1,8\text{m}$ to 13m (mostly under 10m)
- frequencies: S- and C-Band, $2\text{-}6\text{GHz}$ > RMS $2\text{-}3\text{mm}$

Satellite control

- $d= 6\text{m}$ to 18m
- frequencies: Ku-Band, $10,7 - 12,75\text{GHz}$

Geodesy / Metrology

- $d=13\text{m}$ to 35m
- frequencies: L- and M-Band, $40 - 100\text{GHz}$

Geodesy / Deep-Space Missions / Astronomy

- $d=35\text{m}$ to 100m
- frequencies M-Band, up to 200GHz

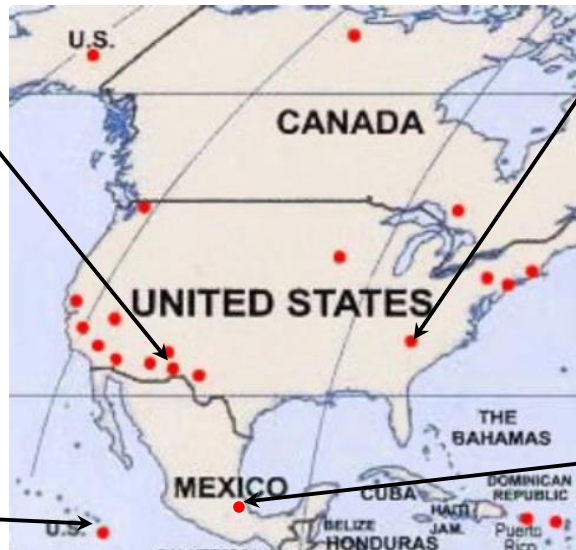


Radio Telescopes in America

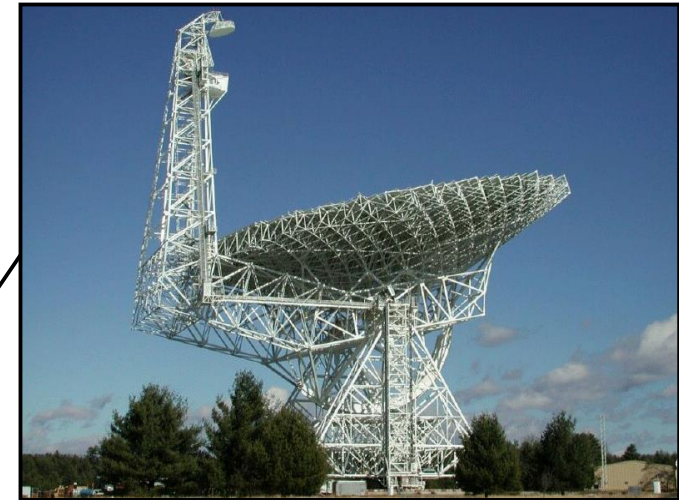
Very Large Array, New Mexico. 27 x 25m



Mauna Kea, 25m, Hawaii



Green Bank Telescope, 110m x 100m

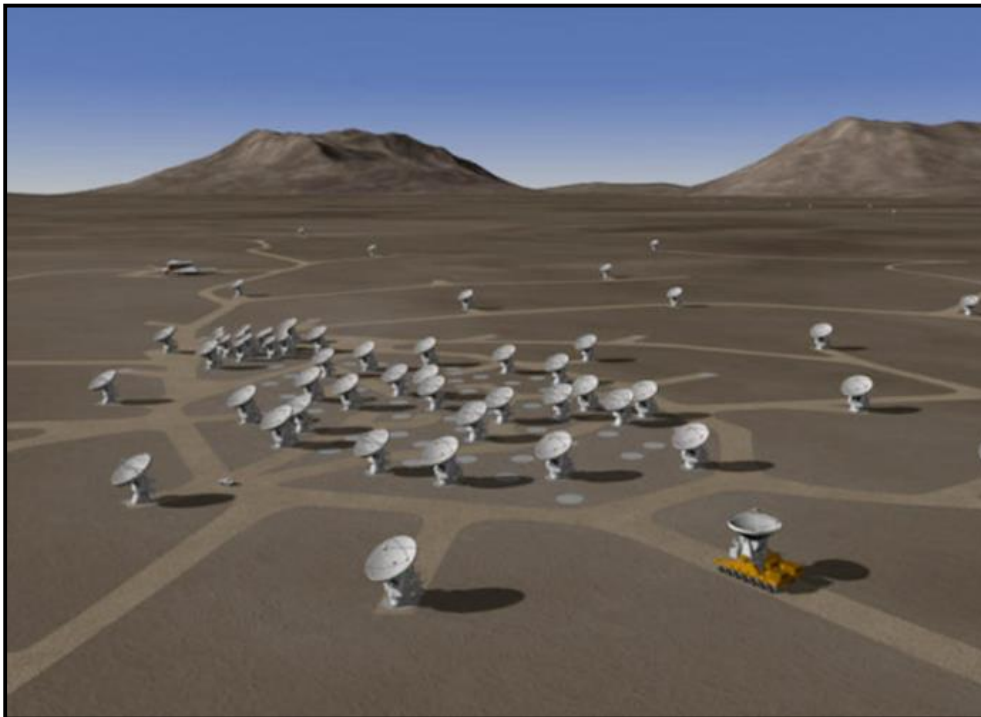


LMT, Mexico, 50m

The biggest Radio Telescope project

ALMA – Atacama Large Milimeter Array

- Location Atacama desert, Chile, 5000m o. sea-level
- 66 single Telesopes (54 x 12m und 12 x 7m)



Radio Telescopes - Europe

Sardinia Radio Telescope, actual technology

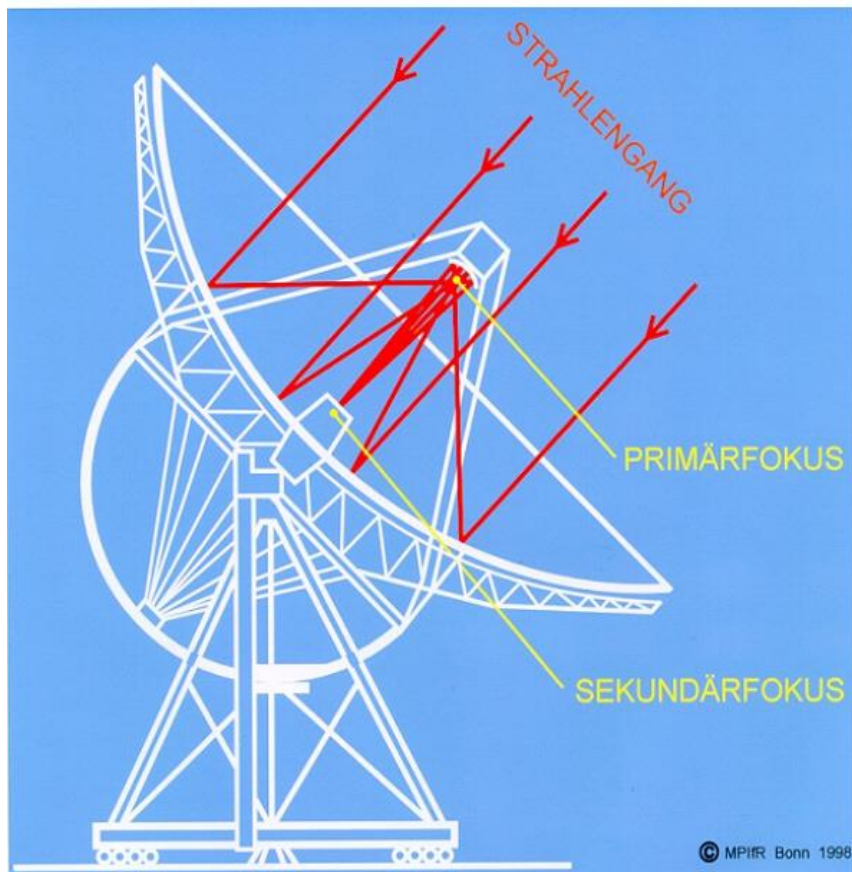


Effelsberg, Germany, d=100m



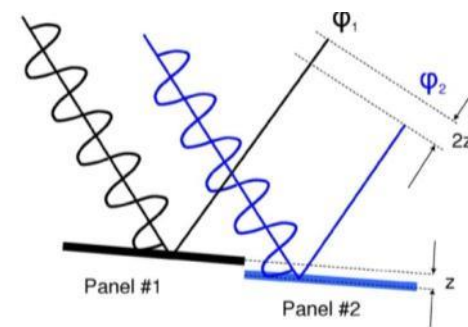
- ✓ Multiple receivers
- ✓ Sub-Reflector driven by Hexapod
- ✓ Active Surface of the Main-Reflector

3D Measurement Challenge



Efficiency depends on the accuracy of the panel surface.

The surface accuracy should be about **1/20** of the wavelength.



For the different frequencies, this means a surface accuracy of:

- X-Band (9 GHz, 33 mm) -> 1,65 mm (RMS)
- Ka-Band (32 GHz, 9,2 mm) -> 0,45 mm (RMS)

Sardinia Radio Telescope - SRT



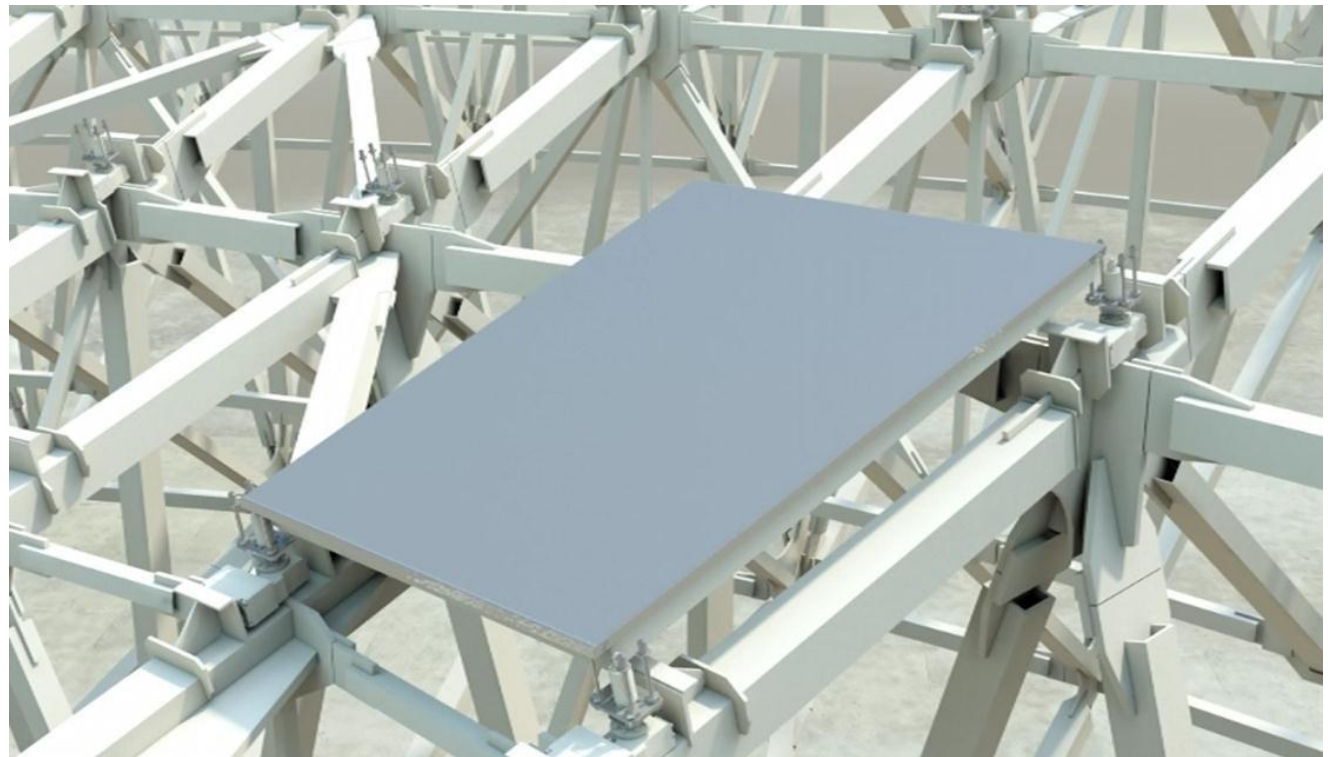
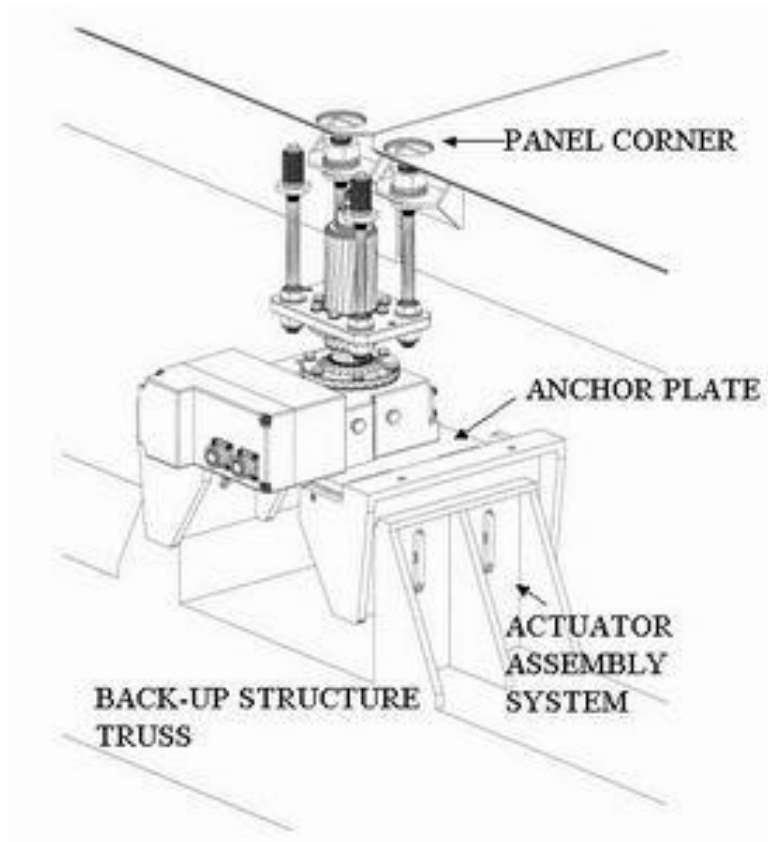
Technical Data SRT

- 3rd largest Radio Telescope in Europe
- Main Reflector **64 m diameter**
- 1008 panels
- Sub-Reflektor 7,9 m diameter
- Gregorianische setup (concave Sub-Reflector)
- **Active Surface**

- Surface accuracy RMS 500 μm
(guaranteed by the manufacturer)

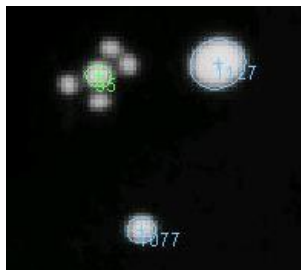
- Need deformation information in six
different elevation positions for Active
Surface (look-up table)

Active Surface



Measurement & Evaluation process

Image acquisition



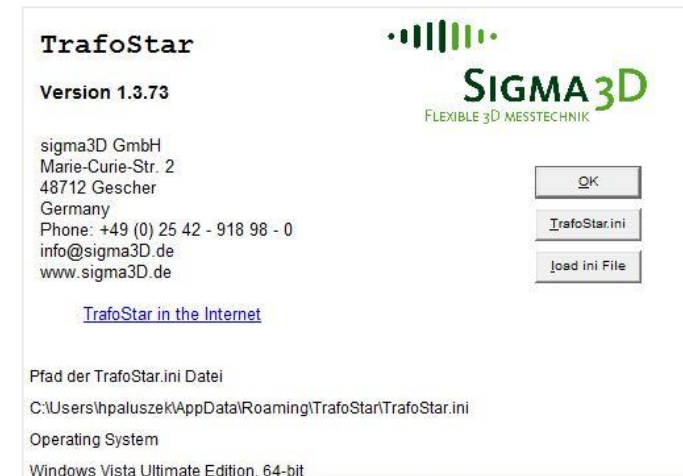
$x' y'$
2D coordinates

Calculate 3D coordinates



XYZ
3D coordinates

Determine Surface deviation



Best-Fit Parameters
 Δh

Components Measurement System

A modern photogrammetric measurement system consists of:

- ✓ 24 MPixel high resolution digital camera Nikon D3X
- ✓ Personal computer (Notebook) with analysis software
- ✓ Calibrated carbon fibre scale bar
- ✓ Coded targets to identify identical points during image processing

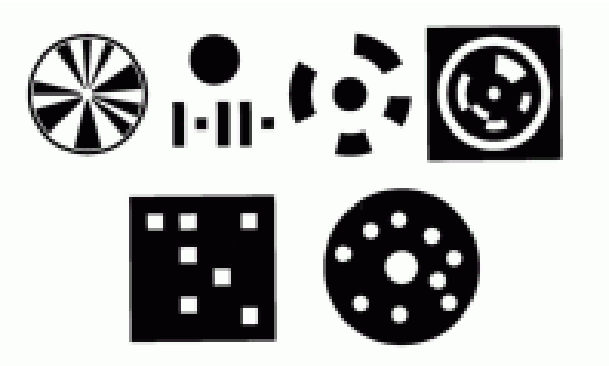


Coded targets to identify identical points



Coded targets are targets that serve to signal points in object space and are provided with a code.

This code number is a point at which the item is automatically identifiable.



Different codes available

Accuracy for Photogrammetry

In general, the following general approach applies to the measurement accuracy (S_{xyz}):

$$S_{xyz} = q * m * S_{x'y'}$$

1- σ value!

q = Quality factor for the geometry of the recordings
0.4 to 0.8 with a good configuration, 2 for bad configuration

m = Image scale

$S_{x'y'}$ = Image measurement accuracy

For panel alignment following theoretical results estimated:

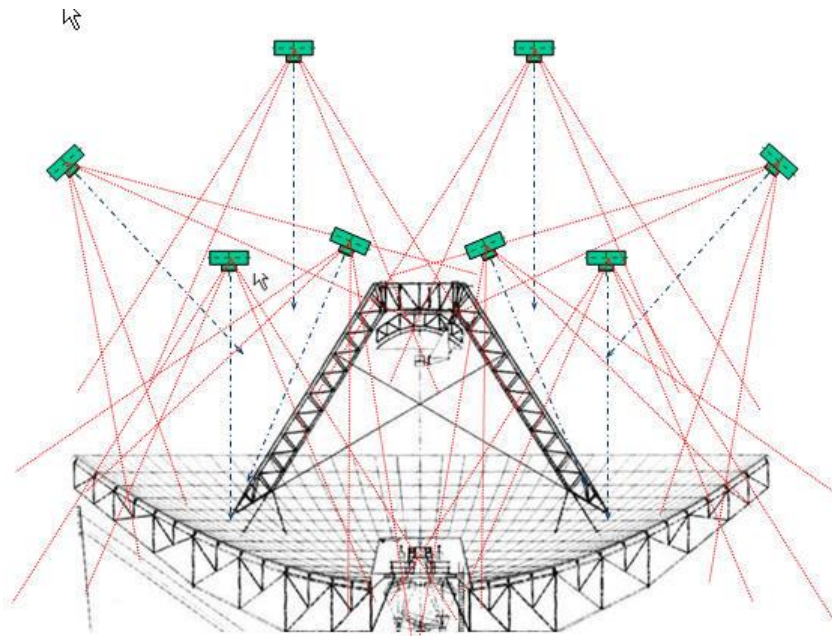
- best-case $S_{xyz} = 0,7 * 1200 * 0,06 \mu\text{m} \rightarrow 50 \mu\text{m} \rightarrow$ Surface RMS 175 μm
- worst-case $S_{xyz} = 1 * 1500 * 0,20 \mu\text{m} \rightarrow 300 \mu\text{m} \rightarrow$ Surface RMS 1050 μm
- average $S_{xyz} = 0,8 * 1400 * 0,10 \mu\text{m} \rightarrow 112 \mu\text{m} \rightarrow$ Surface RMS 392 μm

Reachable: **Only with stable measurement conditions!**

Camera Positions

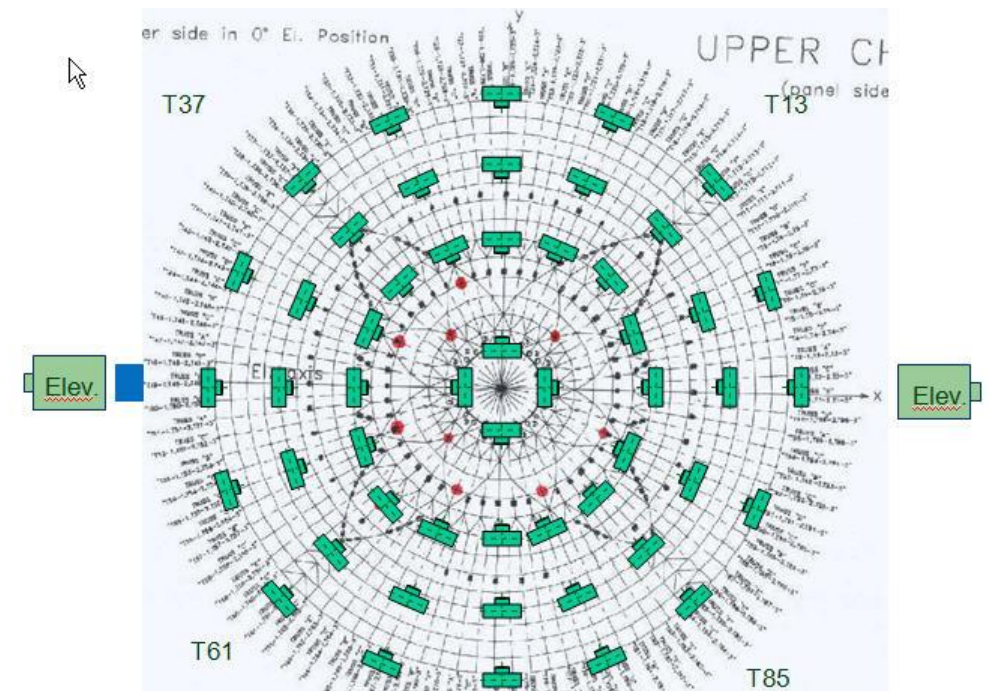
“Best” camera positions for a high measurement accuracy have been defined apriory.

Side view



50 different positions
3-4 images in different orientations

Top view



Platform options



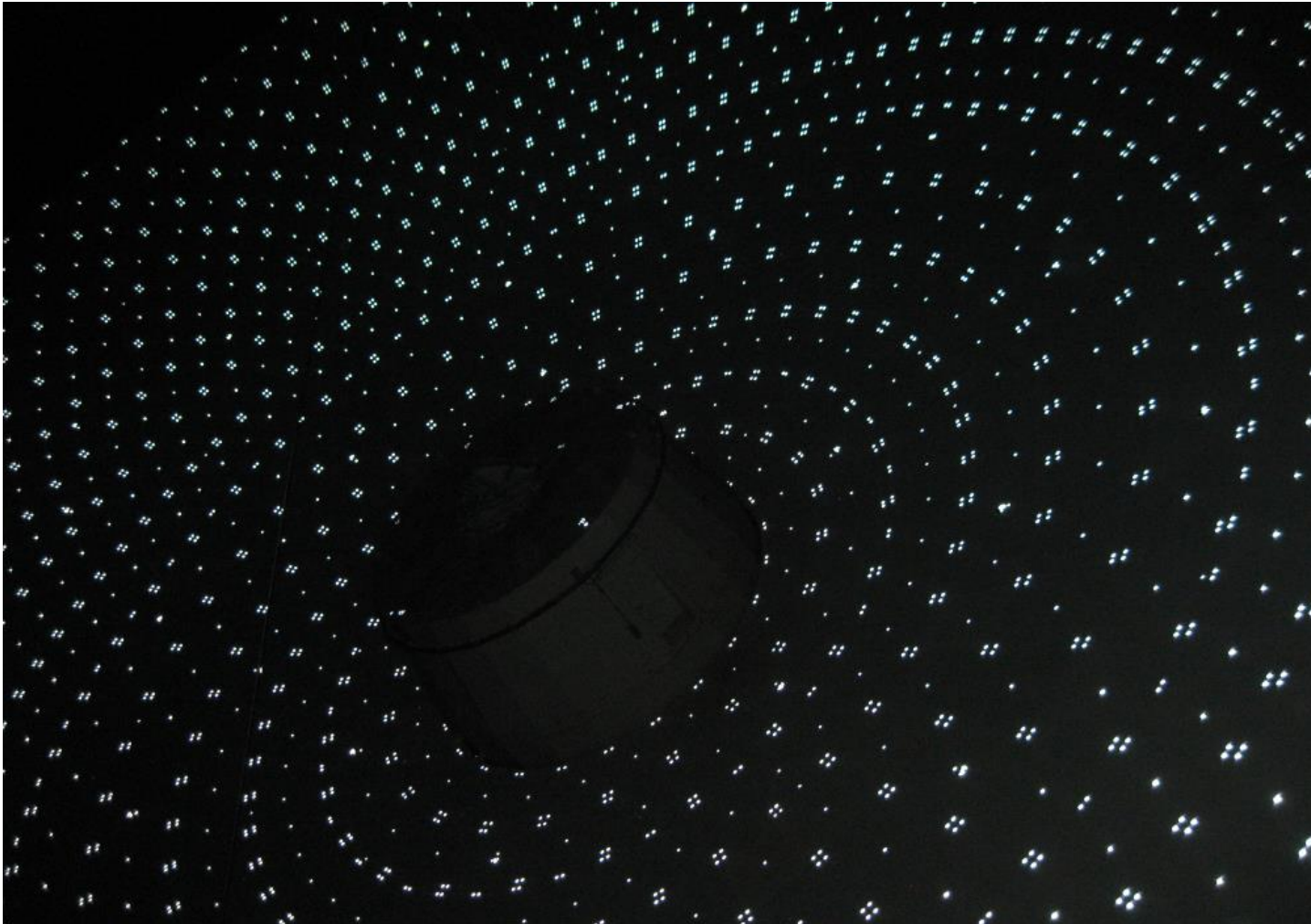
UAV
(unmanned aerial vehicle)

or

mobile crane



Measuring during night time

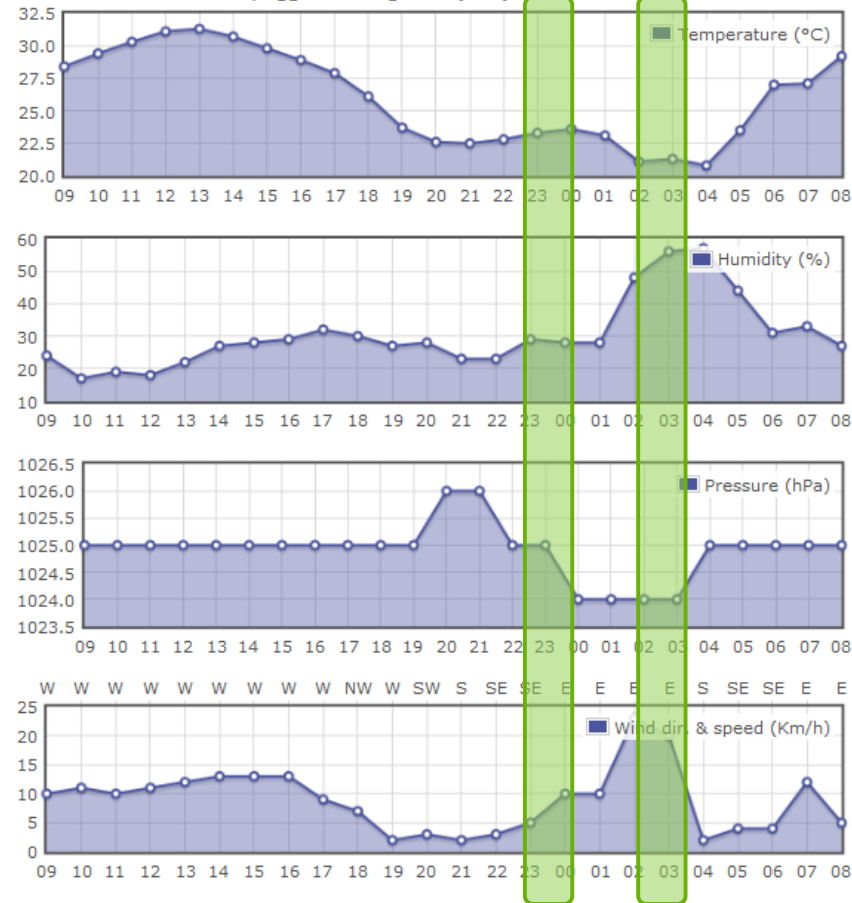


up to 300 pictures
5040 points
4x corner
1x center

Meteorological data

Dati meteo


I dati delle ultime 24 ore, aggiornate ogni ora(UTC).



Meteo-station data

1. Temperature
 2. Humidity
 3. Pressure
 4. Wind speed
- 6 hours “stable“ conditions during night-time
 - measurements over 80% humidity not necessary (no reflection from Retro-targets)
 - sometimes very high wind speed

3D coordinate calculation with Bundle-Adjustment (AICON Software)

| Statistik der Ausgleichung | | | | | | | | | | | |
|----------------------------|----------|----------|---------|---------|---------|---------|---------|-------------------------------------|-------------------------------------|-------------------------------------|---|
| Sigma 0: | | | | | | | | | | 0.00057 |  |
| Median: [mm] | | 0.03 | | | 0.03 | | | | 0.03 | | |
| RMS: [mm] | | 0.05 | | | 0.05 | | | | 0.03 | | |
| Ergebnis der Ausgleichung | | | | | | | | | | | |
| Nr. | X [mm] | Y [mm] | Z [mm] | Sx [mm] | Sy [mm] | Sz [mm] | Strahl. | Aktiv | | | |
| 1226 | 3284.02 | -3372.35 | 1339.80 | 3.99 | 9.63 | 2.34 | 3 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | |
| 1223 | 1037.56 | 1065.57 | 3780.91 | 0.59 | 0.11 | 0.07 | 4 | <input type="checkbox"/> | <input type="checkbox"/> | <input type="checkbox"/> | |
| 31 | -2409.45 | -2469.55 | 2312.29 | 0.12 | 0.08 | 0.09 | 5 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 41 | -2296.80 | 2389.89 | 2455.04 | 0.09 | 0.08 | 0.09 | 10 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 24 | 1273.49 | -1295.97 | 3519.03 | 0.08 | 0.11 | 0.06 | 7 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 40 | -2206.31 | 2127.69 | 2645.18 | 0.10 | 0.06 | 0.07 | 8 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 42 | -1442.68 | 1358.99 | 3467.31 | 0.10 | 0.05 | 0.06 | 8 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 44 | -1209.09 | 1204.82 | 3608.59 | 0.10 | 0.06 | 0.06 | 6 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1120 | 5941.15 | 2566.27 | 2404.03 | 0.10 | 0.05 | 0.05 | 23 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1213 | 6459.76 | 96.01 | 2397.05 | 0.10 | 0.03 | 0.05 | 24 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1122 | 6003.03 | 2397.56 | 2398.19 | 0.10 | 0.05 | 0.04 | 26 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1212 | 6464.67 | -84.13 | 2400.77 | 0.10 | 0.03 | 0.05 | 25 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1173 | 2388.65 | -6000.75 | 2397.65 | 0.05 | 0.10 | 0.04 | 36 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1179 | 4506.60 | -4633.90 | 2401.69 | 0.07 | 0.08 | 0.04 | 29 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1181 | 89.82 | -6467.01 | 2402.81 | 0.03 | 0.11 | 0.04 | 38 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1180 | 4635.22 | -4501.49 | 2399.46 | 0.08 | 0.08 | 0.04 | 30 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1185 | -4512.01 | 4635.39 | 2394.05 | 0.08 | 0.08 | 0.05 | 23 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1184 | -4639.77 | 4507.23 | 2393.83 | 0.08 | 0.08 | 0.05 | 23 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1172 | 2559.01 | -5939.92 | 2404.17 | 0.05 | 0.10 | 0.04 | 37 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 11 | 2153.71 | 2059.81 | 2689.59 | 0.07 | 0.07 | 0.07 | 6 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1182 | -89.48 | -6462.20 | 2399.28 | 0.03 | 0.11 | 0.04 | 39 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1157 | -4511.10 | -4634.07 | 2398.58 | 0.07 | 0.08 | 0.04 | 34 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1197 | -2390.64 | -6005.99 | 2399.15 | 0.05 | 0.10 | 0.04 | 31 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1105 | -4635.72 | -4502.58 | 2395.20 | 0.07 | 0.08 | 0.04 | 35 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |
| 1196 | -2556.29 | -5936.52 | 2398.48 | 0.05 | 0.10 | 0.04 | 30 | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | |

Determinate surface deviations with 4032 points (sigma3D Software)

Transformation Calculation

Calculate ...

| | Value | sigma | value/sigma |
|---|-----------|--------|-------------|
| <input type="checkbox"/> tra x | 0.000 | | |
| <input type="checkbox"/> tra y | 0.000 | | |
| <input checked="" type="checkbox"/> tra z | -4556.290 | 0.004 | 1032315.5 |
| <input checked="" type="checkbox"/> rot x | 75.6213 | 0.0474 | 1589.2 |
| <input type="checkbox"/> rot y | 0.0000 | | |
| <input type="checkbox"/> rot z | 0.0000 | | |
| <input type="checkbox"/> scale x | 1.000000 | | |
| <input type="checkbox"/> scale y | 1.000000 | | |
| <input type="checkbox"/> scale z | 1.000000 | | |
| <input type="checkbox"/> scale xyz | not used | | |
| <input type="checkbox"/> xy | 0.0000 | | |
| <input type="checkbox"/> Azimuth z | 0.0000 | | |
| <input type="checkbox"/> z to xy | 0.0000 | | |

R Option

R Dist. 0.000

R Data is known Load R Data

OCS = TRA + Rot_Matrix * Affine_Matrix * Scale_Matrix * MCS

Display: Deviation MCS => OCS

| Point | sigma x | sigma y | sigma z | X | Y | Z |
|----------|---------|---------|---------|---|---|---|
| T01H03P2 | 0.104 | -0.001 | -0.541 | X | X | X |
| T01H03P3 | 0.071 | 0.001 | -0.369 | X | X | X |
| T01H04P1 | 0.074 | 0.000 | -0.311 | X | X | X |
| T01H04P2 | 0.003 | 0.000 | -0.012 | X | X | X |
| T01H04P3 | 0.029 | 0.000 | -0.117 | X | X | X |
| T01H04P4 | 0.050 | 0.000 | -0.210 | X | X | X |
| T01H05P1 | -0.111 | 0.001 | 0.383 | X | X | X |
| T01H05P2 | -0.028 | 0.000 | 0.095 | X | X | X |
| T01H05P3 | -0.142 | -0.001 | 0.480 | X | X | X |
| T01H05P4 | -0.127 | -0.001 | 0.439 | X | X | X |
| T01H06P1 | 0.059 | 0.000 | -0.174 | X | X | X |
| T01H06P2 | 0.031 | 0.000 | -0.089 | X | X | X |
| T01H06P3 | -0.004 | 0.000 | 0.010 | X | X | X |
| T01H06P4 | 0.037 | 0.000 | 0.199 | X | X | X |
| T01H07P1 | -0.037 | 0.000 | 0.095 | X | X | X |
| T01H07P2 | -0.007 | 0.000 | 0.018 | X | X | X |
| T01H07P3 | 0.006 | 0.000 | -0.014 | X | X | X |
| T01H07P4 | -0.106 | 0.000 | 0.271 | X | X | X |
| T01H08P1 | -0.222 | 0.001 | 0.502 | X | X | X |
| T01H08P2 | -0.169 | 0.001 | 0.378 | X | X | X |
| T01H08P3 | -0.111 | 0.000 | 0.249 | X | X | X |
| T01H08P4 | -0.282 | -0.001 | 0.639 | X | X | X |
| T01H09P1 | 0.018 | 0.000 | -0.037 | X | X | X |
| T01H09P2 | 0.013 | 0.000 | -0.026 | X | X | X |
| T01H09P3 | 0.032 | 0.000 | -0.064 | X | X | X |
| T01H09P4 | 0.018 | 0.000 | -0.037 | X | X | X |
| T01H10P1 | -0.178 | 0.001 | 0.332 | X | X | X |

Norm (Solution) L1 L2

Standards: 6 Parameter, 7 Parameter, 9 Parameter, 12 Parameter, Hold Level

Control: Calculate, Monte Carlo, MCS <=> OCS, Use all pts, Details, STOP, Auto recalculate, Close

Statistics

| | | | | | | | |
|--|----------------|-----------|-----------------|-----------|-----------------|-----------|-----------------|
| sigma xyz | 0.485 | sigma x | 0.161 | sigma y | 0.167 | sigma z | 0.427 |
| max dev xyz | 2.251 T50H07P3 | max dev x | 0.781 T52H14P2 | max dev y | 0.888 T77H14P2 | max dev z | 1.681 T90H15P4 |
| s0 Standard Deviation of p=1 [sigma 0] | 0.280 | min dev x | -1.147 T90H15P4 | min dev y | -0.963 T22H15P1 | min dev z | -2.094 T50H07P3 |
| | | max-min x | 1.928 | max-min y | 1.851 | max-min z | 3.775 |

Iteration 2 calculating corrections... Convergence Ratio: 6568773.456 on VarNumber: 1 delta x(i): 2.5194791030665E-14 ...L2 ...L2

Best-Fit Parameter

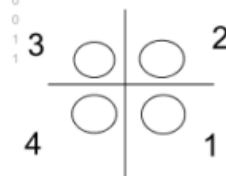
Abweichungen in X, Y und Z

RMS Wert der Kontur

6 Alignment Teams

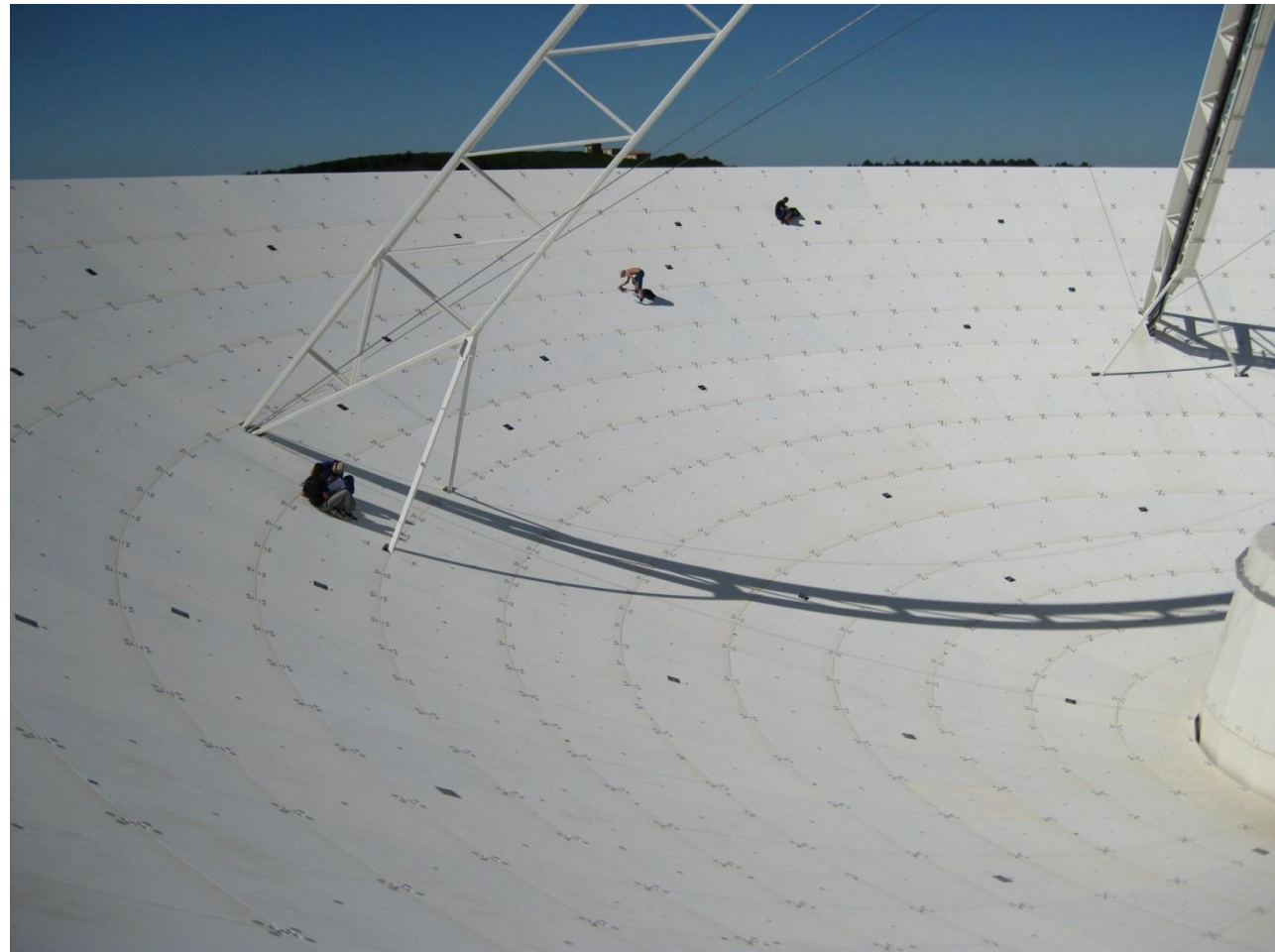


| ID | Abweichung [mm] | NOK | ID | Abweichung [mm] | NOK | ID | Abweichung [mm] | NOK |
|----------|-----------------|-----|----------|-----------------|-----|----------|-----------------|-----|
| T13H03P2 | 0.00 | 0 | T14H07P2 | 0.00 | 0 | T15H01P2 | -1.16 | 1 |
| T13H03P3 | 0.00 | 0 | T14H07P3 | 0.00 | 0 | T15H01P3 | -1.53 | 1 |
| T13H04P1 | 0.13 | 1 | T14H08P1 | -0.19 | 1 | T15H02P1 | -1.24 | 1 |
| T13H04P2 | -0.12 | 1 | T14H08P2 | 0.21 | 1 | T15H02P2 | -1.63 | 1 |
| T13H04P3 | 0.00 | 0 | T14H08P3 | 0.27 | 1 | T15H02P3 | -1.38 | 1 |
| T13H04P4 | 0.41 | 1 | T14H08P4 | 0.54 | 1 | T15H02P4 | -0.90 | 1 |
| T13H05P1 | 0.44 | 1 | T14H09P1 | 0.00 | 0 | T15H03P1 | 0.00 | 0 |
| T13H05P2 | 0.45 | 1 | T14H09P2 | 0.00 | 0 | T15H03P2 | 0.13 | 1 |
| T13H05P3 | 0.25 | 1 | T14H09P3 | 0.00 | 0 | T15H03P3 | 0.23 | 1 |
| T13H05P4 | 0.25 | 1 | T14H09P4 | 0.00 | 0 | T15H03P4 | 0.30 | 1 |
| T13H06P1 | 0.00 | 0 | T14H10P1 | 0.37 | 1 | T15H04P1 | 0.00 | 0 |
| T13H06P2 | 0.00 | 0 | T14H10P2 | 0.24 | 1 | T15H04P2 | 0.19 | 1 |
| T13H06P3 | 0.00 | 0 | T14H10P3 | 0.00 | 0 | T15H04P3 | 0.00 | 0 |
| T13H06P4 | 0.00 | 0 | T14H10P4 | 0.39 | 1 | T15H04P4 | 0.00 | 0 |
| T13H07P1 | 0.16 | 1 | T14H11P1 | 0.27 | 1 | T15H05P1 | 0.17 | 1 |
| T13H07P2 | 0.12 | 1 | T14H11P2 | 0.00 | 0 | T15H05P2 | 0.18 | 1 |
| T13H07P3 | 0.00 | 0 | T14H11P3 | 0.29 | 1 | T15H05P3 | 0.00 | 0 |
| T13H07P4 | 0.38 | 1 | T14H11P4 | 0.39 | 1 | T15H05P4 | 0.17 | 1 |
| T13H08P1 | 0.28 | 1 | T14H12P1 | 0.35 | 1 | T15H06P1 | -0.28 | 1 |
| T13H08P2 | 0.00 | 0 | T14H12P2 | 0.12 | 1 | T15H06P2 | 0.00 | 0 |
| T13H08P3 | 0.25 | 1 | T14H12P3 | 0.40 | 1 | T15H06P3 | -0.32 | 1 |
| T13H08P4 | -0.14 | 1 | T14H12P4 | 0.00 | 0 | T15H06P4 | -0.44 | 1 |
| T13H09P1 | 0.00 | 0 | T14H13P1 | -0.16 | 1 | T15H07P1 | 0.00 | 0 |
| T13H09P2 | 0.00 | 0 | T14H13P2 | 0.18 | 1 | T15H07P2 | 0.00 | 0 |
| T13H09P3 | 0.00 | 0 | T14H13P3 | 0.20 | 1 | T15H07P3 | 0.00 | 0 |
| T13H09P4 | 0.00 | 0 | T14H13P4 | 0.00 | 0 | T15H07P4 | 0.00 | 0 |
| T13H10P1 | 0.16 | 1 | T14H14P1 | 0.00 | 0 | T15H08P1 | 0.00 | 0 |
| T13H10P2 | 0.36 | 1 | T14H14P2 | 0.00 | 0 | T15H08P2 | 0.00 | 0 |
| T13H10P3 | 0.30 | 1 | T14H14P3 | 0.00 | 0 | T15H08P3 | 0.00 | 0 |
| T13H10P4 | 0.29 | 1 | T14H14P4 | 0.00 | 0 | T15H08P4 | 0.00 | 0 |
| T13H11P1 | 0.29 | 1 | T14H15P1 | 0.00 | 0 | T15H09P1 | 0.00 | 0 |
| T13H11P2 | 0.00 | 0 | T14H15P4 | 0.00 | 0 | T15H09P2 | 0.00 | 0 |
| T13H11P3 | 0.14 | 1 | | | | T15H09P3 | 0.00 | 0 |
| T13H11P4 | 0.00 | 0 | | | | T15H09P4 | 0.00 | 0 |
| T13H12P1 | 0.17 | 1 | | | | T15H10P1 | 0.21 | 1 |
| T13H12P2 | 0.00 | 0 | | | | T15H10P2 | 0.00 | 0 |
| T13H12P3 | -0.15 | 1 | | | | T15H10P3 | 0.15 | 1 |
| T13H12P4 | 0.16 | 1 | | | | T15H10P4 | 0.17 | 1 |
| T13H13P1 | 0.34 | 1 | | | | T15H11P1 | 0.00 | 0 |
| T13H13P2 | 0.00 | 0 | | | | T15H11P2 | 0.00 | 0 |
| T13H13P3 | 0.00 | 0 | | | | T15H11P3 | 0.00 | 0 |
| T13H13P4 | 0.19 | 1 | | | | T15H11P4 | 0.00 | 0 |
| T13H14P1 | 0.00 | 0 | | | | T15H12P1 | 0.25 | 1 |
| T13H14P2 | 0.14 | 1 | | | | T15H12P2 | 0.35 | 1 |
| T13H14P3 | 0.00 | 0 | | | | T15H12P3 | 0.33 | 1 |
| T13H14P4 | 0.00 | 0 | | | | T15H12P4 | 0.00 | 0 |
| T13H15P1 | -1.08 | 1 | | | | T15H13P1 | 0.22 | 1 |
| T13H15P4 | -1.01 | 1 | | | | T15H13P2 | -0.16 | 1 |
| | | | | | | T15H13P3 | 0.00 | 0 |
| | | | | | | T15H13P4 | 0.00 | 0 |
| | | | | | | T15H14P1 | 0.00 | 0 |
| | | | | | | T15H14P2 | 0.00 | 0 |
| | | | | | | T15H14P3 | 0.00 | 0 |
| | | | | | | T15H14P4 | 0.00 | 0 |
| | | | | | | T15H15P1 | -0.20 | 1 |
| | | | | | | T15H15P4 | 0.29 | 1 |

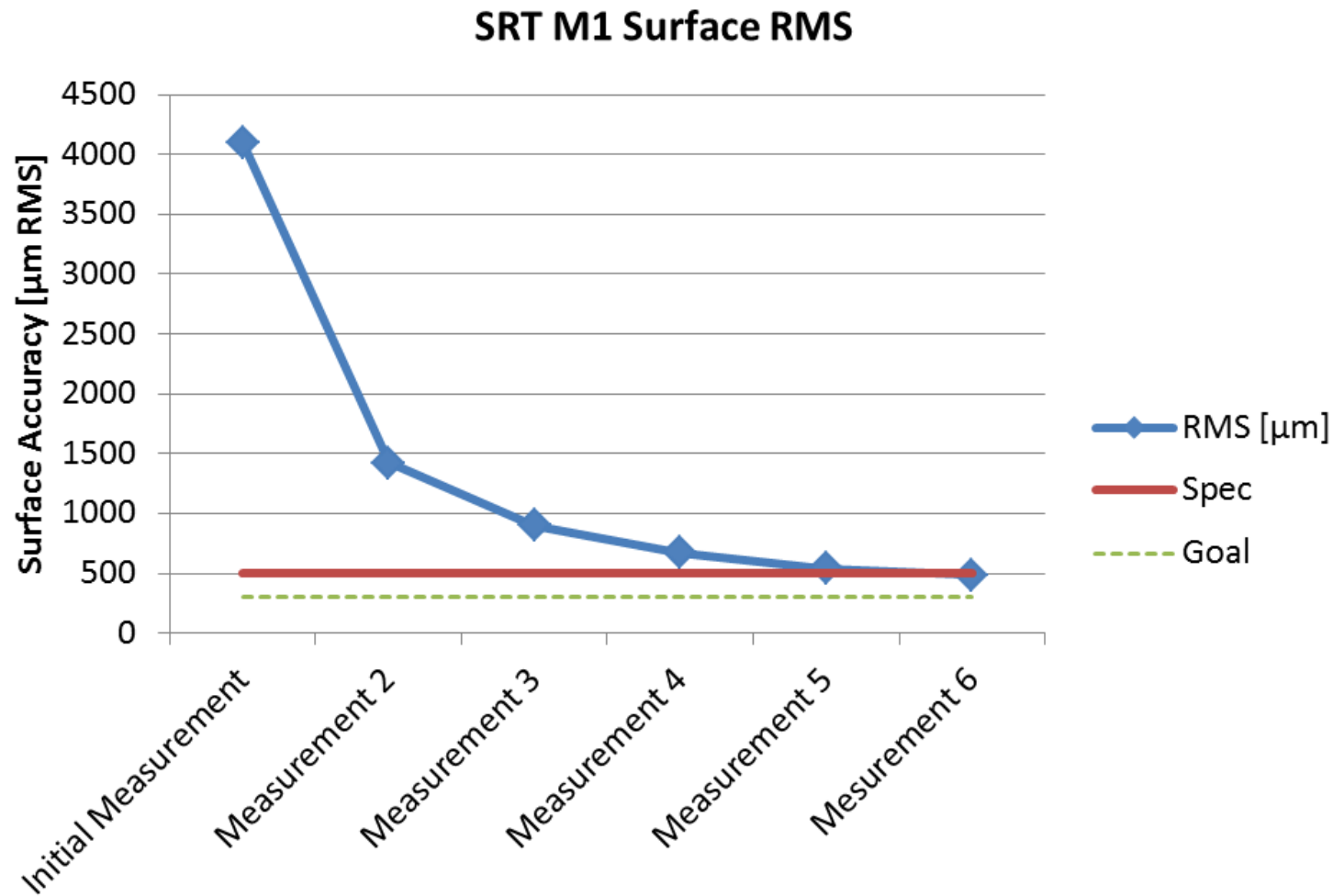


Finish Alignment within 5 days

| | |
|--------------------------|-------------|
| Alignment teams | 6 |
| Number Targets (used) | 4032 |
| Number Pictures | 250-300 |
| Meas. Accuracy | 130 μ m |
| RMS Surface | 485 μ m |



Alignment Iterations



Surface deviation in different elevation angles (90/75/60/45/30/15)



Main Reflector in various elevation (90°/75°/60°/45°/30°/15°)

All measurements in one night

Number elevation positions 6

Mobile crane 110m (1 Pos.)

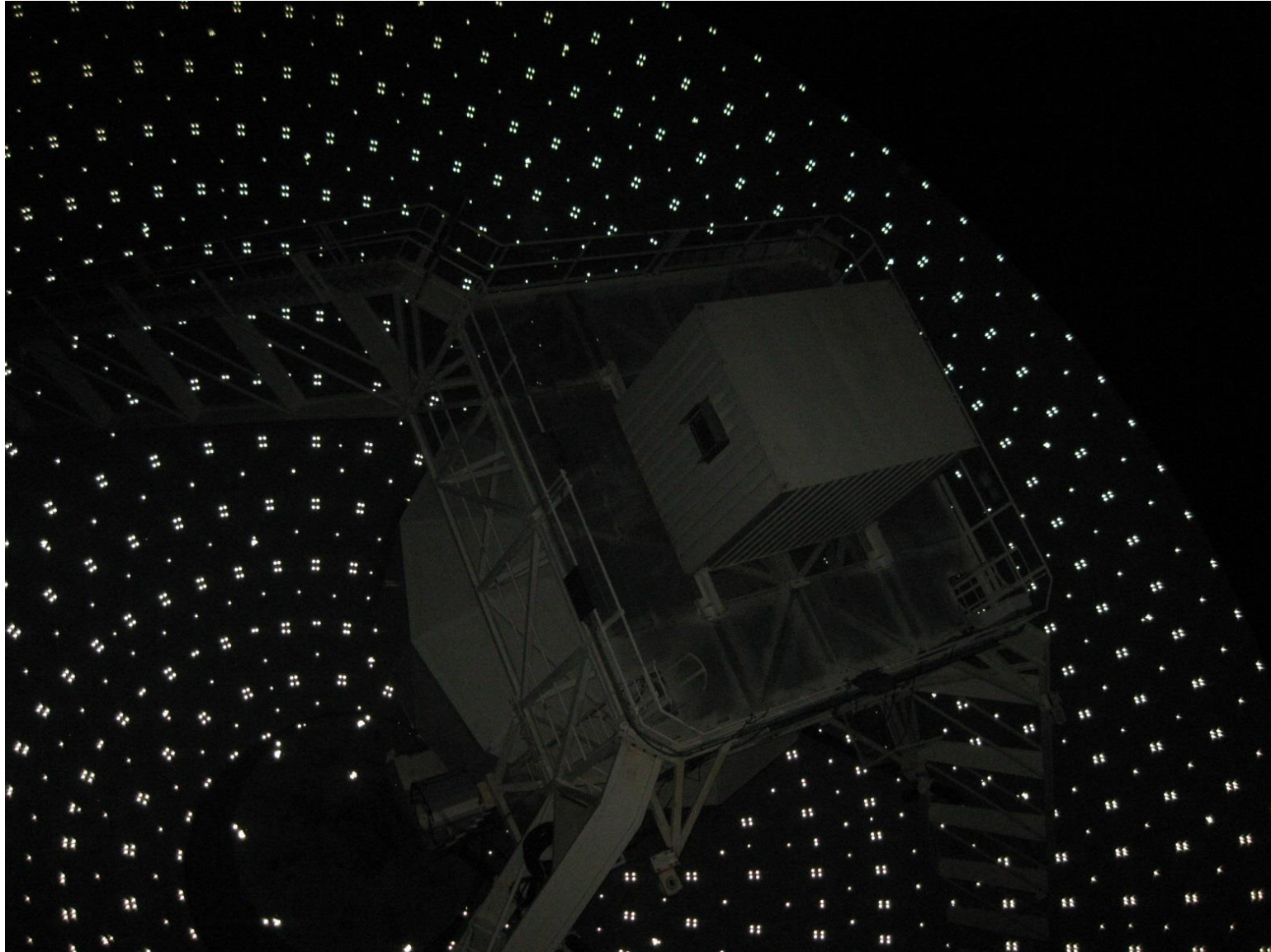
Number targets 4032 / 5040

Number pictures 200

Meas. Uncertainty 160 μm (1σ)

**Turning Antenna in 75° und 90°
azimuthal!**

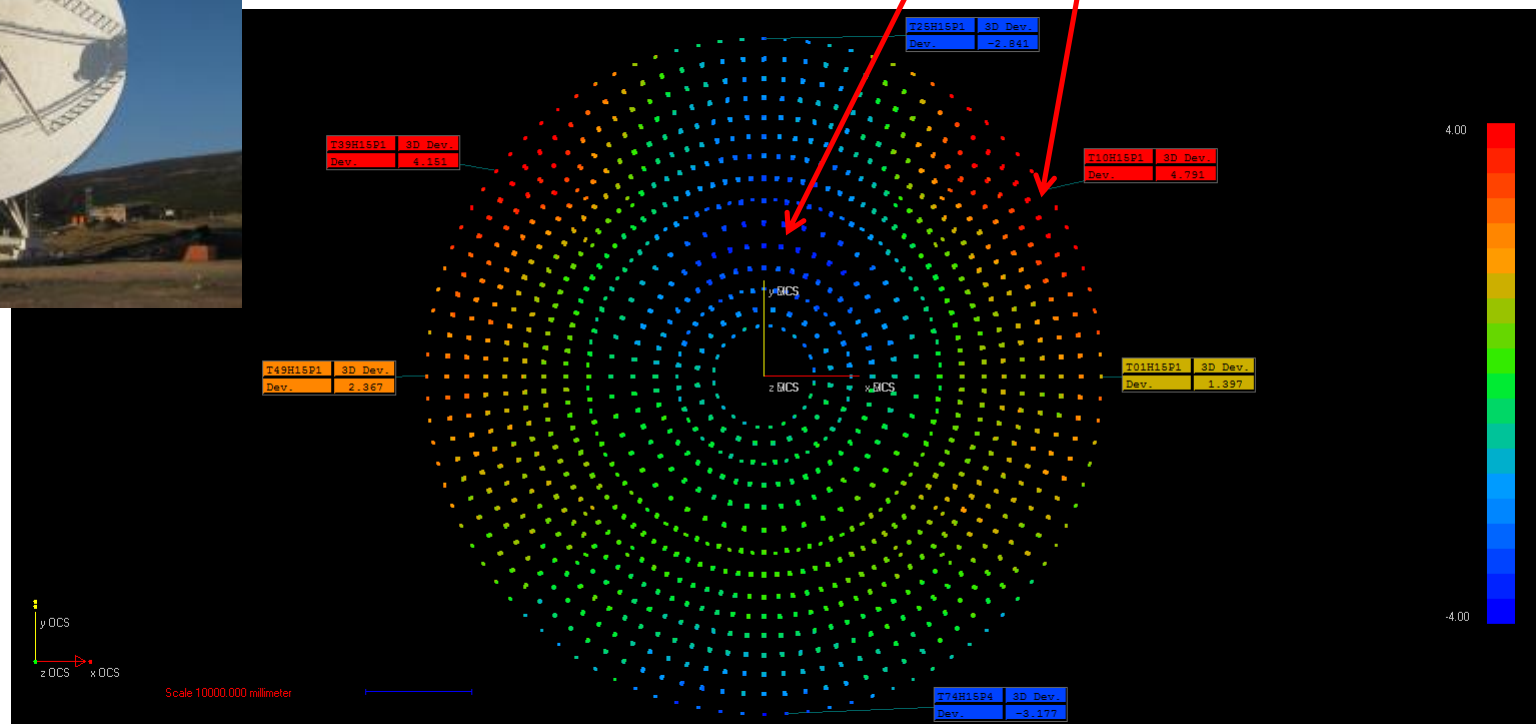




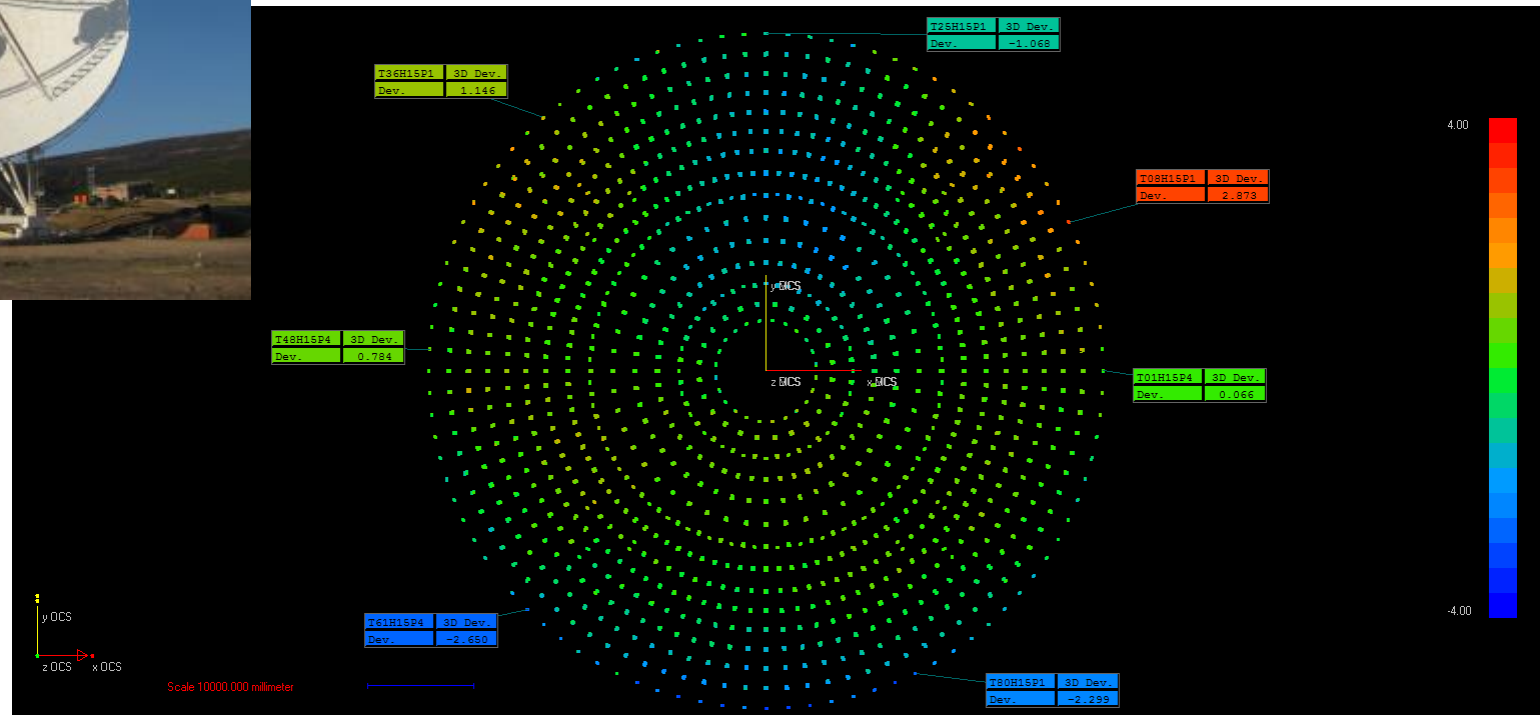
Main-Reflector in 15° elevation



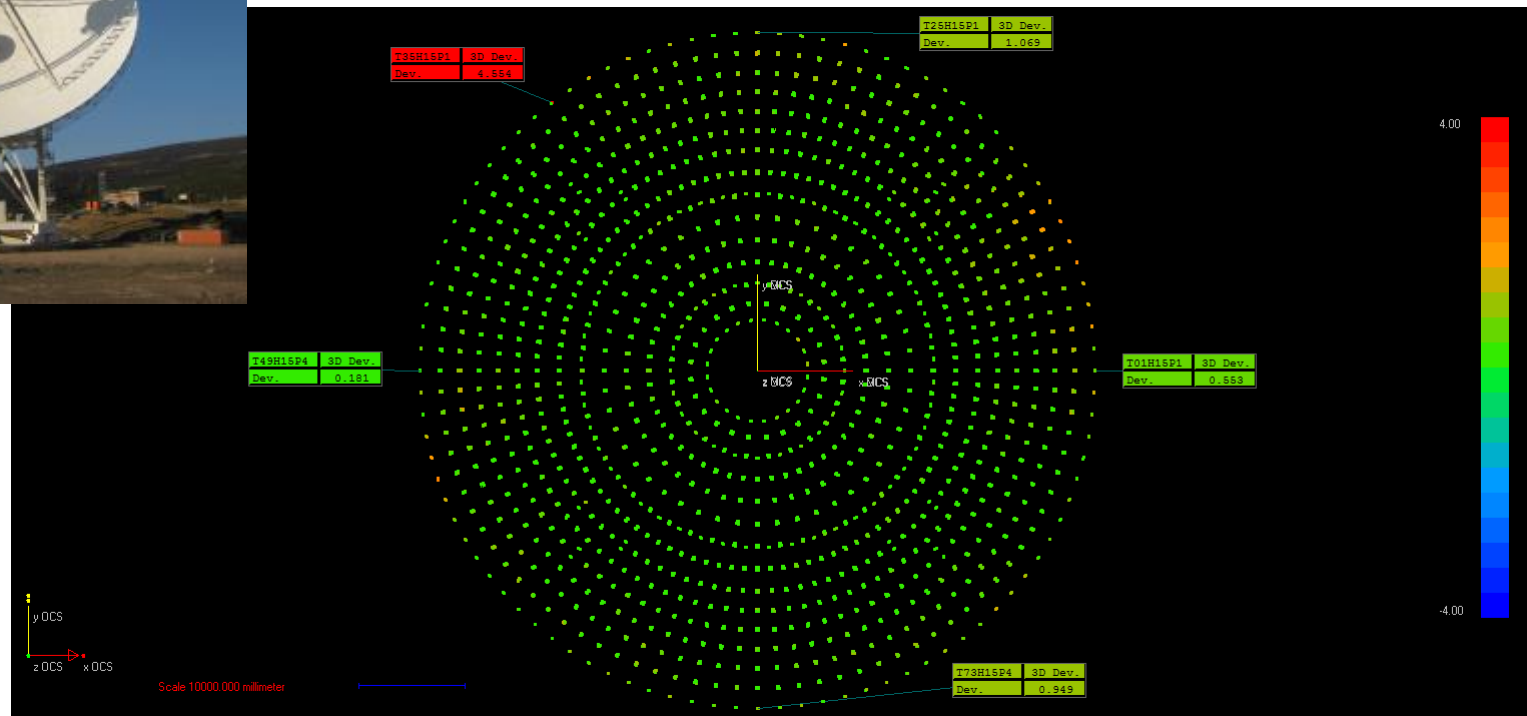
Surface deviation: -4mm to 5mm



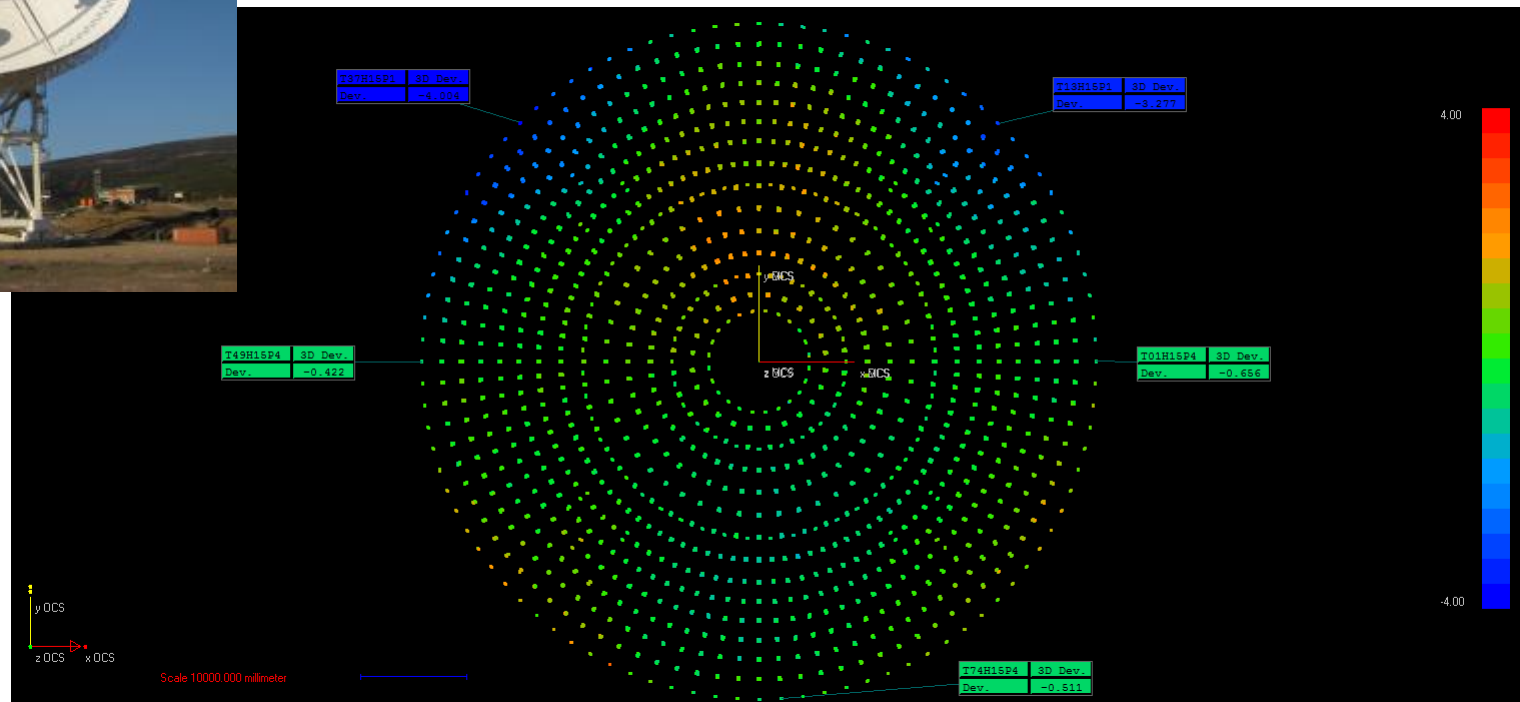
Main-Reflector in 30° elevation



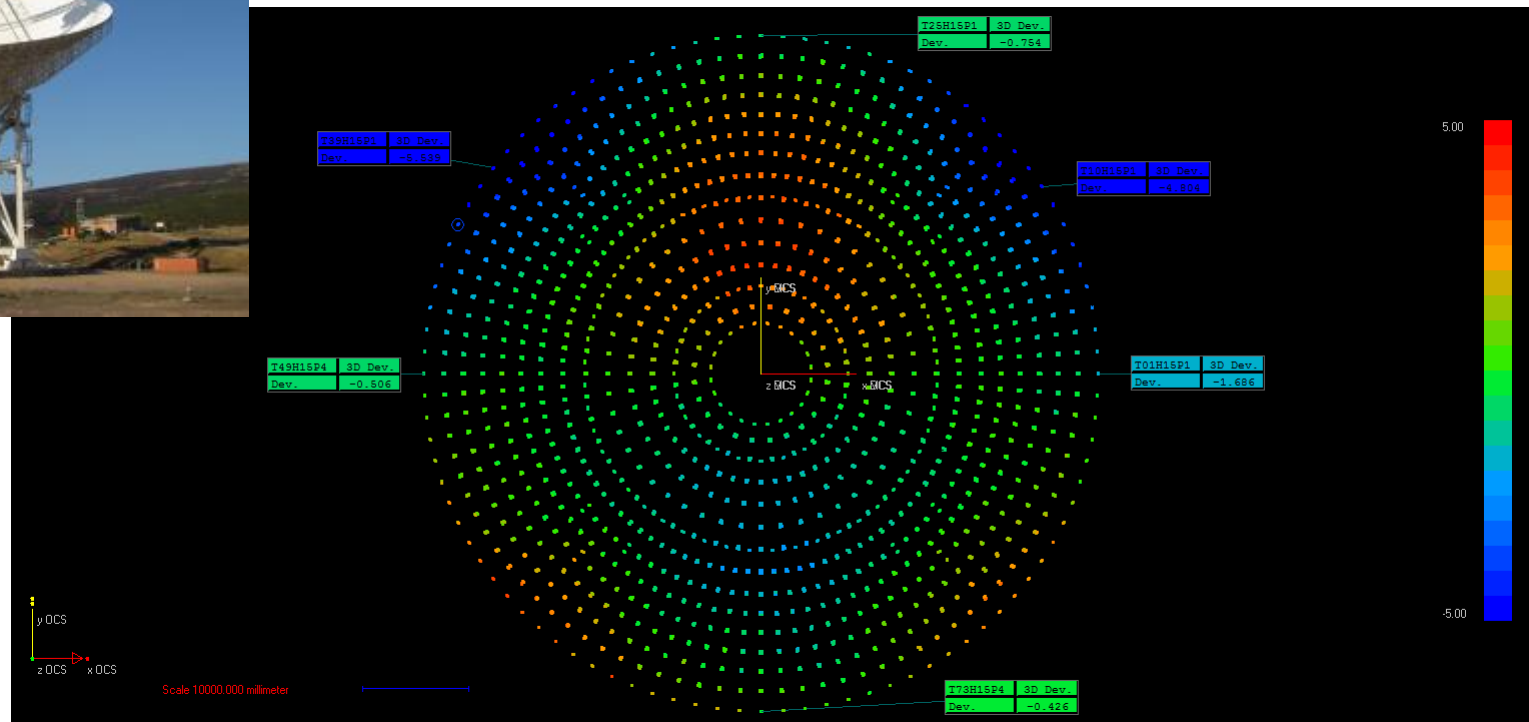
Main-Reflector in 45° elevation



Main-Reflector in 60° elevation



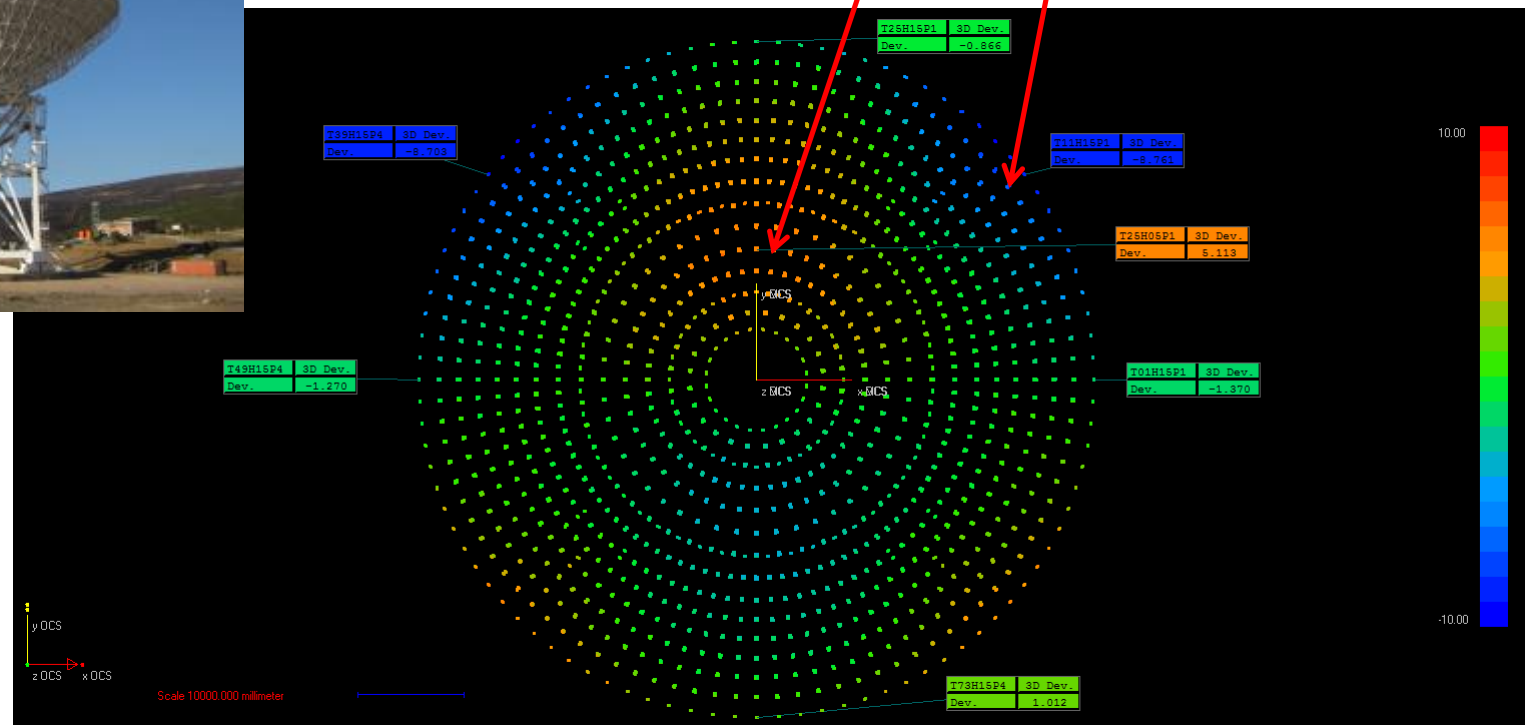
Main-Reflector in 75° elevation



Main-Reflector in 90° elevation



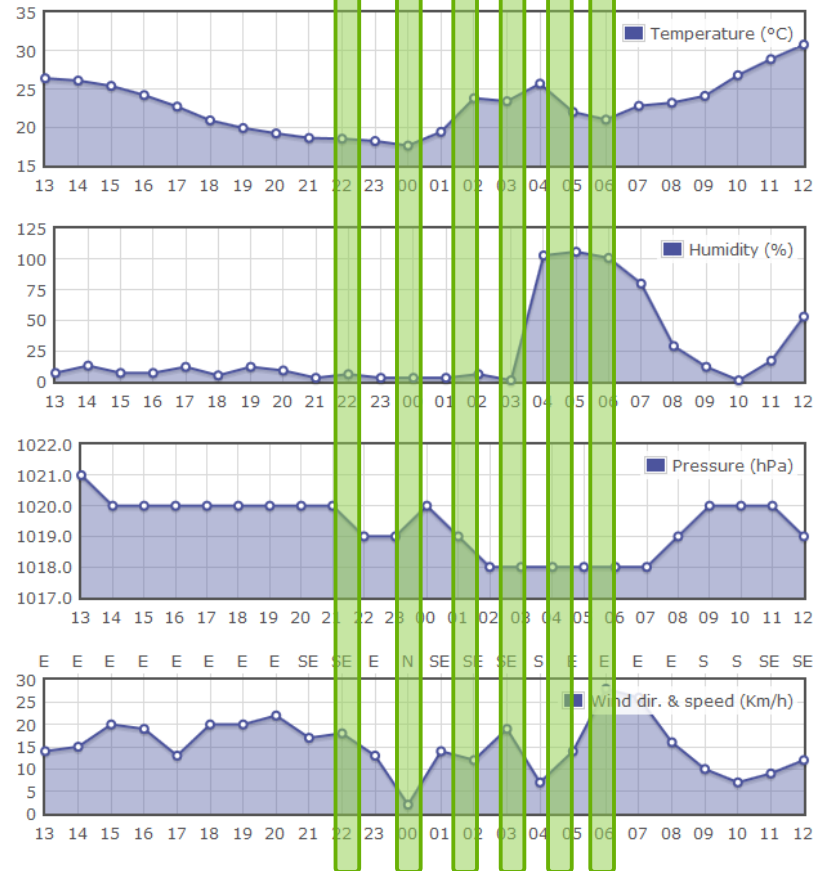
Surface deviation: 5mm to -9mm



Meteorological data

Dati meteo

I dati delle ultime 24 ore, aggiornate ogni ora (UTC)



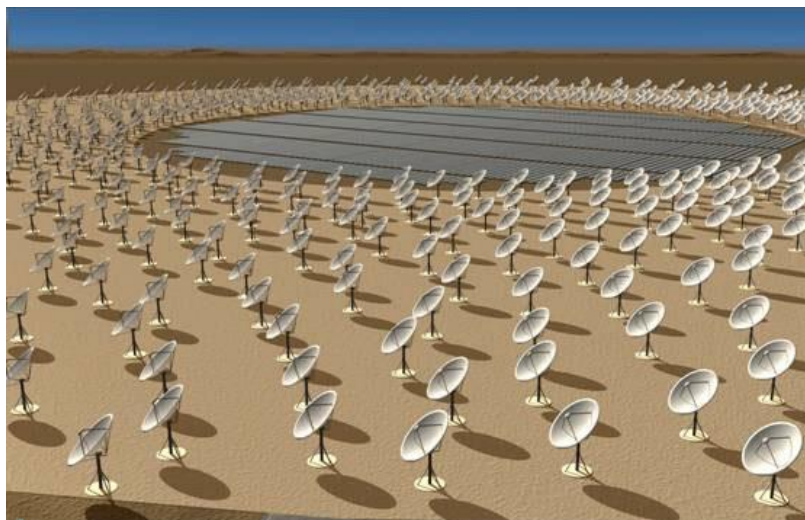
Main Reflector in various elevation - Results

| Elevation-Position | 15° | 30° | 45° Panel Corner | 45° | 60° | 75° | 90° |
|--------------------|---------------|---------------|------------------|---------------|---------------|---------------|---------------|
| Origin task | Various Elev. | Various Elev. | Global | Various Elev. | Various Elev. | Various Elev. | Various Elev. |
| ID | 3D Dev. [mm] | 3D Dev. [mm] | 3D Dev. [mm] | 3D Dev. [mm] | 3D Dev. [mm] | 3D Dev. [mm] | 3D Dev. [mm] |
| R01_01_P5 | -2.26 | -0.74 | | -0.35 | 0.10 | 0.35 | 0.44 |
| R01_02_P5 | -2.27 | -0.54 | | -0.41 | 0.37 | 0.85 | 1.26 |
| R01_03_P5 | -2.36 | -0.45 | | -0.51 | 0.41 | 1.22 | 1.95 |
| R01_04_P5 | -2.24 | -0.42 | | -0.02 | 0.86 | 1.92 | 2.47 |
| R01_05_P5 | -2.19 | -0.22 | | 0.07 | 1.04 | 2.53 | 3.16 |
| R01_06_P5 | -1.97 | -0.25 | | 0.17 | 1.19 | 2.64 | 3.45 |
| R01_07_P5 | -1.82 | -0.54 | | 0.07 | 1.26 | 2.68 | 3.69 |
| R01_08_P5 | -1.82 | -0.48 | | 0.24 | 1.66 | 2.75 | 3.63 |
| R01_09_P5 | -1.77 | -0.34 | | 0.02 | 1.43 | 2.25 | 3.33 |
| R01_10_P5 | -1.55 | -0.11 | | 0.02 | 1.36 | 1.78 | 2.88 |
| R01_11_P5 | -1.37 | -0.33 | | 0.12 | 0.99 | 1.30 | 2.36 |
| R01_12_P5 | -1.34 | -0.29 | | 0.16 | 0.68 | 1.13 | 1.71 |
| R01_13_P5 | -1.22 | -0.08 | | 0.06 | 0.40 | 0.61 | 0.99 |
| R01_14_P5 | -0.89 | -0.06 | | 0.10 | 0.30 | 0.14 | 0.21 |
| R01_15_P5 | -1.02 | 0.23 | | -0.16 | 0.13 | -0.39 | -0.51 |
| R01_16_P5 | -0.92 | 0.41 | | 0.03 | -0.03 | -0.90 | -1.06 |
| R01_17_P5 | -0.85 | 0.51 | | 0.08 | 0.00 | -1.04 | -1.37 |
| R01_18_P5 | -0.77 | 0.62 | | 0.08 | -0.12 | -0.72 | -1.82 |
| R01_19_P5 | -0.52 | 1.10 | | 0.29 | 0.07 | -0.54 | -1.73 |
| R01_20_P5 | -0.90 | 0.85 | | -0.26 | -0.17 | -0.64 | -1.87 |
| R01_21_P5 | -0.89 | 0.59 | | -0.75 | -0.39 | -0.86 | -2.30 |
| R01_22_P5 | -0.50 | 0.69 | | -0.10 | -0.19 | -0.33 | -1.05 |
| R01_23_P5 | -0.77 | 0.61 | | 0.18 | -0.32 | -0.37 | -0.56 |
| R01_24_P5 | -0.77 | 0.36 | | 0.35 | 0.28 | 0.22 | 0.20 |

Summary: Alignment with Photogrammetry

- ✓ Quick, reliable and scalable measurement technology for surface and deformation measurements
- ✓ User-Experience is much more important as in other 3D measurement technologies
- ✓ Need targets (retro or paper) for high accuracy
- ✓ Good weather conditions necessary

Thank you for your attention!



New Challenge for the future:

Square Kilometre Array (SKA)
in South Africa

Next generation Radio Telescope